

# M. TECH. DEFENCE TECHNOLOGY

(Duration: 2 Years)

**CURRICULUM and SYLLABUS** 

(Applicable for Students admitted from Academic Year 2021-22)

DEPARTMENT OF AERONAUTICAL ENGINEERING
HINDUSTAN INSTITUTE OF TECHNOLOGY AND SCIENCE

# HINDUSTAN INSTITUTE OF TECHNOLOGY AND SCIENCE

## Motto:

To Make Every Man a Success and No Man a Failure

#### Vision:

To be an International Institute of Excellence, providing a conducive environment for education with a strong emphasis on innovation, quality, research and strategic partnership blended with values and commitment to society.

### Mission:

- To create an ecosystem that promotes learning and world class research.
- To nurture creativity and innovation.
- To instill highest ethical standards and values.
- To pursue activities for the development of the Society.
- To develop national and international collaborations with institutes and industries of eminence.
- To enable graduates to become future leaders and innovators.

### Value Statement:

Integrity, Innovation, Internationalization.

# M.Tech Defence Technology

#### **ABOUT THE COURSE:**

The M.Tech. in defence technology courses has been designed to produce Post Graduates who will have the necessary theoretical & experimental knowledge, skill and aptitude in various defence technologies areas and pursue them to carry out R&D in defence.

The students will be provided valuable exposure & knowledge for various state of the art defence systems and contemporary technologies through class lectures & main thesis work with the collaboration of DRDO. During the program, the students would be given opportunities in carrying out their main thesis work in DRDO labs, Defence PSUs & Private Defence Industries. This collaborative effort of DRDO, AICTE and Industries will provide required knowledge to the students and create job opportunities for them.

#### **PROGRAM OBJECTIVE:**

- To develop Post Graduates who have the necessary theoretical & experimental knowledge, skill and aptitude in defence technologies and systems and can get recruited in the various defence laboratories, defence public sector & private industries, ordnance factories and other similar sectors of the economy at national and international level.
- To contrive skilled manpower in the field of defence technologies.
- To enhance students" interaction with the senior, experienced manpower engaged in defence labs and defence industries and have real time knowledge / experience in the technology development, technology deployment and defence systems.
- To acquaint students for the needs of technologies related to defence & security of nation and to create zeal among students to pursue research and development for defence technologies.

PO1	Acquire technical competence, comprehensive knowledge and understanding the methodologies and technologies associated with land, air & naval defence systems. Apply knowledge to identify, formulate and analyse complex engineering problems.	Scholarship of Knowledge
PO2	Having an ability to apply knowledge of science, mathematics, engineering & technology for development of defence technologies.	Critical Thinking
PO3	Having an ability to design a component, subsystem or a system applying all the relevant standards and with realistic constraints, including operational and environmental.	Research Skill
PO4	Acquire the skills for uses of contemporary techniques, resources and modern engineering and IT tools	Usages of Modern Techniques
PO5	An ability to identify, investigate, understand and analyse complex problems, apply creativity, carry out research /investigation and development work to solve practical problems related to defence technological issues.	Design, Development & Solutions
PO6	Ability to communicate effectively in both oral and written contexts in the form of technical papers, project reports, design documents and seminar presentations.	Communication
P07	Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.	Individual &Team Work

## **PROGRAM OUTCOME:**

#### **PROGRAM STRUCTURE:**

It is a 4-semester program with total 80 credits. It is having 4 specializations, as regard to the specializations, semester -1 will have common curriculum and semester 2 curriculum will be varied as per the specialization. Semester 3 & 4 includes dissertation and industrial training. The M.Tech. in Defence Technology will be having following specializations:

- 1. Combat Vehicle Engineering
- 2. Aerospace Technology
- 3. Communication Systems & Sensors
- 4. High Energy Materials Technology

Semester - 1:Courses will be same for all specializations.

Semester -2:Courses will be as per the selected specialization.

Semester - 3 &4:Projects and Industrial Training.

### **ELIGIBILITY CRITERIA:**

Those who have pursued under graduation in following disciplines are eligible for taking up the M.Tech. Defence Technology courses:

1) Aerospace Engineering	26) Electronics and Computer Engineering
2) Aeronautical engineering	27) Electronics and Communication
	Engineering
3) Applied Electronics and	28) Electronics and Computer Science
Communication Engineering	
4) Applied Electronics and	29) Electronics and Control Systems
Instrumentation Engineering	
5) Chemical Technology	30) Electronics and Power Engineering
6) Chemical engineering	31) Electronics and Telecommunication
7) Computer Science & Engineering	32) Electronics, Instruments and Control
	Engineering
8) Computer and Communication	33) Electronics System Engineering
Engineering	
9) Computer Engineering	34) Instrumentation and Electronics
10) Computer Engineering and	35) Instrumentation Engineering
Applications	
11) Computer Networking	36) Marine Engineering
12) Computer Science and Information	37) Marine Technology
Technology	
13) Computer Science and Technology	38) Mechanical and Automation Engineering
14) Computer Technology	39) Mechatronics Engineering
15) Electrical and Computer Engineering	40) Mechanical engineering
16) Electrical and Electronics Engineering	41) Metallurgical and Materials Engineering

17) Electrical and Instrumentation Engineering	42) Military engineering
18) Electrical and Power Engineering	43) Optics and Opto-electronics
19) Electrical Engineering	44) Power Electronics Engineering
20) Electronics engineering	45) Radio, Physics and Electronics
21) Electrical, Electronics and Power	46) Software Engineering
Engineering	
22) Electronics and Communication	47) Structural Engineering
engineering	
23) Instrumentation engineering	48) Telecommunication Engineering
24) Electronics, Instrumentation and	
Control Engineering	
25) Electronics, Science and Engineering	

# M.Tech - Defence Technology

			SEMESTER- I								
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	Р	С	S	тсн		
1	BS	MAA0704	Advanced Engineering Mathematics	4	0	0	4	1	4		
2	PC	DTB0701	Warfare Simulations & Strategies	4	0	0	4	1	4		
3	PC	DTB0702	Systems and warfare Platforms	4	0	0	4	1	4		
4	DE-I	DTB0751	Rockets and Missiles Fundamentals	3	0	0	3	1	3		
5	DE-I	DTB0753	Communication Technology	3	0	0	3	1	3		
6	DE-II	DTB0752	Autonomy and Navigation Technology	3	0	0	3	1	3		
			PRACTICAL								
7	PC	DTB0731	Warfare Simulations & Strategies Lab	0	0	2	2	0	2		
8	PC	DTB0732	Systems and Warfare Platforms Lab	0	0	2	2	0	2		
9	BS	DTA0701	Seminar	0	0	1	1	0	1		
			Total				23		23		
L	L – Lecture; T – Tutorial; P – Practical; C – Credit; S- Self Study; TCH- Total Contact Hours										

		SEN	MESTER- II ( AEROSPACE TECHNOLOG	iY)					
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	P	C	S	тсн
1	BS	DTB0716	Aerospace System Configuration, Design & Simulation	4	0	0	4	1	4
2	PC	DTB0717	Guidance & control	4	0	0	4	1	4
3	PC	DTB0718	Aerospace Propulsion	4	0	0	4	1	4
4	DE	DTB0754	Structural Dynamics and Aero- Elasticity	3	0	0	3	1	3
6	DE	DTB0755	Elective 4	3	0	0	3	1	3
			PRACTICAL						
7	PC	DTB0741	Aerospace System Configuration, Design & Simulation Lab	0	0	2	2	0	2
8	PC	DTB0742	Guidance & control Lab	0	0	2	2	0	2

9	BS	DTA0701	Seminar	0	0	1	1	0	1
			Total				23		23
ı	L – Lecture ; T	– Tutorial ; P	- Practical; C - Credit; S- Self Study	; TCF	l- To	tal C	ontact	Hou	rs

		SEMESTER	- II ( COMMUNICATION SYSTEMS & S	SENS	ORS	)					
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	Р	С	s	тсн		
1	BS	DTD3703	Radar Technologies	4	0	0	4	1	4		
2	PC	DTD3704	Digital & satellite Communication and Navigation from Space	4	0	0	4	1	4		
3	PC	DTD3705	Tactical battlefield Communication & Electronic Warfare	4	0	0	4	1	4		
4	DE	DE	Elective 3	3	0	0	3	1	3		
6	DE	DE	Elective 4	3	0	0	3	1	3		
			PRACTICAL								
7	PC	DTD3791	Radar Technologies Lab	0	0	2	2	0	2		
8	PC	DTD3792	Digital & Satellite Communication and Navigation from Space Lab	0	0	2	2	0	2		
9	BS	DTD3796	Seminar	0	0	1	1	0	1		
			Total				23		23		
L	L – Lecture ; T – Tutorial ; P – Practical ; C – Credit; S- Self Study; TCH- Total Contact Hours										

	SEMESTER- III ( COMMON FOR ALL SPECIALISATION )											
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	Р	С	S	тсн			
7	PC	DTA3797	Project - Phase 1	0	0	24	10	0	24			
8	PC	DTA3798	Internship	0	0	8	4	0	8			
Total 14												
L – Lecture ; T – Tutorial ; P – Practical ; C – Credit; S- Self Study; TCH- Total Contact Hours												

	SEMESTER- IV ( COMMON FOR ALL SPECIALISATION )									
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	Р	С	S	тсн	

1	PC	DTA3799	Project - Phase 2	0	0	40	20	0	40
			Total				20		0
L	– Lecture : T	– Tutorial : P	- Practical ; C - Credit; S- Self Study	: TCF	l- To	tal C	ontact	Hou	rs

# LIST OF DEPARTMENTAL ELECTIVES WITH GROUPING – SEMESTER WISE

SEM	COURSE CATEGORY	COURSE	NAME OF THE COURSE	L	Т	Р	С	S	тсн		
	ELECTIVE -1										
1	DE	DTB0751	Rockets & Missiles Fundamentals	3	0	0	3	1	3		
1	DE		Advanced Thermal Engineering	3	0	0	3	1	3		
1	DE		Numerical Methods for Science and Engineering	3	0	0	3	1	3		
1	DE	DTB0753	Communication Technology	3	0	0	3	1	3		
1	DE		Advanced Mechanical Engineering	3	0	0	3	1	3		
			ELECTIVE - 2	•							
1	DE	DTB0752	Autonomy and Navigation Technology	3	0	0	3	1	3		
1	DE		Optimization Theory & Applications	3	0	0	3	1	3		
1	DE		Military Electronics System Engineering	3	0	0	3	1	3		
1	DE		System Engineering and Analysis	3	0	0	3	1	3		
	ELECTIVE - 3										
2	DE	DTA-3730	Robotics (MSS, MCC)	3	0	0	3	1	3		
2	DE	DTA-3731	EMI/EMCIn Military Systems	3	0	0	3	1	3		

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2	DE	DTA-3732	Defence Electro-Optics and Imaging Systems	3	0	0	3	1	3
2	DE	DTA-3733	Structural Dynamics and Aero- Elasticity	3	0	0	3	1	3
2	DE	DTA-3734	Safety, Health & Hazard Management	3	0	0	3	1	3
2	DE	DTA-3735	Fundamental of Telemetry, Telecommand& Transponder	3	0	0	3	1	3
2	DE	DTA-3736	Jamming and ECM/ECCM Technologies	3	0	0	3	1	3
2	DE	DTA-3737	Software Defined Radios	3	0	0	3	1	3
2	DE	DTA-3738	Advanced Lightweight and Composite Structures	3	0	0	3	1	3
2	DE	DTA-3739	Test Methodologies for Dew Systems (Lasers & Microwave)	3	0	0	3	1	3
2	DE	DTA-3740	Advanced Analytical Techniques/Lab Testing	3	0	0	3	1	3
2	DE	DTA-3741	Sonar System Engineering	3	0	0	3	1	3
			ELECTIVE - 4						
2	DE	DTA-3742	Unmanned Aerial Vehicle Design	3	0	0	3	1	3
2	DE	DTA-3743	Naval Ocean Analysis and Prediction	3	0	0	3	1	3
2	DE	DTA-3744	Modelling &Simulation Of Laser Matter Interaction	3	0	0	3	1	3
2	DE	DTA-3745	Computational Aerodynamics	3	0	0	3	1	3
2	DE	DTA-3746	Launch Vehicle Design & Analysis	3	0	0	3	1	3
2	DE	DTA-3747	Acquisition, Tracking & Pointing Technology	3	0	0	3	1	3

2	DE	DTA-3748	Data Acquisition, Tracking & Post Flight Analysis	3	0	0	3	1	3
2	DE	DTA-3749	Air Independent Propulsion and Batteries	3	0	0	3	1	3
2	DE	DTA-3750	Advanced Digital Modulation Technologies & Standards	3	0	0	3	1	3
2	DE	DTA-3751	Trajectories Modelling & Simulation	3	0	0	3	1	3
2	DE	DTA-3752	Sensor Technology	3	0	0	3	1	3

## SEMESTER – I

COURS	E TITLE	Д	DVANO	CREDITS	4									
COURS	E CODE		MA	A0704		COURS	SE CATEO	ORY	DE	L-T-P-S	4-0-0-0			
Vers	sion		1	1.0		Approval Details			23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3			
ASSESSM	ENT SCH	IEME			•									
First Pe Assess		1	Second Asses	Periodi ssment		Assi	eminar/ ignmen Project		Surprise Test / Quiz	Attendance	ESE			
15	%		1	5%			10%		5%	5%	50%			
Course Ol	ojective	To provide knowledge to the students about probability theory, algebra, solutions Differential equations, Transform techniques, special functions & their applications the areas with defence relevance.												
Course Outcome  Upon completion of this course, the students will be able to  1. Know the methods for solving differential equations, generating functions.  2. Understand basic concepts of Fourier Transform, Laplace Transforms and solv problems with periodic functions, step functions, impulse functions and convolution.  3. Demonstrate MATLAB programming for engineering problems.  4. Understand the utilization of mathematical methods for solving problems havin relevance to defence applications.														
CO, PO M	IAPPING	3												
со	PO- 1	PO- 2	PO-	PO- 4	PO- 5	PO- 6	PO- 7							
CO-1	3	3	-	3	3	-	-							
CO-2	3	2	-	-	-	-	-							
CO-3	3	3	-	3	2	-	-							
CO-4	3	3	-	3	2	-	-							
			1:	Weakly	/ relate	ed, 2: Mo	oderatel	y relate	d and 3: Strongly r	elated				
MODULE	1:										(7)			
Element Algebra.		obab	ility and	d Statis	stics, (	compo	nents c	of oper	ations research,	Linear	CO-1 BTL-3			
MODULE	2:										(7)			
Ordinary function			•		Nume	rical m	ethods	for OI	DE and P.D.E. Ge	nerating	CO-2 BTL-3			
MODULE 3: (7)														
Transfor	m Tec	hniqu	ies, Fou	ırier se	eries, I	ourier	Transf	orm, L	aplace Transfor	m	CO-2 BTL-3			
MODULE	4:										(6)			

·	s: Power series method, Frobenious method, Legendre equation, omials, Bessel equation, Bessel functions of first kind, Orthogonal	CO-3 BTL-3						
MODULE 5:		(6)						
Elements of Rar block designs.	nsey theory, theorems of Burnside and Polya, and balanced incomplete	CO-3 BTL-3						
MODULE6:		(6)						
science and o	reas with defence relevance range from mathematics to computer perations research, applications in probability, game theory, network theory, and experimental design.	CO-4 BTL-4						
REFERENCE BOOKS								
1.	"Advanced engineering mathematics", by Kreyszig. Publisher: Wiley.							
2.	2. "Advanced engineering mathematics", by Jain/Iyenger. Publisher: Narosa.							
3. "Advanced engineering mathematics", by Taneja. Publisher: I K international .								
4. "Advanced engineering mathematics", by Alan Jeffery. Publisher: Academic Press.								
5.	"Advanced engineering mathematics", by Peter V. O"Neil. Publisher: Cen	gage Learning.						

COURS	COURSE TITLE WARFARE SIMULATIONS & STRATEGIES CREDITS													
COURS	COURSE CODE DTB0701 COURSE CATEGORY DE L-T-P-S													
Vers	sion		1	1.0		Appr	oval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-4				
ASSESSM	ENT SCH	IEME												
First Pe Assess		1 9	Second Asses	Periodi ssment		Assi	eminar/ ignments/ Project	Surprise Test / Quiz	Attendance	ESE				
15	50%													
Course Ol	Course Objective  To provide knowledge to the students about warfare system and affluent them with combat modeling using mathematical modeling.													
Course Ou	Upon completion of this course, the students will be able to  1. Understand the systems used in warfare scenario.  2. Understand combat simulation & modelling  3. Understand the war gaming simulation & modelling and human factor representation.													
CO, PO N	IAPPING	3												
со	PO- 1	PO- 2	PO-	PO- 4	PO- 5	PO-	PO- 7							
CO-1	3	-	2	-	-	-	-							
CO-2	3	2	3	3	3	-	-							
CO-3	3	2	3	3	3	-	-							
			1:	Weakly	/ relate	ed, 2: Mo	oderately relate	ed and 3: Strongly re	elated					
MODUL	E 1:									(7)				
Types of operation	•			ea, air;	Lifec	ycle: co	oncept, desig	n, pre-production	n, production,	CO-1 BTL-2				
MODUL	E 2:									(7)				
Military capabilities: air warfare, surface warfare, sub surface warfare, littoral warfare  CO-2  BTL-2														
MODULE 3: (7)														
	Introduction to the methods used in modeling combat and their application in support of defence decision making and training, Combat simulation.  CO-2  BTL-3													
MODUL	E 4:									(7)				

War gaming/int	eractive simulation, Lanchester"s equations, Mathematical models of	CO-2,3								
combat.										
MODULE 5: (6)										
War gaming and	A combat modeling in practice, manual war gaming	CO-3								
war gaming and	d combat modeling in practice, manual war gaming.	BTL-4								
MODULE 6:		(6)								
Lluman factors	representation in war gaming and combat modeling	CO-3								
numan factors	representation in war gaming and combat modeling.	BTL-4								
REFERENCE BOOKS										
	"DefenseModeling, Simulation, and Analysis: Meeting the Challeng	e". Publish-er:								
1.	National Academies Press (October 22, 2006).									
2.	"Introduction to Electronic Warfare Modeling and Simulation" by Dav	vid L. Adamy".								
۷.	Publisher: Artech Print on Demand (October 31, 2002).									
"Engineering Principles of Combat Modeling and Distributed Simulation", by An-										
dreasTolk (Editor), Old Dominion University. Publisher : John Wiley & Sons.										
4.	Literature / books suggested by respective course Lecturers.									

COURS	E TITLE			SYSTE	MS A	ND WA	RFARE P	LATI	FORMS	CREDITS	4			
COURS	E CODE										4-0-0-0			
Vers	sion		:	1.0		Appr	oval Detai	ls	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3			
ASSESSM	ENT SCH	HEME												
First Pe Assess		I	Second Asse	Periodi ssment		Assi	eminar/ ignments, Project	/	Surprise Test / Quiz	Attendance	ESE			
15	15% 15% 10% 5% 5%													
Course Ol	ojective	<ol> <li>To provide knowledge to the students about various types of military platforms used in air, naval &amp; land warfare.</li> <li>Students will also be apprised for weapon system and self-protection strategies and techniques.</li> </ol>												
Course O	Course Outcome  Upon completion of this course, the students will be able to  1. Understand types of warfare platform used for Army, Air and Marine and their design fundamentals.  2. Understand the weapon systems like guns, ordnance, missiles projectiles, mines/countermines, lasers, undersea weapons, air-launched weapons, anti-aircraft, anti-ship and anti-submarine.													
CO, PO N	IAPPING	3												
со	PO- 1	PO-	PO-	PO-	PO- 5	PO-	PO- 7							
CO-1	3	-	-	3	2	2	-							
CO-2	3	-	-	3	-	2	-							
			1:	Weakly	y relate	ed, 2: M	oderately	relate	ed and 3: Strongly re	elated				
MODULE	1:										(7)			
Types of operation	•		•	ea, air;	; Lifec	ycle: co	oncept, d	esig	n, pre-productio	n, production,	CO-1 BTL-2			
MODULE	2:										(7)			
Ship design fundamentals: buoyancy, stability, ship resistance, survivability; damage control, NBCD, crew numbers, power requirements. Submarine design: buoyancy, stability, hull/tank design, air interdependence.														
MODULE	MODULE 3: (7)													
control	Mechanics of flight: fixed and rotary wing, straight and level flight of aircraft, aircraft control and movement, aircraft control surfaces, aerodynamics, power requirements, range; speed, ceiling, survivability, payload.													
MODULE	4:										(6)			

Military vehicle	fundamentals: tracked, wheeled, A, B and C vehicles.	CO-1 BTL-2	
MODULE 5:			(6)
mines/ counter	ns: guns, ordnance, missiles, rockets, bombs, sub- munitions, projectiles, rmines, lasers, undersea weapons, air-launched weapons, anti-aircraft, anti-ship, anti-submarine.	CO-2 BTL-2	
MODULE6:		(	(6)
	and Protection systems: Armour, smoke, chaff, decoys; Introduction to on, lab tests and flight trials.	CO-2 BTL-2	
REFERENCE BOOK	S		
1.	"Light And Heavy Vehicle Technology ", by Nunney. Publisher Elsevier.		
2.	"Practical approach to motor vehicle engineering and maintenance", by E et. Al. Publisher: Yesdee.	Bonnick Allan	l
3.	"Automotive Vibration Control Technology: Fundamentals, Materials, Con Simulation, and Applications", by Trelleborg	struction,	
4.	"An Introduction to Weapons Systems", by Yacov Bar-Shlomo. Publisher: Cre Independent Publishing Platform.	eate Space	
5.	"Heavy Vehicle Mechanics", by Ian Nicholson. Publisher: McGraw-Hill Educat	tion – Europe	·.
6.	"Military Laser Technology for Defense: Technology for Revolutionizing 21st Warfare", by Alastair D. McAulay. Publisher: Wiley-Interscience; 1st edition.	Century	

COURSE	URSE TITLE WARFARE SIMULATIONS & STRATEGIES LAB CREDITS										
COURSE	COURSE CODE DTB0731 COURSE CATEGORY DE L-T-P-S										
Versi	on	LEARNING LEVEL	BTL-3								
LIST OF EX	PERIMEN <sup>*</sup>	ΓS									
1.	1. Lab experiments will be added in consultation with DRDO labs considering the available facilities.  CO-BTL-3										

COURS	E TITLE		SYSTEMS AND WARFARE PLATFORMS LAB  CREDITS											
COURS	E CODE		DTB0732 COURSE CATEGORY DE L-T-P-S											
Ver	Version     1.0     Approval Details     23 ACM, 06.02.2021     LEARNING LEVEL										BTL-3			
ASSESSM	ASSESSMENT SCHEME													
	First Periodical Assessment Seminar/ Assignments/ Project Surprise Test / Quiz Attendance ESE													
1!	15% 15% 5% 5%									50%				
Course O	bjective					1								
Course O	utcome			Upon	comple	etion of	this cou	ırse, the	e studen	ts will be able to				
CO, PO	//APPING	G												
со	PO- 1	P(		PO- 3	PO- 4	PO- 5	PO-	PO- 7						
CO-1														
CO-2														
CO-3														
1: Weakly related, 2: Moderately related and 3: Strongly related														
LIST OF E	LIST OF EXPERIMENTS													
1.														

# **SEMESTER I - ELECTIVE -1 COURSES**

COURS	E TITLE			ROCKE	TS &	MISSIL	ES FUNDAM	ENTALS	CREDITS	3			
COURS	COURSE CODE DTB0751 COURSE CATEGORY DE L-T-P-S									3-0-0-0			
Vers	sion		1	1.0		Appr	oval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3			
ASSESSM	ENT SCH	IEME											
First Pe Assess		I s	Second Asses	Periodi ssment		Assi	eminar/ gnments/ Project	Surprise Test / Quiz	Attendance	ESE			
15	5%	50%											
Course Ol	Course Objective  To provide knowledge to the students about missile system, classification of missiles, aerodynamics of missiles, subsystems and missile trajectory.												
Course O	Course Outcome  1. Understand basics of missile physics as well as the engineering aspects of missile integration. 2. Understand physics behind guided missiles and aero dynamics of missiles. 3. Characterization of sub-systems used in missiles.												
CO, PO N	1APPING	3											
со	PO- 1	PO- 2	PO-	PO-	PO- 5	PO-	PO- 7						
CO-1	3	-	-	2	2	-	-						
CO-2	3	-	-	2	2	-	-						
CO-3	-	-	3	2	2	-	-						
			1:	Weakly	/ relate	ed, 2: Mo	oderately relat	ed and 3: Strongly re	elated				
MODUL	E 1:									(5)			
Basics o	f Missi	le Ph	/sics, In	trodu	ction 1	to Guid	ed Missiles,	Classification of I	Missiles.	CO-1 BTL-2			
MODUL	E 2:									(5)			
Missile Aerodynamic Configurations, Introduction to Missile System, Interrelationship between various Missile Sub-Systems.  CO-2 BTL-2													
MODUL	E 3:									(5)			
	Basic Characteristics of Guided Missile Systems, Missile System Reliability, Range dispersion and CEP Concept,  CO-2 BTL-2												

MODULE 4:		(7)
Design, System	Layout and integration of Sub-Systems.	CO-3
		BTL-4
MODULE 5:		(7)
	nsformation, Transformation Matrices. Two, Three and Six DOF otion, Ballistic Missile Trajectory.	CO-3 BTL-3
MODULE6:		(7)
Effect of Curvat	ure of Earth, Rotation of Earth, Variation of Gravity on Missile Trajectory.	CO-3 BTL-2
REFERENCE BOOKS	S	
1.	"Fundamentals of Guided Missiles",by S. R. Mohan. Publisher: Defence Development Organisation.	Re-search and
2.	"Estimation and Prediction of Ballistic Missile Trajectories" by Jeffrey David R. Vaughan. Publisher: RAND (29 May 1996)	y A. Isaac-son,
3.	"Introduction to Modern Algebra and Matrix Theory", by O. Schreid Martin David, Melvin Hausner. Publisher: Dover Publications.	er, E. Sperner,

COURS	E TITLE			ADVA	NCED	THER	MAL E	NGINE	ERING	CREDITS	3			
COURS	E CODE					COURS	SE CATE	GORY	DE	L-T-P-S	3-0-0-0			
Vers	sion		1	1.0		Approval Details 23 ACM, 06.02.2021			-	LEARNING LEVEL	BTL-3			
ASSESSM	ENT SCH	IEME												
First Pe Assess		S		Periodi ssment		Assi	eminar gnmen Project	ts/	Surprise Test / Quiz	Attendance	ESE			
15	5%	5%	50%											
Course Objectiv	re	To provide knowledge to the students for the thermal management requirements / problems of the defence systems and thermal system design & simulation for the various air, land & naval defence systems utilized under different environmental conditions.												
Course Outcom	e	1. 2. 3.	Und Carr Und	erstan y out C	d ther CFD sii d the	mal de mulatio concep	esign a	nd sim	students will be ulations for syste heat exchanger management re	em design. s, refrigeration				
Prerequis	ites:													
CO, PO N	1APPING	i												
СО	PO-	PO-	PO-	PO-	PO-	PO-	PO-							
CO-1	3	3	3	3	5 3	6	7							
	3	<u> </u>	-	3	3	<u> </u>	-							
CO-2	3		-	-	3	-	-							
			1:	Weakly		ed. 2: Mo	derate	lv relate	ed and 3: Strongly re	elated				
MODUL	E 1:							7			(7)			
	therma		_	-				_	and simulation	, Heat	CO-1 BTL-3			
MODUL	E 2:										(7)			
Comput	CO-2 Computation fluid dynamics (CFD), Thermal Finite Element Analysis  BTL-4													
MODUL	MODULE 3: (6)													
Heat Exc	Heat Exchangers for: Heat Exchanger Network Design.  CO-2 BTL-4													
MODUL	E 4:										(5)			

Refrigeration, H	lumidifiers, Air Washers and Cooling Towers.	CO-2
		BTL-4
MODULE 5:	(6)	
Thermal manag vehicles etc.)	CO-3 BTL-4	
MODULE 6:		(5)
Thermal testing	CO-3	
systems.	BTL-4	
REFERENCE BOOKS	S	
1.	"Fundamentals of Heat and Mass Transfer", by Incropera and Dewitt. Pul Wiley.	olication: John
2.	"Convective Heat and Mass Transfer", by W M Kays and M E Crawford. Pomos McGraw-Hill publishing Company.	ublisher:
3.	"Thermal Radiation Heat Transfer" by J Siegel and R Howell. Publisher: El	sevier.
4.	"Manohar Prasad, Refrigeration and Air Conditioning", 3rd Edition, New International, 2015.	Age
5.	"Computational Fluid Dynamics – The Basics with Applications", by John Publisher :1st Edition, McGraw Hill, 2012.	D Anderson.
6.	"Thermal System Design and Simulation", by P.L. Dhar, 1st Edition.	

COURS	E TITLE		NUMER	ICAL N	/IETH C	DDS FO	R SCIENCE &	ENGINEERING	CREDITS	3			
COURS	E CODE					COURS	E CATEGORY	DE	L-T-P-S	3-0-0-0			
Ver	sion		:	1.0		Appr	oval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3			
ASSESSM	ENT SCH	IEME			•								
First Pe Asses	riodica sment	I	Second Periodical Assessment			Assi	eminar/ gnments/ Project	Surprise Test / Quiz	Attendance	ESE			
15	5%		1	.5%			10%	5%	5%	50%			
Course Objectiv	<b>v</b> e	<ol> <li>To provide knowledge to the students to develop numerical methods aided by technology to solve algebraic equations, calculate derivatives and integrals, curve fitting and optimization techniques.</li> <li>The course will also develop an understanding of the finite element analysis and computational fluid engineering.</li> </ol>											
Course Outcome  1. Use the numerical techniques (algorithms) to find the solution (approalgebraic equations and system of equations.  2. Fit the data using interpolation technique and spline methods.  3. Use to finite element analysis, interpretation of analysis results.  4. Understanding of computational engineering process.									roximate)				
CO, PO M	//APPING	3	_			•							
со	PO- 1	PO- 2	- PO- 3	PO-	PO- 5	PO-	PO- 7						
CO-1	3	3	2	-	-	-	-						
CO-2	3	3	-	3	-	-	-						
CO-3	3	3	2	3	-	-	-						
CO-4	3	3	-	-	-	-	-						
		I	1:	Weakly	y relate	ed, 2: Mo	derately relate	d and 3: Strongly re	elated				
MODUL	E 1:									(5)			
Introduc	ction, s	oluti	ion of n	on-line	ear equ	uations	, solution of	inear systems.		CO-1 BTL-3			
MODUL	E 2:									(5)			
Introduc intergra	ations &	CO-2 BTL-3											

**MODULE 3:** 

(5)

Matrices and t stability of solu	ypes of linear systems, direct elimination methods, conditioning and	CO-3 BTL-3					
Stubility of 3010	acions.						
MODULE 4:		(7)					
	Finite Element Analysis (FEA) simulation software, Pre- and Post-	CO-4					
-	ee mesh and Mapped mesh techniques, Quality checks on nodes and ndary conditions.	BTL-4					
MODULE 5:	indaily conditions.	(7)					
	o computational fluid engineering, Fundamental equations,	CO-4					
Computational	Engineering Process.	BTL-3					
MODULE6:		(7)					
		CO-5					
Fluid Simulatio	n for Computer Graphics, Modelling techniques.	BTL-4					
REFERENCE BOOK	cs						
1.	"Numerical Methods for Scientific and Engineering Computation", by M. S.R.K. Iyengar. Publisher: New Age International Publishers.	K. Jain and					
2.	"Applied Numerical Analysis", by Gerald & Wheatley. Publisher Addison	– Wesley.					
3.	"Introductory Methods of Numerical Analysis", by, S.S. Sastry. Publisher: 5th Edition,New Delhi, 2009.	PHI Pvt. Ltd.,					
4.	"Applied Numerical Methods Using MATLAB", by W.Y. Yang, W. Cao, T.S. Chung and J. Morris. Publisher: Wiley India Edn., 2007.						
5.	"Numerical Methods for Engineers with Programming and Software App Steven C. Chapra and Ra P. Canale. Publisher: Tata McGraw Hill, 2014 7th						
6.	"Finite Element Procedures", by K.J. Bathe, Prentice Hall of India.						
7.	"Finite Elements in Engineering", by Chandrupatla and Belegundu.						
8.	"Finite element Method", by J.N.Reddy.						

COUR	SE TITI	.E			CON	MUN	IICATIO	CREDITS	3			
COUR	SE COE	ÞΕ		DTB	0753		COURS	E CATE	GORY	DE	L-T-P-S	3-0-0-0
Ve	rsion			1	L.O		Approval Details			23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSM	ENT SC	НЕМЕ										
First P Asse	eriodi ssmen		Se		Periodi ssment		Seminar/ Assignments/ Project			Surprise Test / Quiz	Attendance	ESE
1	15%		15%					10%		5%	5%	50%
Course Objective  To provide knowledge to the students about communication system desi calculation of bandwidth and signal-to-noise ratio of a signal, digital communicat systems, performance evaluation, explain the concepts of link budget and multi accesses as it applies to wireless communication.										ommunication		
Course Outcome  Upon completion of this course, the students will be able to  1. Understand communication system design methodologies, communication system architecture, analogue & digital modulation techniques.  2. Computation of data rates, bandwidth, BER.  3. To carry out the link budget analysis.									unication			
CO, PO N	/IAPPIN	IG										
со	PO- 1	PO-	-2	PO- 3	PO- 4	PO- 5	PO- 6	PO- 7				
CO-1	3	-		-	2	3	-	-				
CO-2	3	-		-	2	3	-	-				
CO-3	3	-		-	-	3	-	-				
				1: W	l Jeakly r	elated	2: Mod	l erately	related	and 3: Strongly re	 lated	
MODUL	E 1:				-			-				(6)
		on Co	mm	unicat	tion Sy	/stems	, Basic	s of w	reless	channel behavi	or.	CO-1
												BTL-2
MODUL	.E 2:											(6)
Digital c	lata co	ommı	unic	ation	system	ns, dig	ital sig	naling	techni	ques.		CO-1
												BTL-2
MODUL	.E 3:											(5)
Data rat	Data rates and bandwidth calculation in digital data communication systems.  CO-2  BTL-3											
MODUL	E 4:											(7)
		error	and	d BER	calcula	ation,	Modul	ation t	echno	logies (analogue	e & digital),	CO-2
Voice so	-											BTL-3

MODULE 5:		(7)						
	Communication system architectures, terminal design and performance, associated information systems.							
MODULE 6:	MODULE 6: (5							
Link budget calc	CO-3 BTL-3							
REFERENCE BOOKS								
1.	"Fundamentals of communication systems," by Proakis and Salehi. Publ Pearson.	isher:						
2.	"Communication Systems", by Simon Haykin and Michael Moher. Publisher: Wiley.							
3.	"Modern digital and analog communication systems," by B.P. Lathi and Publisher: Oxford University Press.	Zhi Ding.						

COURS	E TITLE		Α	DVAN	CED N	ЛЕСНА	NICAL	IEERING	CREDITS	3	
COURS	E CODE					COURS	E CATE	GORY	DE	L-T-P-S	3-0-0-0
Vers	sion		1	0		Appr	oval De	tails	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSM	ENT SCH	IEME			•						
First Pe Assess		l Se	econd I Asses	Periodi ssment		Seminar/ Assignments/ Project			Surprise Test / Quiz	Attendance	ESE
15	5%		1	5%			10%		5%	5%	50%
Course Ol	Course Objective To provide knowledge to the students about different methods of mechanical system analysis, mechanical simulation soft-ware and use of computational techniques for structural and fluid dynamics.									-	
Course O	<ol> <li>Upon completion of this course, the students will be able to</li> <li>Understand mechanical analysis software and carry out mathematical modeling for simulation of phenomena behind the structural and fluid dynamics.</li> <li>Carry out design &amp; finite element analysis of components of systems and subsystems.</li> <li>Carry out the CFD analysis.</li> </ol>										
CO, PO N	1APPING	3				,					
СО	PO-	PO-	PO-	PO-	PO-	PO-	PO-				
	1	2	3	4	5	6	7				
CO-1	3	2	-	3	3	-	-				
CO-2	3	2	-	3	3	-	-				
CO-3	3	2	-	3	3	-	-				
			1:	Weakly	/ relate	d, 2: Mo	derate	y relate	ed and 3: Strongly re	elated	
MODUL	E 1:		(5)								
Introduc	ction to	tools	for m	echani	ical de	sign &	analys	is			CO-1
											BTL-2
MODUL	E 2:	(7)									
Stress e	nginee	ring –	theory	/ & sim	nulatio	on, me	chanics	of sol	ids		CO-1 BTL-2
MODUL	E 3:										(7)
	Finite element methods in structural dynamics, Structural integrity  CO-2										
				: <b>-: -:</b>		,	, - 3. 3	• •	0 -1		BTL-3
MODUL	E 4:										(5)
Fluid me	echanic	cs	_		_			_			CO-2
MODIII	C F.										BTL-3
INIODUL	MODULE 5: (7)										

Communitational	fluid duna naice	CO-3							
Computational	nuid dynamics	BTL-3							
MODULE 6:		(5)							
Component design, Applied materials and corrosion									
REFERENCE BOOKS									
1.	"An Introduction to Computational Fluid Dynamics: The Finite Volume Method " by H. Versteeg. Publisher: Pearson.								
2.	"Computational Fluid Dynamics the Basics with Applications", by Joh Publisher: McGraw Hill Education (1 July 2017)	n D. Ander Jr.							
3.	"Fluid Mechanics: Volume 2: Foundations and Applications of Mechanics (Cam-bridge-iisc)" by C. S. Jog. Publisher: Cambridge University Press.								
4.	Fundamentals of Machine Component Design", by Robert C. Juvinall, Ku Publisher: John Wiley & Sons	rt M. Marshek.							

# **SEMESTER I - ELECTIVE - 2 COURSES**

COURS	E TITLE	A	UTONO	OMY A	ND N	AVIGA	TION TE	CHNO	DLOGY	CREDITS	3
COURS	E CODE		DTB	0752		COURS	E CATEG	ORY	DE	L-T-P-S	3-0-0-0
Vers	sion		1	1.0		Appr	oval Deta	ils	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMI	ENT SCH	HEME									
First Pe Assess		ı	Second   Asses	Periodi ssment		Assignments/			Surprise Test / Quiz	Attendance	ESE
15	%		1	5%			10%		5%	5%	50%
Course Ob	ojective		•			_			nts about techr tems, UAV guida		
Course Ou	Course Outcome  Upon completion of this course, the students will be able to  Describe the basic principle of operation of a global navigation satellite system  Understand the navigation systems and derive the navigation equations.  Carry out path planning the UGV / UAV.  Solve the equations for calculating a position estimate from a given satellite constellation.							tions.			
CO, PO N	1APPING	3									
СО	PO-	PO-	PO-	PO-	PO-	PO-	PO-				
	1	2	3	4	5	6	7				
CO-1	3	-	2	-	3	-	-				
CO-2	3	-	3	-	3	-	-				
CO-3	3	-	2	-	3	-	-				
CO-4	3	-	-	-	3	-	-				
			1:	Weakly	/ relate	d, 2: Mo	derately	relate	d and 3: Strongly re	elated	
MODUL	E 1:										(6)
Introduc guidance			_	_		•		idanc	e approaches: co	onventional	CO-1 BTL-3
MODUL	E 2:										(7)
	Geodetic fundamentals of navigation, positioning, reference- and coordinate systems and computational methods for navigation and positioning on the surface of the earth.  CO-2 BTL-3										
MODUL	E 3:										(7)
Geomet for UGV	_				ng and	follov	ving, and	dopt	imal guidance; p	ath planning	CO-3 BTL-3

MODULE 4:		(5)							
Navigation app System (GPS)	roaches: navigation systems, Understanding the Global Positioning	CO-1,3 BTL-3							
MODULE 5:		(6)							
GNSS (Global N	CO-3 BTL-3								
MODULE 6:									
SLAM (Simultar avoidance.	CO-4 BTL-3								
REFERENCE BOOK	S								
1.	"Global Navigation Satellite Systems: Insights Into GPS", by Bhatta, B., Global Compass, and Others. Publisher: BS Publications, New Delhi 2010.	onass, Galileo,							
2.	"Global Positioning Systems, Inertial Navigation, and Integration", by Gre Weill, L. R., Andrews, A. P., Publisher: John Wiley & Sons, New York, 2006	-							
3.	"GNSS – Global Navigation Satellite Systems" by Verlag Wien, Hofmann-Wellenhof, B.								
4.	"Global Positioning System Theory and Practice", Hofmann-Wellenhof, B Lichtenegger, H., Verlag Wien, Collins, J. Publisher: Springer 2001.	.,							

COURSE TITLE	OPTIN	IIZATIOI	N THE	ORY &	APPLICA	TION	<b>NS</b>	CREDITS	3	
COURSE CODE				COURS	E CATEGO	RY	DE	L-T-P-S	3-0-0-0	
Version		1.0		Appr	oval Detai	ls	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT SCH	EME									
First Periodical Assessment		d Period essment		Seminar/ Assignments/ Project			Surprise Test / Quiz	Attendance	ESE	
15%		15%			10%		5%	5%	50%	
<ol> <li>To cover the concepts of optimization methods and algorithms developed for solving various types of optimization problems.</li> <li>Apply the mathematical results and numerical techniques of optimization theo to various Engineering and Analytics problems and applications in both theoretical and applied research areas.</li> </ol>										
Course Outcome	1. Ur production production as as 3. Ur sto 4. Ur	<ol> <li>Upon completion of this course, the students will be able to</li> <li>Understand mathematical modeling and the formulation of optimization problems.</li> <li>Create programs based on different optimization algorithms using IT tools, such as MATLAB etc.</li> <li>Understand theory about linear programming, integer programming, and stochastic programming</li> <li>Understand the process of finalizing design of engineering systems by applying the numerical optimization.</li> </ol>								
Prerequisites:										
CO, PO MAPPING	i									
CO PO-	PO- PO	- PO-	PO-	PO-	PO-					
1	2 3	4	5	6	7					
CO-1 3	-   -	-	1	-	-					
CO-2 3	- 2	-	3	-	-					
CO-3 3	- 2	-	3	-	-					
CO-4 3		-	-	-	-					
		1: Weakl	y relate	d, 2: Mo	derately r	relate	d and 3: Strongly re	elated		
MODULE 1:										
Introduction to	optimizati	on, class	ical op	timizat	ion techr	nique	!S.		CO-1	
	•								BTL-1	

 $Linear\ programming\ \&non-linear\ programming\ and\ dimensional\ minimization\ methods.$ 

BTL-2

MODULE 3:		(7)						
Non coordinatio	n optimization techniques, coordinated optimization techniques, gramming.	CO-2 BTL-3						
MODULE 4:		(6)						
Dynamic program	mming, integer programming, stochastic programming.	CO-3 BTL-3						
MODULE 5:	<u>,                                      </u>	(5)						
Solution of a variety of design problems in mechanical engineering, using numerical optimization techniques.								
MODULE6: (5)								
Additional Topic	cs: multi-objective, optimization, game theory, optical control theory.	CO-4 BTL-2						
REFERENCE BOOKS	5							
1.	"Numerical Optimization", by Jorge Nocedal and Stephen J.Write. Publish 2006.	ner: Springer,						
2.	"Practical methods of Optimization" by R.Fletcher. Publisher: Wiley, 198	7.						
3.	"Iterative method for optimization" by C. T. Kelley. Publisher: SIAM, 1999	9.						
4.	"Introduction to Nonlinear Optimization:Theory, Algorithm, and Application MATLAB. MOS-SIAM Series on Optimization", by Amir Becker.	ionwith						
5.	"Dynamic Programming and Optimal Control (Volumel) " by Dimitri P. Be Publisher : Athena Scientic, 2005.	rtsekas.						
6.	Optimization Theory and Applications", by SS Rao.							

COURS	E TITLE	M	ILITAR	Y ELEC	TRON	NICS SY	STEM	ENGIN	EERING	CREDITS	3
COURS	E CODE					COURS	SE CATE	GORY	DE	L-T-P-S	3-0-0-0
Vers	sion		1	1.0		Appr	oval De	tails	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSM	ENT SCH	IEME									
First Pe Assess		I S	econd Asses	Periodi ssment		Assi	eminar gnmen Project	its/	Surprise Test / Quiz	Attendance	ESE
15	%		1	5%			10%		5%	5%	50%
Course Ol	ojective	re	quiren	nent fo	or mili	tary er	vironr	nent, g	about the learni eneration of sys s on the electron	tem requireme	•
Upon completion of this course, the students will be able to  1. Understand the military electronics systems.  2. Generate system design requirements as per mission needs & operation requirements.  3. To create digital simulation models.  4. Understand the limitations of the COTS available electronics systems.  5. Evaluate the radiation effects on the performance of electronics systems									tems.		
CO, PO M	APPING	i									
со	PO- 1	PO- 2	PO-	PO- 4	PO- 5	PO-	PO-				
CO-1	1	1	1	1	1	1	1	-			
CO-2	3	-	-	2	-	-	-				
CO-3	3	-	2	-	-	-	-	-			
CO-4 CO-5	3	-	-	3	-	-	-	-			
	3	_					<u> </u>				
1105:::	F 4		1:	weakly	relate	ea, 2: Mo	oderate	iy relate	d and 3: Strongly re	eiated	(-)
MODUL							- 1			1	(5)
Introduction to electronics engineering concepts and methods for the design and integration of complex defense systems.  CO-1 BTL-2											
MODULE 2: (5)											
Familiar defense	•		system	s engi	neerir	ng proc	ess th	rough o	case studies of re	epresentative	CO-2 BTL-2
MODUL		<u> </u>									(6)
	ntroduction to methods used for determination of system requirements from mission needs and operational requirements.  CO-2 BTL-3										

MODULE 4: (7)									
Digital simulation	CO-3 BTL-4								
MODULE 5: (7									
Limitations of c electrostatic br	CO-3 BTL-3								
MODULE 6: (6)									
Radiation effect military integra	CO-4 BTL-3								
REFERENCE BOOKS									
1.	"Introduction to Electronic Defense Systems", by Neri Filippo. Publisher: Artech House Publishers.								
2.	"Military Handbook of Electronic Reliability design", by US Department of Defence.								
3.	"Defence Electronics Standards and Quality Assurance", by Ray Tricker. Pub-: Elsevier								
4.	"Handbook of Defence Electronics and Optronics: Fundamentals, Technologies and Systems", by Anil K. Maini. Publisher: John Wiley & Sons Ltd								
5.	"Digital Simulation Methods", by M.G. Hartley. Publisher: P. Peregrinus Ltd								
6.	6. "Analysis and Simulation of Noise in Nonlinear Electronic Circuits and Systems", By Alper Demir. Publisher: Springer.								

COURS	E TITLE	SY	SYSTEM ENGINEERING & ANALYSIS							CREDITS	3	
COURSE CODE						COURSE CATEGORY			DE	L-T-P-S	3-0-0-0	
Version			1.0			Approval Details			23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT SCHEME												
First Periodical Assessment		l s	Second Periodical Assessment			Seminar/ Assignments/ Project			Surprise Test / Quiz	Attendance	ESE	
15%			15%			10%			5%	5%	50%	
Course Ob	To provide knowledge to the students about the military systems engineering, system requirements, basics of system design, architecture, operational requirements system reliability and management.									<u> </u>		
Course Ou	Upon completion of this course, the students will be able to  1. Understand the system design requirements, architecture, functional requirements  2. Generate the system requirements documents as per the requirement analysis.  3. Understand the system reliability, maintainability, usability issues.  4. Carry out the system reliability analysis.											
CO, PO MAPPING												
со	PO-	PO-	PO-	PO-	PO-	PO-	PO-					
	1	2	3	4	5	6	7					
CO-1	3	-	-	-	-	-	-					
CO-2	3	3	-	-	-	-	-					
CO-3	3	3	2	-	-	-	-					
CO-4	3	3	-	-	4	-	-					
			1:	Weakly	, relate	d, 2: Mo	deratel	y relate	d and 3: Strongly re	elated		
MODUL	E 1:										(5)	
Fundamentals of systems engineering and system architecting of weapon system, system engineering. standards 15288, requirements analysis, functional analysis and allocation, preliminary system architecture.  CO-1  BTL-3												
											(5)	
Systems analysis, system design, and the basics of test and evaluation, Introduction to combat systems,									CO-2 BTL-3			
MODULE 3:										(6)		
System development phases (Conceiving, Designing, Implementing, and Operating),										CO-2 BTL-		
MODUL	E 4:										(7)	

Supportability, and producibility, System cost assessment and effectiveness estimation.  CO-3 BTL-3							
MODULE 5:  Supportability, and producibility, System cost assessment and effectiveness estimation.  MODULE 6:  Reliability analysis and management (basic tools and methods of reliability for developing complex systems including electronic components, mechanical components, and software), redundancy, graceful degradation, fault tolerance, MTBF.  CO-4  BTL-3  REFERENCE BOOKS  1. "The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc.  2. "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia  3. "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor Graw Hill.  5. "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	· · · · · · · · · · · · · · · · · · ·		CO-3				
Supportability, and producibility, System cost assessment and effectiveness estimation.  MODULE 6:  Reliability analysis and management (basic tools and methods of reliability for developing complex systems including electronic components, mechanical components, and software), redundancy, graceful degradation, fault tolerance, MTBF.  CO-4  BTL-3  REFERENCE BOOKS  1. "The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc.  2. "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia  3. "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor Graw Hill.  5. "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	reliability, maintainability, usability (including human factors and human performance).  BTL-3						
MODULE 6:  Reliability analysis and management (basic tools and methods of reliability for developing complex systems including electronic components, mechanical components, and software), redundancy, graceful degradation, fault tolerance, MTBF.  **The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc.  2. "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia  3. "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor Graw Hill.  5. "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  8 "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	MODULE 5:		(7)				
MODULE 6:  Reliability analysis and management (basic tools and methods of reliability for developing complex systems including electronic components, mechanical components, and software), redundancy, graceful degradation, fault tolerance, MTBF.  REFERENCE BOOKS  1. "The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc. 2. "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia 3. "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management. 4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  1. "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited Technology (Control of the Control of	Supportability	and producibility, System cost assessment and effectiveness estimation.					
Reliability analysis and management (basic tools and methods of reliability for developing complex systems including electronic components, mechanical components, and software), redundancy, graceful degradation, fault tolerance, MTBF.  1. "The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc. 2. "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia 3. "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management. 4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor Graw Hill. 5. "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  1. "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited		, ,, ,					
developing complex systems including electronic components, mechanical components, and software), redundancy, graceful degradation, fault tolerance, MTBF.  REFERENCE BOOKS  1. "The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc. 2. "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia 3. "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management. 4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  1. "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	MIODULE 6:		(6)				
and software), redundancy, graceful degradation, fault tolerance, MTBF.  8TL-3  REFERENCE BOOKS  1. "The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc. 2. "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia 3. "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management. 4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  8. "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	Reliability anal	ysis and management (basic tools and methods of reliability for					
REFERENCE BOOKS  1. "The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc.  2. "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia  3. "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor Graw Hill.  5. "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  6 "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	developing cor	mplex systems including electronic components, mechanical components,	CO-4				
"The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc.  "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia  "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor The State of Maintenance of Planned M	and software),	redundancy, graceful degradation, fault tolerance, MTBF.	BTL-3				
"The Engineering Design of Systems: Models and Methods", by Buede D.M.2. Publisher: John Wiley & Sons Inc.  "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia  "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor The State of Maintenance of Planned M							
Publisher: John Wiley & Sons Inc.  2. "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia  3. "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New York "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  8. "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	REFERENCE BOOK	KS					
Publisher: John Wiley & Sons Inc.  "Systems engineering fundamentals", by Defense Acquisition University Pressfort Belvoir, Virginia  "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New York "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited		"The Engineering Design of Systems: Models and Methods", by Buede D.	M.2.				
Belvoir, Virginia  "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	1.	Publisher: John Wiley & Sons Inc.					
Belvoir, Virginia  "System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.  "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	2	"Systems engineering fundamentals" by Defense Acquisition University Pressfort					
<ul> <li>"System Analysis Design and Development", by Charles S. Wasson. Publisher: Wiley Series in System Engineering and Management.</li> <li>"Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.</li> <li>"Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited</li> </ul>	2.						
Series in System Engineering and Management.  4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  6 "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited			her : Wilev				
4. "Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw Hill, New Yor   5. "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M  Graw Hill.  Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	3.	, , , , , , , , , , , , , , , , , , , ,					
"An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata M Graw Hill.  "Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West Press Limited	Δ		Hill New York				
Graw Hill.  "Reliability Engineering", by Srinath L S. Publisher : Affiliated East-West Press Limited							
"Reliability Engineering", by Srinath L S. Publisher : Affiliated East-West Press Limited	5.	4. "An introduction to Reliability and Maintainability Engineering", by Ebling CE. Tata Mc					
n I							
New Delhi, 2002.	6	"Reliability Engineering", by Srinath L S. Publisher : Affiliated East-West P	ress Limited,				
	0.						
7. "Engineering Maintainability", by Dhillon B S. Publisher : Prentice Hall of India.	7.	"Engineering Maintainability", by Dhillon B S. Publisher : Prentice Hall of	India.				

## **SEMESTER – II (AEROSPACE TECHNOLOGY)**

COURSE TIT		AEROSF SIMULA		M CONFIGUR	ATION	N, DESIGN &	CREDITS	4	
COURSE CO	DE			COURSE CATEGO	ORY	BS	L-T-P-S	4-0-0-0	
Version			1.0 Approval Details 23 ACM, LEARNING 06.02.2021 LEVEL						
ASSESSMENT	SCHEM	E							
First Period	lical	Second	Periodical	Seminar/		Surprise Test /	Attendance	ESE	
Assessme	nt	Asse	essment	Assignments	<b>;</b> /	Quiz			
				Project					
15%		:	15%	10%		5%	5%	50%	
Course Object	tive	The ma	in objective	of the course i	s to p	rovide knowled	ge to the stud	ents about the	
			-		•	rstem design, r	_		
		•	-	•	•	carrying structu		_	
		•	•			tability analysis.	•	, ,	
Course Outco	me	•		of this course, the s		<u> </u>			
						e system and	its design rea	uirements and	
			cess.	p.					
		•		snace vehicle	and a	articulate its be	nefits in writt	en and verhal	
		forr	_	Space vernere	una c	inticulate its be	inches in write	en ana versar	
				mothods for	aoro /	elastic analysis,	computations	l fluid analysis	
						elastic allalysis,	computationa	i ilulu allalysis	
				n aero-dynamics					
				_	ouna	to air, air to g	ground weapor	i system, UAV	
		moı	unted GW a	nd UCAVs.					
CO, PO Mappi	<u> </u>	1	DO 3	20.3	DO 4	DO 5	DO 6	20.7	
CO 1	PO-1		PO-2		PO-4	PO-5	PO-6	PO-7	
CO-2	3		3	3	- 2	2	3	2	
CO-3	3		1	-	<u>-</u>	-	-		
C0-4	3		1	-	_		-	-	
MODULE 1:	1							(6)	
Introduction	n (aero	-elastic	phenomena	and design req	uirem	ents), Introduct	ion to	CO-1	
missiles & s	•		-			,,		BTL-3	
MODULE 2:								(6)	
Structural re	Structural requirement, Structural and aerodynamic stiffness, Static aero-elasticity: CO-2								
torsional divergence, Structural vibration and modal analysis.  BTL-3									
MODULE 3: (7)									
Aerodynamic loads on an oscillating lifting surface, Characteristics of flutter and CO-2									
important design parameters, Methods for aero-elastic analysis, Computational fluid  BTL-3									
	dvance	es in aer	o dynamics	(Hypersonic Flo	ws an	d Aerodynamic	Heating).		
MODULE 4:								(7)	
Aircraft per	formar	nce (crui	sing, climb,	descent, takeof	f, land	ling, maneuver,	flight path).	CO-3	
								BTL-3	

MODULE 5:		(7)					
System's stability & control, aerodynamics control, Introduction to dynamic stability,							
first and second	BTL-3						
MODULE6:	(7)						
Introduction to	o air to air, ground to air, air to ground weapon systems, UAV mounted	CO-4					
GW and UCAV	GW and UCAVs.						
REFERENCE BOOKS	3						
1.	"Aircraft design: a conceptual approach", by D. Raymer						
2.	"Flight Dynamics Principles", by Michael V. Cook						
3.	"IntroductiontoStructuralDynamicsandAeroelasticity",byDeweyH.Hodge	s,G.AlvinPierce					
4. "Airplane Aerodynamics and Performance", by Chuan Tau Edward Lan							
5.	5. "Fundamentals of Structural Dynamics", by Roy R. Craig Jr., Andrew J. Kurdila.						
6.	Literature / books suggested by respective course Lecturers.						

Version 1.0 Approval Details 23 ACM, 06.02.2021 BT  ASSESSMENT SCHEME  Seminar/	-0-0 -L-3						
ASSESSMENT SCHEME  Seminar/	'L-3						
Seminar/							
Seminar/							
First Periodical   Second Periodical   Surprise Test /	SE						
15% 15% 10% 5% 5%	0%						
The main objective of the course is to provide knowledge to the students fundamental of satellite navigation, navigation mathematics, principles of navigation, INS/GNSS integration and missile control methods							
Upon completion of this course, the students will be able to  1. Understand the principles of satellite navigation, inertial navigation, radio positioning.  Course Outcome  2. Understand various aspects of designing a navigation system.  3. Develop mathematical model of missile dynamics.  4. Carry out simulation for aircraft/missile using mathematical tools like MATLAB.							
CO, PO Mapping							
CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7	7						
CO-1 3							
CO-2 3 - 2 - 2							
CO-3 3 2 3 - 3 2 2							
CO-4         3         3         3         3         2         3							
MODULE 1:	(6)						
maroduction to mangation, mangation mathematics.	D-1 'L-3						
MODULE 2:	(7)						
GNSS: fundamentals, Signals, and Satellites: Fundamentals of Satellite Navigation,	D-2 L-3						
MODULE 3:	(6)						
Errors and Geometry, Dead Reckoning, Attitude, and Height Measurement, Feature matching, INS/GNSS Integration.  CO-2 BTL-3							
MODULE 4:	(6)						
Missile Control Methods: Aerodynamic and Thrust Vector Control, Polar and Cartesian Control.  CO-3 BTL-3							
MODULE 5: (8)							
Mathematical Modeling of Missile Dynamics; Missile Actuators and Sensors. Roll and CO-3 Roll Rate Stabilization. BTL-3							
MODULE6:	(7)						

Design and Ar MATLAB	nalysis of Lateral Autopilots, 6 DOF simulation for aircraft/missile using	CO-4 BTL-4			
REFERENCE BOOK	S				
"ModernInertialTechnologyNavigation,Guidance,andControl",byAnthonyLawrence 2012. Publisher:Springer New York.					
2.	"The Global Positioning System & Inertial Navigation", by Jay Farrell. Publisher: McGraw-Hill Education (16 December 1998).				
3.	"MATLAB for Engineering Applications", by William Palm. Publisher: McGraw-Hill Education; 4th edition (February 6, 2018).				
4.	"Global Navigation Satellite Systems, Inertial Navigation, and Integration", by Andrews, A. P., Bartone, C. G. (2013). Publisher: John Wiley and Sons Inc.	y Grewal, M. S.,			
5.	"Principles of GNSS, inertial and multi-sensor integrated navigation systems" D. Publisher: ArtechHouse.	, by Groves, P.			
6.	"Optimal State Estimation", by Kalman, H Infinity.				
7.	"Nonlinear Approaches", by Simon, D. (2006). Publisher: Wiley-Interscienc	e			
8.	Literature / books suggested by respective course Lecturers.				

COURSE TITLE AEROSPACE PROPULSION CREDITS							4		
COURSE CO	COURSE CODE COURSE CATEGORY PC L-T-P-S								
Version			1.0	Approval Details		23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT S	ASSESSMENT SCHEME								
First Periodical Assessment			l Periodical essment	Seminar/ Assignments/ Project	9	Surprise Test / Quiz	Attendance	ESE	
15%			15%	10%		5%	5%	50%	
Course Object	ive	differer systems	nt criteria fo	e of the course is or the selection a f propulsion syste system.	nd e	evaluation of o	different types	of propulsion	
Course Outcor	me	<ol> <li>Kno syst</li> <li>Uno</li> <li>Uno</li> </ol>	owledge abo tem. derstanding	of this course, the stud out thermodynam of Rocket motor d of different desig	nics a	and fluid dyna n		·	
CO, PO Mappi	ng								
со	PO-1		PO-2	PO-3 PO	)-4	PO-5	PO-6	PO-7	
CO-1	3		2	1 -		-	-	-	
CO-2	3		2	1 -		-	-	-	
CO-3	3		2	1 -		-	-	- (7)	
MODULE 1:	n 0. m	odo of o	noration of	various propulsior	. cvct	toms basis		(7) CO-1	
thermodyna			•	various propuisioi	ısysı	terris, basis		BTL-3	
MODULE 2:		<u> </u>	71101111001					(8)	
Rocket motor design & analysis, Gas Turbine Engine design, GT engine efficiency, GT engine heat transfer & cooling.						iency, GT	CO-2 BTL-3		
MODULE 3:								(6)	
Aircraft performance, jet engine performance.						CO-2 BTL-3			
MODULE 4: (7)							(7)		
Jet engine control (compressor performance, axial turbine performance, Fuel systems & pumps, airframe fuel systems, hydro-mechanical fuel metering, Electronics engine control)						CO-3 BTL-3			
MODULE 5:								(6)	
System integ	gratio	n						CO-3 BTL-3	
MODULE6:								(6)	

Computational difference equ	CO-4 BTL-4							
REFERENCE BOOKS	REFERENCE BOOKS							
1. "Rocket Propulsion Elements", by George Paul Sutton and Oscar Biblarz. Pub-lisher: John Wiley & Sons								
2.	"Modern Engineering for Design of Liquid-Propellant Rocket Engines: Progress in Astronautics and Aeronautics Series" by Dieter K. Huzel, David H. Huang.							
3.	"An Introduction to Computational Fluid Dynamics: The Finite Volume Method" by H. Versteeg. Publisher: Pearson; 2nd edition.							
4.	"Computational Fluid Dynamics the Basics with Applications" by John D. An-ders Publisher: McGraw Hill Education (1 July 2017)	son, Jr.						
5.	"Fluid Mechanics: Volume 2: Foundations and Applications of Mechanics", by C Publisher: Cambridge University Press; 3rd edition.	C.S.Jog.						

COURSE	TITLE	AEROSPACE SYSTEM	2					
COURSE	CODE	0-0-2-0						
Version		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3		
LIST OF EX	LIST OF EXPERIMENTS							
1.	Lab experiments will be added in consultation with DRDO labs considering the available facilities.							

COURSE	TITLE	GUIDA	CREDITS	2				
COURSE	COURSE CODE COURSE CATEGORY DE		DE	L-T-P-S	0-0-2-0			
Version		on 1.0 Approval Details		23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3		
LIST OF EXI	LIST OF EXPERIMENTS							
1.	CO- BTL-							

## **SEMESTER- II (COMMUNICATION SYSTEMS & SENSORS)**

Version 1	DTD3703	COURSE CATEGORY	DE					
			L-T-P-S	4-0-0-0				
ACCECCNAENT COLIENAE	Version 1.0 Approval Details 23 ACM, LEARN LEVEL							
ASSESSMENT SCHEME								
	Second Periodical Assessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE			
15%	15%	10%	5%	5%	50%			
Course Objective	earning on the ra	of the course is to dar systems, radar n of radar elements,	parameters, ra	dar environm	ent, theory of			
Course Outcome	<ol> <li>Understand</li> <li>Apply approsystems to particular ca</li> <li>Understand</li> <li>Learn basic r</li> <li>Understand</li> </ol>	this course, the studenth the design of radar sopriate mathematical calculate system passes the major componer adar signal processing advanced radar techajor functions and approximate the major functions and approximate the system is a second control of the studenth the system is a second control of the system is a second control of the system is a system in the system in the system is a system in the system in the system is a system in the system in the system in the system is a system in the system in the system is a system in the system in the system in the system is a system in the system in the system in the system is a system in the system in the system in the system is a system in the system in the system in the system is a system in the system in the system in the system is a system in the system in the system in the system in the system is a system in the system in the system in the system in the system is a system in the s	ystems, solve raid and compute performance, and not so a modern rang techniques.	nge equations. er models rele nd assess the radar system	limitations of			
CO, PO Mapping					_			
CO PO-1	PO-2	PO-3 PO-4	PO-5	PO-6	PO-7			
CO-1 3	2	1 -	1	-	-			
CO-2 3	2	1 -	-	-	-			
CO-3 3	2	1 -	-	-	-			
CO-4 3								
CO-5 3	2	1 -	-	-	-			
CO-6 3	2	1  -	-	-	- (6)			
	MODULE 1: (6) Introduction to RADAR, Radar parameters/definitions, radar equations.  CO-1 BTL-3							
MODULE 2:					(6)			
Radar cross section (RCS) & Theory of detection, Clutter.  CO-2 BTL-3								
MODULE 3:					(6)			
Atmospheric propa	agation, Surveillance	e and Tracking Radar	, Radar Designs.		CO-2 BTL-			
MODULE 4:					(7)			

Radar elements switch & Radar	Design, Radar Transmitter design, Radar antenna design, Duplexer/TR Receiver.	CO-3 BTL-3				
MODULE 5:		(7)				
micro-doppler p	and networks, Radar signal processing chain, Pulse compression and processing, Tracking algorithms	CO-3 BTL-3				
MODULE 6:		(8)				
•	adar, Data processing for phased array radar, Airborne radar, imaging caperture radar, inverse synthic aperture radar, adaptive array	CO-4 BTL-3				
REFERENCE BOOKS						
1.	"Introduction to Radar Systems", by M.I. Skolnik. Publisher: Tata Mcgraw hill edition, 2001.					
2.	"Radar Systems Analysis and Design using MATLAB", by B.R.Mahafza. Press, 2013.	Publisher CRC				
3.	"Monopulse Principles and Techniques", by S.M.sherman and D.K.Bart Artech house, 2011	on. Publisher :				
4.	"Fundamentals of Radar Signal Processing", by M.A.Richards. Publishe hill.	r Tata Mcgraw				
5. "Ground Penetrating Radar: Theory and Applications",by, Editor: H.M. Jolt. Publisher: Elsevier.						
6.	"Radar, Sonar And Navigation Engineering", by K. K Sharma. Publisher: S K Kataria& Sons.					
7.	Literature / books suggested by respective course Lecturers.					

COURSE TITLE		Digital	& satellite C	ommunication a	and			CREDITS	3	
COOKSE TITLE		Navigation from Space					CHEBITO			
COURSE CODE DTD3704 COURSE CATEGORY DE L-T-P-S						4-0-0-0				
Version		1.0		Approval Details		23 06.02.202	ACM,	LEARNING LEVEL	BTL-3	
ASSESSMENT S	CHEN	ΛE								
First Periodical Assessment		Second Assessm	Periodical nent	Seminar/ Assignments/ Project		Surprise Quiz	Test /	Attendance	ESE	
15%		15%		10%		5%		5%	50%	
Course Objecti	ve	analogu commu	ue and digi	of the course tal communica ystems, modula es.	tion	systems	, opti	cal communic	ation, s	atellite
Course Outcon	ne	1. 2. 3. 4.	Understand Evaluate the Design the a Understand	this course, the the communicat performance of nalogue and dig and analyse the the different type	tion t f com ital cosigna	echnique imunicat ommunical al transm	es ion syst cation s ission e	ems ystems effects		
CO, PO Mappir	ng									
СО	PO-	1	PO-2	PO-3	PO-4	F	PO-5	PO-6	PO-	7
CO-1	3		2	-  -	•	-		-	-	
CO-2	3		3		3	3		2	3	
CO-3	3		2	3 2	2	2	=	2	2	
CO-4	3		2	- 2	2	2	<u> </u>	1	-	
CO-5	3		2	<u> -  -</u>	•	-		-		
MODULE 1:										(6)
Elements of	a cor	mmunica	tions system	and their relation	onshi	ip to syst	em per	formance.	CO-1 BTL-3	
MODULE 2:									•	(7)
Free space	opti	ical com	munication,	Fiber optics	comr	nunicatio	on, Wi	reless/cellular	CO-2	
Free space optical communication, Fiber optics communication, Wireless/cellular communications.							BTL-3			
MODULE 3:										(7)
Fundamental concepts such as current/voltage relationships, time and frequency domains, power spectral density, random signals, Communications system components and functions, analog and digital communications systems,						CO-2 BTL-				
								(7)		
	se, t	transmiss	sion lines,	ion; baseband a waveguides and					CO-3 BTL-3	

MODULE 5:		(7)
and RF system	ffects on signal transmission; end-to-end path calculations for wire/coax, as including terrestrial ground links and satellite communications, Spread ecpt of frequency hoping.	CO-3 BTL-3
MODULE 6:		(6)
Navigation te Galileo	chniques from space regarding functioning of GPS, GLONASS, IRNSS &	CO-4 BTL-3
REFERENCE BOO	KS	I
1.	"Satellite communication", by T. Pratt, C. W. Bostian, J. E.Allnut. Publish and sons	er: John Willey
2.	"Satellite Communications Systems: systems, techniques and techn Maral, M. Bousquet, Z. Sun. Publisher:John Willy and sons	nology", by G.
3.	"Digital Communications: Fundamentals and Applications", B. Sklar . Pres	ntice-Hall, Inc.
4.	"Understanding of GPS/GNSS: Principles and Applications", by E. Kaplan a Publisher: Artech House Publishers.	and C. Hegarty.
5.	Literature / books suggested by respective course Lecturers.	

COURSE TITLE		Tactical battlefield Communication & Electronic Warfare					CREDITS	3	
COURSE CODE	<u> </u>	DTD370		COURSE CATEGORY DE		L-T-P-S	4-0-0-0		
Version 1.0			Approval Details	23	ACM, 2.2021	LEARNING LEVEL	BTL-3		
ASSESSMENT	SCHEN	ΛE							
First Perio Assessment	dical	Second Assessn	Periodical nent	Seminar/ Assignments/ Project	Sur <sub> </sub> Qui	orise Test /	Attendance	ESE	
15%		15%		10%	5%		5%	50%	
Course Object	tive	techniq against links, co and jan	ues for sett ground to ell phone lin nming perfor		pt and jar communi n control	nming links cation signa links, techni	for Electronicals, UAV comi	c Warfare mand and	(EW) data
2. Ca 3. Ca Course Outcome 4. Ca ta lin			Understand	the nature of ta	actical bat	tlefield com			
Course Outco	me	3. 4.	Calculate the Calculate the tactical come links.	mmunication ling requirements are requirement im. Signals included tools to perforr	for intercons s for emi	eption of tac tter location apon contro	n, intercept a ol link, UAV li	nd jammii	_
CO, PO Mappi		3. 4.	Calculate the Calculate the tactical come links.	e requirements e requirement im. Signals incl	for intercons s for emi	eption of tac tter location apon contro	n, intercept a ol link, UAV li	nd jammii	_
		3. 4. 5.	Calculate the Calculate the tactical come links.	e requirements e requirement im. Signals incl	for intercons s for emi	eption of tac tter location apon contro	n, intercept a ol link, UAV li	nd jammii	_
CO, PO Mappi CO	ing	3. 4. 5.	Calculate the Calculate the tactical com links. Use various	e requirements e requirement im. Signals incl tools to perforr	for interco s for emi luding wea	eption of tac tter location apon contro ic warfare c	n, intercept a ol link, UAV li alculations	nd jammii nks, Cell p	_
CO, PO Mappi	ing PO-:	3. 4. 5.	Calculate the Calculate the tactical comlinks. Use various	e requirements e requirement im. Signals incl tools to perforr	for interco s for emi luding wea	eption of tac tter location apon contro ic warfare c	n, intercept a bl link, UAV line alculations	nd jammii nks, Cell p	_
CO, PO Mappi CO CO-1	PO-:	3. 4. 5.	Calculate the Calculate the tactical comlinks. Use various  PO-2 2	e requirements e requirement im. Signals incl tools to perforr  PO-3 -	for interces for emiluding western electron	eption of tac tter location apon control ic warfare c	n, intercept a bl link, UAV line alculations  PO-6 -	nd jammii nks, Cell p PO-7	_
CO, PO Mappi CO CO-1 CO-2	ing PO-:	3. 4. 5.	Calculate the Calculate the tactical comlinks. Use various PO-2 2 3	e requirements e requirement im. Signals incl tools to perforr  PO-3	for interces for emiluding western electron  PO-4 -	eption of tac tter location apon control ic warfare c	n, intercept a bl link, UAV line alculations  PO-6 - 2	nd jammii nks, Cell p PO-7	_
CO, PO Mappi CO CO-1 CO-2 CO-3	ing PO-:	3. 4. 5.	Calculate the Calculate the tactical comlinks. Use various  PO-2 2 3 3	e requirements e requirement im. Signals incl tools to perforr  PO-3 3	for interces for emiluding western electron  PO-4 - 2	eption of tac tter location apon contro ic warfare c  PO-5 - 2 2	n, intercept a link, UAV link alculations  PO-6 - 2 2	PO-7 - 3 1	_
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4	ing PO-:	3. 4. 5.	Calculate the Calculate the Calculate the tactical combines. Use various PO-2 2 3 3 2	e requirements e requirement im. Signals incl tools to perforr  PO-3 3 2	for interces for emiluding western electron  PO-4  - 2 2 2	eption of tacter location apon control ic warfare control   PO-5 - 2 2 2	PO-6 - 2 2 2	PO-7 - 3 1	_
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1:	PO-3 3 3 3 3 3 3	3. 4. 5.	Calculate the Calculate the Calculate the tactical comlinks. Use various  PO-2 2 3 3 2 2	e requirements e requirement im. Signals incl tools to perforr  PO-3 3 2	for interces for emiluding western electron  PO-4 - 2 2 2 2	eption of tacter location apon control ic warfare c	PO-6 - 2 2 2 2	PO-7 - 3 1	hone
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1:	PO-3 3 3 3 3 3	3. 4. 5.	Calculate the Calculate the Calculate the tactical comlinks. Use various  PO-2 2 3 3 2 2	e requirements e requirement im. Signals incl tools to perforr  PO-3 3 2 2	for interces for emiluding western electron  PO-4 - 2 2 2 2	eption of tacter location apon control ic warfare c	PO-6 - 2 2 2 2	PO-7 - 3 1 1 1 CO-1	hone
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1: Radiometry	PO-3 3 3 3 3 and poeration	3. 4. 5.	Calculate the Calculate the Calculate the Calculate the tactical complex of the Calculation of the Calculati	e requirements e requirement im. Signals incl tools to perforr  PO-3 3 2 2	ror interces for emital luding western electrons  PO-4 - 2 2 2 - 2	PO-5 - 2 2 2 2 spheric effect	PO-6 - 2 2 2 2 2	PO-7 - 3 1 1 1 CO-1	hone (6)
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1: Radiometry	PO-: 3 3 3 3 3 and poeration	3. 4. 5.	Calculate the Calculate the Calculate the Calculate the tactical complex of the Calculation of the Calculati	PO-3 3 2 2 mature generat	ror interces for emital luding western electrons  PO-4 - 2 2 2 - 2	PO-5 - 2 2 2 2 spheric effect	PO-6 - 2 2 2 2 2	PO-7 - 3 1 1 1 CO-1 BTL-3	hone (6)
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1: Radiometry MODULE 2: Radar ES opstrategies, j. MODULE 3: Introduction characterist	PO-3 3 3 3 3 and poeration	3. 4. 5.  oower ca onal use, ing of SA oradar f electro	Calculate the Calculate the Calculate the Calculate the tactical complex of the Calculation of the Calculati	PO-3 3 2 2 2 cnature generate etection battle, interception Signal process	ror interces for emiliarity was for emiliarity was melectron melec	PO-5 - 2 2 2 2 spheric effector, jamming	PO-6 - 2 2 2 2 2 techniques &	PO-7 - 3 1 1 1 CO-1 BTL-3	(6)

Decision theory systems, error p	CO-3 BTL-3				
MODULE 5:			(7)		
•	k Issues, cell phone issues, Intercept links, Frequency hopping and other ial techniques for jamming LPI signals	CO-3 BTL-3			
MODULE 6:			(7)		
Introduction to	electronic counter measures and counter-counter measures.	CO-4 BTL-3			
1.	"Tactical Battlefield Communications Electronic Warfare", by David Adan	ny 2008			
2. "Military Communications in the Future Battlefield", by Marko Suojanen.					
3.	"Electronic Warfare for the Digitized Battlefield", by Michael Frater, Mich	nael Ryan.	•		
4.	Literature / books suggested by respective course Lecturers.				

COURSE	TITLE	CREDITS	2					
COURSE	CODE	DTD3791	COURSE CATEGORY	PC	L-T-P-S	0-0-2-0		
Versi	ion	1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3		
LIST OF EX	PERIMEN	rs						
2.	2. Lab experiments will be added in consultation with DRDO labs considering the available facilities.  CO-BTL-							

COURSE TITLE		DIGITAL & SATELLITE COMMUNICATION AND  CREDITS  NAVIGATION FROM SPACE LAB							
COURSE CODE	DTD3792	COURSE CATEGORY	PC	L-T-P-S	0-0-2-0				
Version	1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3				
LIST OF EXPERIME	NTS								
	b experiments will be a vailable facilities.	added in consultation v	with DRDO labs co	onsidering the	CO- BTL-				

## **SEMESTER II - ELECTIVE - 3 COURSES**

COURSE TIT	LE	Robotic	cs (MSS, MC	C)			CREDITS	3	
COURSE COI	DE	DTA-37	'30	COURSE CATEGO	DRY	DE	L-T-P-S	3-0-0-0	
Version			1.0	Approval Detai	ls	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT SCHEME									
First Periodical Second Periodical Assign Assessment Assessment Pro					/	Surprise Test / Quiz	Attendance	ESE	
15%			15%	10%		5%	5%	50%	
Course Objecti	ive	exposin coordin	ng students to nate transfor	nded to provide o a broad range mation and kin s, robot application	of top emat	pics with empha ics, trajectory	nsis on basics o olanning, cont	f manipulators,	
Course Outcor	me	<ol> <li>Use</li> <li>Call rob</li> <li>Call</li> <li>To</li> </ol>	e matrix alge culate the foots. culate the Ja	f this course, the bra and Lie algel orward kinemat cobian for serial planning for a ro e tools for analys	bra fo tics ar and p botic	or computing the nd inverse kine coarallel robot. system.	e kinematics of ematics of seri		
CO, PO Mappi	ng		1					-	
СО	PO-	1	PO-2	PO-3	PO-4	PO-5	PO-6	PO-7	
CO-1	3		2		-	-	-	-	
CO-2	3		3	2 2	2	2	2	2	
CO-3	3		2		• 		-	-	
CO-4	3		2		2	2	2	1	
CO-5	3		3	3   3	3	3	2	2 (7)	
MODULE 1:			1 1			<u> </u>		(7)	
				ystems covering			ion,	CO-1	
MODULE 2:	n, gra	asping, se	ensory perce	ption, and teleo	perat	1011.		BTL-3 (5)	
Kinematics,	Kinematics, dynamics, manipulability, motion/force control, real-time programming, co-2 controller architecture, motion planning, navigation, and sensor integration, Control BTL-3							CO-2	
MODULE 3:								(4)	
Transformat	ion o	f coordir	nates, Kinem	atics and inverse	e kine	matics, Jacobia	ns.	CO-2 BTL-	

MODULE 4:		(7)
Modelling Cont Derivative (PID)	CO-3 BTL-3	
MODULE 5:		(7)
Feedback Contr	rol System, Motion and path planning, Collision avoidance and navigation	CO-3 BTL-3
MODULE 6:		(6)
Fundamental of	f AI, Programming methods for robotics, Human-Robot interaction.	CO-4 BTL-3
REFERENCE BOOK	S	
1.	Text Book: Introduction to Robotics by S.K. Saha (Tata McGraw-Hill, New 2008, 1st Reprint 2009)	Delhi, India
2.	"Introduction to Robitcs: Mechanics and Control", by Craig, J.J. Publisher Delhi.	: Pear-son,
3.	"Fundamentals of Robotics: Analysis and Control", by Schilling Robert J. F Prentice- Hall, 1990.	Pub-lisher :
4.	"An Introduction to Robotics Analysis, Systems, Applications", by Niku Sa Publisher: Prentice-Hall, 2001.	eed B.
5.	Stuart Russell and Peter Norvig, Publisher: Prentice Hall	
6.	Literature / books suggested by respective course Lecturers.	

COURSE TIT	LE	EMI/EN	ИС in Militar	y Systems		CREDITS	3
COURSE CO	DE	DTA-37	<b>'31</b>	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
Version			1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEN	ΛE					
			l Periodical essment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE
15%			15%	10%	5%	5%	50%
	techniques for prevention of electronic equipment through good ENtechniques – grounding, shielding, cable management, and power into troubleshooting techniques, EMI/EMC standards.  Upon completion of this course, the students will be able to  1. Understand the concept of EMI / EMC protection of equipment  2. Identify and prevent the common EMI/EMC problems in military  3. Understand the Design impact (by requirement) of military EMC  4. Understand EMI/EMC troubleshooting tips and techniques.					terface design,	
CO, PO Mappi				ate EMI/EMC require			
СО	PO-	1	PO-2	PO-3 PO-4	PO-5	PO-6	PO-7
CO-1	3		2			-	-
CO-2 CO-3	3		2		2	2	2
CO-4	3		2	1- 1-	2	2	3
CO-5	3		3	2 -	2	3	3
MODULE 1:					<u> </u>	1 -	(6)
Basic Conce	uplin		-	C and EMP, Classifica mena and effects, Tr	· · · · · · · · · · · · · · · · · · ·		CO-1 BTL-3
MODULE 2:							(6)
•			•	ems, Non-ideal Beha II measurements, EM	•		CO-2 BTL-3
MODULE 3:							(6)
EMI Control Methods: Conducted and radiated emissions and susceptibility, Crosstalk and shielding, Grounding, Bonding, Filtering, EMI gasket, Isolation transformer, opto isolator; Faraday cage, isolation of shelters					CO-2 BTL-		
MODULE 4:							(5)
		_	tions: Nation ectrum conv	nal and Intentional soversation;	tandardizing orga	anizations,	CO-3 BTL-3

MODULE 5:		(7)				
selection and m	EMC Design and Interconnection Techniques: Cable routing and connection, Component selection and mounting, PCB design (Trace routing, Impedance control, decoupling, Zoning and grounding);					
MODULE 6:		(6)				
,	EMC analysis and detection techniques: Using tools for signal integrity analysis, Study eye diagrams for communication systems.					
REFERENCE BOOKS	S					
1.	"EMI/EMC Computational Modeling Handbook", by brucearchambeault, Ramahi, et al.	Omar M.				
"EMI/EMC Computational Modeling Handbook: 630 (The Springer International Series in Engineering and Computer Science)", by Bruce R. Archambeault, Omar M. Ramahi, et al.						
3.	"A practical approach to electromagnetic compatibility", by Chetan Katha	alay				
4.	Literature / books suggested by respective course Lecturers.					

COURSE TIT	LE D	Defence	e Electro-Op	tics and Imaging	Systems		CREDITS	3
COURSE CO	DE D	DTA-37	32	COURSE CATEGOR	RY	DE	L-T-P-S	3-0-0-0
Version			1.0	Approval Details		ACM, 02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT S	SCHEME							
	First Periodical Assessment Second Periodical Assessment Seminar/ Assignments/ Project Surprise Test / Quiz Attendance					Attendance	ESE	
15%		:	15%	10%		5%	5%	50%
Course Object	ive St	urrent	and future s to light o	rse is to provide a electro-optic ar n application of	nd imagin	g devices	. Course will	also to enable
Course Outcor		1. ! 2. /	Understand systems. Apply their k lems.	this course, the state of the s	d principle tical electr	s underpii o-optic de	nning electro-o	
CO, PO Mappi	ng							
со	PO-1		PO-2	PO-3 PO	<b>D-4</b>	PO-5	PO-6	PO-7
CO-1	3		2			-	-	-
CO-2	3		3	2 1		2	2	2
CO-3	3		2	2 -		-	-	-
MODULE 1: Principles of	radiom	netry, T	he human e	ye, Visible band o	optical sigl	nting syste	ems.	(6) CO-1 BTL-3
MODULE 2:								(6)
Camera syst	ems, Im	nage in	tensifiers, N	lissile seekers.				CO-2 BTL-3
MODULE 3:								(6)
Electro-optio	c count	ermeas	sures.					CO-2 BTL-
MODULE 4:								(7)
Thermal imagers, II cameras, Hyper-spectral imaging, Digital image processing.  CO-3 BTL-3							CO-3	
								BTL-3
MODULE 5:								BTL-3 (5)

MODULE 6:		(6)			
Electro-optic protection measures.  CO-4 BTL-3					
REFERENCE BOOKS	5				
1.	"Systems engineering analysis of electro-optical and Infra red system", b Wolfgang Arrasmith.	y William			
2.	"Introduction to Infrared and Electro-Optical Systems", by Author Ronald Ronald G. Driggers.	d G. Driggers			
3.	"Handbook of Defence Electronics and Optronics: Fundamentals, Techno Systems", by Author(s): Anil K. Maini	logies and			
4.	"Building Electro-Optical Systems: Making It all Work", by Author Philip C	C. D. Hobbs.			
5.	"Electro-Optical Instrumentation: Sensing and Measuring with Lasers", b Silvano Donati.	y Author			
6.	"Electro-optical systems design, Analysis and testing", by Author Michael	C. Dudzik.			
7.	Literature / books suggested by respective course Lecturers.				

COURSE TIT	LE	Structu	ral Dynamic	s and Aero-Elastici	ty		CREDITS	3	
COURSE CO	DE	DTA-37	'33	COURSE CATEGORY		DE	L-T-P-S	3-0-0-0	١
Version			1.0	Approval Details 23 ACM, 06.02.2021		LEARNING LEVEL	BTL-3		
ASSESSMENT	ASSESSMENT SCHEME								
First Periodical Assessment			l Periodical essment	Seminar/ Assignments/ Project	Surp	rise Test / Quiz	Attendance	ESE	
15%			15%	10%		5%	5%	50%	
Course Object	ive	comput various	ational anal	ended to provide ysis, Different met a related to vibrati acture.	nods of	analysis, I	Mathematical r	nodeling of	the
Course Outcome		1. 2.	Understand Understand	f this course, the st vibrations and fluid of different design a m dynamic analysis	dynami spects	ics behind to l	the aerospace s oading in aeros	•	١.
CO, PO Mappi	ing								
СО	PO-	1	PO-2	PO-3 PO-	4	PO-5	PO-6	PO-7	
CO-1	3		2			-	-	-	
CO-2	3		2			-	-	-	
CO-3	3		2	2 2		2	2	2	4-1
MODULE 1:								T	(6)
Principles a	nd me	ethods of	computation	nal structural dyna	mics an	d vibratio	n analysis.	CO-1 BTL-3	
MODULE 2:								BIL-3	(6)
		unamia a	nalucia usias	the finite element	mothe	d Calaulat	ion of model	CO-2	(6)
parameters		yriaiiic a	illalysis usili	g the finite element	memo	u, Calculat	ion or modal	BTL-3	
MODULE 3:									(6)
System dyn	amic	•		uperposition, frequ chniques, Fatigue a	•	sponse, m	odel	CO-2 BTL-	-
MODULE 4:		. actarar	5,110110313 100	ques, rangue u	, 515.				(7)
	n to a		•	vnamic Loading, Be	nding N	loment, Se	ectional	CO-3	(7)
properties (	,, ACI	51511, V 1	. Diagraili,					BTL-3	
MODULE 5:									(5)
Basic theory	of lii	near elas	tic fracture r	nechanics; strain e	nergy re	elease rate	;	CO-3	
•	Basic theory of linear elastic fracture mechanics; strain energy release rate;  BTL-3								

MODULE 6:		(6)		
Applications to tolerance issue	delamination crack growth in polymer composite laminates, Damage s in composites	CO-4 BTL-3		
REFERENCE BOOK	S			
1.	"Elements of vibration analysis", by Leonard Meirovitch. Publisher : McG Inc.,US; 2nd edition (1 March 1986)	raw-Hill		
2.	"Finite Element Analysis Theory And Application With ANSYS", by Moaveni Publisher: Pearson Education; 3rd edition (1 January 2011)			
3.	"Mechanical Vibrations   SI Edition   Sixth Edition", by Singiresu S. Rao. F Pearson	Publisher:		
4.	"Elements of Fracture Mechanics", by Prashant Kumar. Publisher: McGra Education.	aw Hill		
5.	"Introduction to Structural Dynamics and Aeroelasticity", by Dewey H. Ho Alvin Pierce. Publisher: Cambridge University Press.	odges and G.		
6.	Literature / books suggested by respective course Lecturers.			

COURSE TIT	ΓLE	Safety,	Health & Ha	azard Manageme	ent		CREDITS	3
COURSE CO	DE	DTA-37	34	COURSE CATEGO	RY	DE	L-T-P-S	3-0-0-0
Version			1.0	Approval Details	s	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEN	ΛE						
First Period Assessme			l Periodical essment	Seminar/ Assignments/ Project		Surprise Test / Quiz	Attendance	ESE
15%			15%	10%		5%	5%	50%
Course Objective safety		safety h	nealth and h	s of the course azard managemenagement of the	ent.	The course will <sub>l</sub>	orovide unders	tanding on the
Course Outcome 2		1. 2.	Understand Handle toxic	f this course, the chemical safety st liquids & gases, e the NBC warfare s	tand explo	ards, fire safety, osives.	hazard manage	
CO, PO Mapp	ing	l						
СО	PO-	1	PO-2	PO-3 P	0-4	PO-5	PO-6	PO-7
CO-1	3		2	-  -		-	1	2
CO-2	3		2			1	2	2
CO-3	3		2	-  -		1	2	2
Laboratorie Chemical ris	afety: s, Sto sk ana	rage of h	_	ations of chemica emicals, Compati nt		•		(6) CO-1 BTL-3
MODULE 2:								(4)
Fire triangle	and	Handling	of Toxic, Inc	dustrial Gases				CO-2 BTL-3
MODULE 3:								(7)
	_			ZAN techniques, F ardous materials;		rd in manufactu	re, Hazard	CO-2 BTL-
MODULE 4:								(7)
Warfare: Cla warfare safe		cations o	f explosives	based on hazards	s, Nu	clear, biological	and chemical	CO-3 BTL-3
MODULE 5:								(6)
Health: Asse	essme	ent of hu	man factors,	Health & Enviror	nme	nt safety		CO-3 BTL-3
								DIL-3

MODULE 6:		(6)		
Nano materials	CO-4 BTL-3			
REFERENCE BOOKS	S			
1.	"Occupational Health and Safety Management A Practical Approach", by Reese. Publisher: CRC Press.	Charles D.		
2.	"Occupational and Environmental Safety and Health", Arezes, P.M., Baptista, J.S., Barroso, M.P., Carneiro, P., Cordeiro, P., Costa, N., Melo, R.B., Abreu dos Santos Baptista, J.M., Perestrelo, G. (Eds.). Publisher: Springers, 2019			
3.	"Handbook of Occupational Safety and Health", by S. Z. Mansdorf. Publis	her : Wiley.		
4.	"Institution of Chemical Engineers", by Trevor Kletz"Hazop and Hazan			
5.	"Handbook Of Toxicology Of Chemical Warfare Agents", by Ramesh C. Go Edition Elsevier, 2015	upta 2 <sup>nd</sup>		
6.	"Nanomaterials Safety Toxicity And Health Hazards", by Shyamasree Gho	osh De Gruyter.		
7.	"Hazardous Chemicals Handbook", by Phillip Carson, Clive Mumford Butt Heinemann.	terworth-		
8.	Literature / books suggested by respective course Lecturers.			

COURSE TIT	LE	FUND		F TELEMETRY, TELECTRANSPONDER	COMMAND &	CREDITS	3	
COLUBEE CO.	D.F.	DTA 27		LTDC	2000			
Version	DE	DTA-3735		Approval Details	23 ACM, 06.02.2021	L-T-P-S  LEARNING  LEVEL	3-0-0-0 BTL-3	
ASSESSMENT S	SCHEN	1E			1			
	First Periodical Assessment		l Periodical essment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE	
15%			15%	10%	5%	5%	50%	
Course Object	ive	the sate	ellite commu	s of the course will build build be inication, telemetry, nunication systems.	•	_		
Course Outcome		1. 2. 3.	Satellite com Overall cont data. Determination	f this course, the stude on munication and related rol of satellites throut on of the satellite's eand transmitting of r	ited technologies igh collection, pr exact location thr	s. ocessing, and t		n of
			•	rol of satellite throug tion of commands tr	the reception,		d	
CO, PO Mappi	ng		•	rol of satellite throug	the reception,		d	
CO, PO Mappi	ng PO-1		•	rol of satellite throug	the reception,		PO-7	
	PO-1		PO-2	rol of satellite throug tion of commands tr	th the reception, ansmitted from t	the ground.		
CO CO-1 CO-2	PO-1 3 3		PO-2 2	rol of satellite throughtion of commands tr	PO-5	PO-6	PO-7 - -	
CO CO-1 CO-2 CO-3	PO-1 3 3		PO-2 2 2	PO-3 PO-4 2	PO-5 - 2	PO-6 2	PO-7 2	
CO CO-1 CO-2 CO-3 CO-4	PO-1 3 3		PO-2 2	rol of satellite throughtion of commands tr	PO-5	PO-6	PO-7 - -	
CO CO-1 CO-2 CO-3 CO-4 MODULE 1:	PO-1 3 3 3 3	1	PO-2 2 2 2 2	PO-3 PO-4 2 - 2	PO-5 2	PO-6 2 2	PO-7 2 3	(6)
CO CO-1 CO-2 CO-3 CO-4 MODULE 1: Fundamenta	PO-1 3 3 3 3	1	PO-2 2 2 2 2	PO-3 PO-4 2	PO-5 2	PO-6 2 2	PO-7 2	(6)
CO CO-1 CO-2 CO-3 CO-4 MODULE 1:	PO-1 3 3 3 3	1	PO-2 2 2 2 2	PO-3 PO-4 2 - 2	PO-5 2	PO-6 2 2	PO-7 2 3	
CO CO-1 CO-2 CO-3 CO-4 MODULE 1: Fundamenta schemes. MODULE 2:	PO-1 3 3 3 3 3	atellite c	PO-2 2 2 2 2 communicati	PO-3 PO-4 2 - 2 on, different modula	PO-5 - 2 2 ation and multiple	PO-6 2 2 exing	PO-7 2 3  CO-1 BTL-3	(6)
CO CO-1 CO-2 CO-3 CO-4 MODULE 1: Fundamenta schemes. MODULE 2: Satellite Tele	PO-1 3 3 3 3 al of s	atellite c	PO-2 2 2 2 2 communicati	PO-3 PO-4 2 - 2	PO-5 - 2 2 ation and multiple Access Technique	PO-6 2 2 exing	PO-7 2 3 CO-1 BTL-3	
CO CO-1 CO-2 CO-3 CO-4 MODULE 1: Fundamenta schemes. MODULE 2: Satellite Tele Telemetry, [	PO-1 3 3 3 3 al of s	ry, Tracki	PO-2 2 2 2 communications and Telesion, Method	PO-3 PO-4 2 - 2 on, different modula	PO-5 - 2 2 ation and multiple Access Technique me Division and I	PO-6 2 2 exing	PO-7 2 3  CO-1 BTL-3	
CO CO-1 CO-2 CO-3 CO-4 MODULE 1: Fundamenta schemes. MODULE 2: Satellite Tele Telemetry, [	PO-1 3 3 3 3 al of s	ry, Tracki	PO-2 2 2 2 communications and Telesion, Method	PO-3 PO-4 2 - 2 on, different modular-command, Multiple ds of Modulation, Tire	PO-5 - 2 2 ation and multiple Access Technique me Division and I	PO-6 2 2 exing	PO-7 2 3  CO-1 BTL-3	
CO CO-1 CO-2 CO-3 CO-4 MODULE 1: Fundamenta schemes. MODULE 2: Satellite Tele Telemetry, E Division Mul MODULE 3:	PO-1 3 3 3 3 al of s emetro Data 1 ltiples	atellite cory, Tracki	PO-2 2 2 2 2 communications and Telesion, Method MA, TDMA, C	PO-3 PO-4 2 - 2 on, different modular-command, Multiple ds of Modulation, Tire	PO-5 - 2 2 ation and multiple Access Technique me Division and I	PO-6 2 2 exing	PO-7 2 3  CO-1 BTL-3	(6)
CO CO-1 CO-2 CO-3 CO-4 MODULE 1: Fundamenta schemes. MODULE 2: Satellite Tele Telemetry, E Division Mul MODULE 3:	PO-1 3 3 3 3 al of s emetro Data 1 ltiples	atellite cory, Tracki	PO-2 2 2 2 2 communications and Telesion, Method MA, TDMA, C	PO-3 PO-4 2 - 2 on, different modular-command, Multiple ds of Modulation, Tig	PO-5 - 2 2 ation and multiple Access Technique me Division and I	PO-6 2 2 exing	PO-7 2 3  CO-1 BTL-3  CO-2 BTL-3	(6)
CO CO-1 CO-2 CO-3 CO-4 MODULE 1: Fundamenta schemes. MODULE 2: Satellite Telemetry, Edivision Multiple Module 3: Satellite Pace	PO-1 3 3 3 3 al of s emetro Data 1 ltiples	ry, Tracki Fransmiss king, FDN	PO-2 2 2 2 2 2 communications, Methodow, TDMA, Communications, Trace	PO-3 PO-4 2 - 2 on, different modular-command, Multiple ds of Modulation, Tig	PO-5 - 2 2 ation and multiple Access Technique me Division and I ding Schemes.	PO-6 2 2 exing	PO-7 2 3  CO-1 BTL-3  CO-2 BTL-3	(6) (6)

MODULE 5:		(6)				
Signal Processing: Processing of Signal, Data Acquisition and Reduction.						
MODULE 6:		(6)				
Introduction to	CO-4 BTL-3					
REFERENCE BOOKS	S					
1.	"Spacecraft TT&C and Information Transmission Theory and Technologies", by, Jiaxing Liu.Publisher: Springer, 2014					
2.	"Introduction to PCM Telemetering Systems", by Stephen Horan. Publish	er: CRC Press				
3.	"Satellite Communications Systems: Systems, Techniques and Technology", by Gerard Maral, Michel Bousquet, Zhili Sun. Publisher: Wiley, 2020					
4.	"Satellite Communications", by Timothy Pratt, Jeremy E. Allnutt, 3rd Edit Wiley.	ion Publisher :				
5.	"Principles of Modern Communication Systems", by Samuel O. Agbo , Ma Sadiku 2017	atthew N. O.				
6.	Literature / books suggested by respective course Lecturers.					

	ITLE	J	AMMING AN	ID ECM/ECCM TECH	NOLOGIES	CREDITS	3
COURSE C	ODE		DTA-3736	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
Version	n		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEME						
First Periodical Assessment			nd Periodical sessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE
15%			15%	10%	5%	5%	50%
Course Object	tive	mat	ching, contin	ended to provide lea uous interference, f typesofjammingsyst	actors affecting E	ECM, basic prin	ciple of noise
Course Outco		2.Und electr	lerstand the pronic jamming erstand the dif	oncept of electronic rinciples and the pra g technology ferent types of electro	ictical applicatior		
CO, PO Ma <sub>l</sub>	pping						
CO		1					
	PO-1		PO-2	PO-3 PO-4	PO-5	PO-6	PO-7
CO-1	3		2		PO-5	-	-
CO-1 CO-2	3		2	PO-3 PO-4	PO-5 - -	-	-
CO-1 CO-2 CO-3	3 3 3		2		PO-5 - -	-	
CO-1 CO-2 CO-3 MODULE 1:	3 3 3 :		2 2 2 ck(EA),Jammii		- - - nmingTypesBurn-	-	-
CO-1 CO-2 CO-3 MODULE 1:	3 3 3 : : : : : : : :		2 2 2 ck(EA),Jammii		- - - nmingTypesBurn-	-	- - - (7)
CO-1 CO-2 CO-3 MODULE 1: Principals or Through, Co MODULE 2: Repeater Ja	3 3 3 fElectro	nming,	2 2 2 ck(EA),Jammii Range Decept		- - - nmingTypesBurn- GainJamming.		(7) CO-1 BTL-2
CO-1 CO-2 CO-3 MODULE 1: Principals or Through, Co MODULE 2: Repeater Ja	3 3 3 FElectro overJar mmingling vs. N	nming,	2 2 ck(EA),Jammii Range Decept		- - - nmingTypesBurn- GainJamming.		- (7) CO-1 BTL-2 (6)
CO-1 CO-2 CO-3 MODULE 1: Principals of Through, Co MODULE 2: RepeaterJa lobe Jamm MODULE 3:	3 3 3 if Electro over Jar mming I ing vs. N	equation Main lob	z z ck(EA),Jammin Range Decept ns, Noise Jamm be Jamming.		- - - nmingTypes Burn- GainJamming. Deatervs. Transpor	- - - - nder, Side	- (7) CO-1 BTL-2 (6) CO-1 BTL-2

Infrared Count	ermeasures (IRCM), Off-Board ECM Systems, Communications	CO-2	
Countermeasu	res (COM-ECM), Electro-Optic Counter Measure (EOCM) Systems.	BTL-3	
MODULE 5:		(6)	
	al Jamming System, Shipboard Self-Defense System, EA/Susceptibility against ns. Search Radar Counter-Countermeasures, Tracking Radar.	CO-1,2 BTL-3	
MODULE 6:		(6)	
Counter-Countermeasures, Infrared Counter-Countermeasures, Communications Counter-Countermeasures.			
REFERENCE BOO	KS	1	
1.	"Electronic Countermeasure and Electronic Counter-Countermeasure", by Zohuri.	yBahman	
2.	"Fundamentals of Electronic Warfare 2001", by S.A. Vakin , L.N. Shustov, R.H. I	Dunwell.	
3.	"Fundamentals of Electronic Warfare 2001", by S.A. Vakin , L.N. Shustov, R.H. I	Dunwell.	
4.	"Electronic Warfare & Radar Systems Engineering Handbook" 2013, Naval Center Weapons Division.	AirWarfare	
5.	"EW 101: A First Course in Electronic Warfare (Artech House Radar Library)	,1st Edition	

COURSE TI	TLE	SOFTV	WARE DEFINE	D RADIOS		CREDITS	3
COURSE CO	DDE	D	TA-3737	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
Version	l		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEME						
First Periodical So Assessment			nd Periodical sessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE
15%			15%	10%	5%	5%	50%
Course Outcom		Upon 1.Und 2.Und 3.Gair	The course is intended to provide understanding of the fundamental of softwardios, different aspects of SDRs, practical scenarios along with knowledge SDR hardware and software.  Upon completion of this course, the students will be able to  1. Understand the concept, application of SDRs.  2. Understand of analog RF components as front end block in implementary.  3. Gain knowledge of digital hardware architectures and its development to the students are supplied to the students.				
CO, PO Map	ping	4.Gaii	rkilowiedged	of software developr	nentroi embedde	eu wireless syst	eilis.
СО	PO-1		PO-2	PO-3 PO-4	PO-5	PO-6	PO-7
CO-1	3		2		-	-	-
CO-2	3		2		-	-	-
CO-3	3		2		-	-	-
CO-4	3		2	-  -			-
MODULE 1:							(6)
		-		chitecture, SDR enab	ers,advantage/		CO-1
disadvanta	ges, Ap	plicatio	ns.				BTL-2
MODULE 2:							(6)
and non-lir toaveragep	ear ba	ndwidtl	n efficient mo	ckseparation, digital rodulations. Bandwid eanderrorprobabili	th and power eff		CO-1 BTL-2
MODULE 3:							(6)
			•	cture, homodyne arch ssing architecture fo	-	ges&	CO-2 BTL-3
MODULE 4:							(6)
code divisio	n techn	iques as	well as carrier	n, multiple access tecl sensing, Wireless ser eranaloguesignal pr	sor networks and	beam	CO-2 BTL-3

processing					
MODULE 5:		(7)			
	nel coding (Source and channel coding, sampling, entropy, data ce coding, block and convolution coding, turbo coding, space-time coding and	CO-1,2 BTL-3			
MODULE 6:		(5)			
Case studies in sc	oftware radio design, Introduction and a Historical perspective	CO-3 BTL-3			
REFERENCE BOOKS					
1.	"Software Radio, (A modern approach to radio engineering)", by Jeffery H.Red PHI PTR.	ed Publisher :			
2.	"RF and Digital Signal Processing for Software Defined Radio", by John J. Rouphael.  2. Publisher: Elesiver.				
3.	"Digital Techniques in Frequency Synthesis", by B.G.Golderg. Publisher: McGra	ıw-Hill.			
4.	"Multirate Signal Processing", by N.J.Fliege. Publisher: John Wiley and sons				

COURSE TI	TLE		NCED LIGHT TO	WEIGHT AND COMP	OSITE	CREDITS	3
COURSE CO	DDE	[	DTA-3738	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
Version	l		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEME						
First Periodical Assessment			nd Periodical ssessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE
15%			15%	10%	5%	5%	50%
Course Object	ive	mat of st und	thematical mo tructures used erstaticanddy	erials, their manuscrials, their manuscrials design structure in airborne systems lynamicloading, include this course, the stu	ures made of cor ike missiles and a dingcrashandbir	mposites. Basic of the sircrafts & their dstrike will also	understanding performance
Course Outco	me	mater 2. Und comp	ials. derstand the r ositeand met	esign of advanced struc numerical and analytic allic components. to solve real enginee	calskillsin struct		·
CO, PO Map	ping						
СО							
	PO-1		PO-2	PO-3 PO-4	PO-5	PO-6	PO-7
CO-1	3		2		-	-	-
CO-2	3		2	 2 2	- 2	2	2
CO-2 CO-3	3 3 3		2		-	-	- 2 2
CO-2 CO-3 MODULE 1:	3 3 3 rength		2 2 2	 2 2	2 2	- 2 2	2
CO-2 CO-3 MODULE 1:	3 3 3 rength		2 2 2	2 2 2 2 2	2 2	- 2 2	- 2 2 (6)
CO-2 CO-3 MODULE 1: Review of St Reinforced MODULE 2:	3 3 rength Compo	osite.	2 2 2 erials, Introduct	2 2 2 2 2	- 2 2 2 erials — Metal Allo	2 2 2 Dys and Fiber	- 2 2 (6) CO-1 BTL-2
CO-2 CO-3 MODULE 1: Review of St Reinforced MODULE 2: Introduction	3 3 rength Compo	osite.	2 2 2 erials, Introduct	2 2 2 2 2 2 ion to Aerospace Mate	- 2 2 2 erials — Metal Allo	2 2 2 Dys and Fiber	- 2 2 (6) CO-1 BTL-2 (7) CO-1
CO-2 CO-3 MODULE 1: Review of St Reinforced MODULE 2: Introduction Corrugated MODULE 3:	3 3 rength Compo	osite. erent typ	2 2 2 erials, Introduct	2 2 2 2 2 2 ion to Aerospace Mate	erials — Metal Allo	- 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	- 2 2 (6) CO-1 BTL-2 (7) CO-1 BTL-2
CO-2 CO-3 MODULE 1: Review of St Reinforced MODULE 2: Introduction Corrugated MODULE 3:	rength Compo	osite. erent typ	2 2 2 erials, Introduct	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	erials — Metal Allo	- 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	- 2 2 (6) CO-1 BTL-2 (7) CO-1 CO-2 (6)
CO-2 CO-3 MODULE 1: Review of St Reinforced MODULE 2: Introduction Corrugated MODULE 3:	3 3 rength Compo	erent typ	2 2 2 erials, Introduct pes of construct	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	erials — Metal Allo	- 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	- (6) CO-1 BTL-2 (7) CO-1 BTL-2 (6) CO-2 BTL-3

MODULE 5:		(5)		
Material Constit	cutive Relations.	CO-1,2 BTL-3		
MODULE 6:		(5)		
Failure Theories;	Fatigue theory.	CO-3 BTL-3		
REFERENCE BOOKS				
1.	"Composite Structures Safety Management", by Dr. Bjorn Backman. Publisher Science.	r: Elsevier		
2.	"Composite Structures: Design, Mechanics, Analysis, Manufacturing and Testing", by Manoj Kumar Buragohain. Publisher: CRC Press.			
3.	"Lightweight Composite Structures in Transport: Design, Manufacturin and Performance", by James Njuguna Woodhead Publishing, 2016.	ng, Analy-sis		
4.	"Structural and Stress Analysis", by T.H.G. Megson. Publisher: Butterworth-	Heinemann.		

COURSE TITL	.E	TEST METHO	DOLOGIES FOR DEW	SYSTEMS	CREDITS	3		
COURSE COD	ÞΕ	DTA-3739	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0		
Version		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3		
ASSESSMENT SC	HEME							
First Periodic Assessmen		Second Periodical Assessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE		
15%		15%	10%	5%	5%	50%		
Course Objective	e	characterization,	intended to provide system performan cools of laser and microv	ce testing proc	edures, test s	•		
Course Outcome		1. Understand the c 2. Carry out the ind	of this course, the stu characterization and to oors & outdoors syste safety issues, safety sta	esting requireme m performance	ents of DEW sys testing.			
CO, PO Mapp		T			1	T		
	PO-1	PO-2	PO-3 PO-4	PO-5	PO-6	PO-7		
	3	2			-	-		
	3 3	2 2		1	1	2		
MODULE 1:	<b>.</b>		-  -		-	2		
		La CDEMA ALAMA				2 (6)		
		Testing requirements of DEW system, types of testing, laser effect testing on target, system						
	outputtesting.							
A405:::==	g.	ison DE w system, typ	es of testing, laser effec	ttestingontarget	, system	(6) CO-1 BTL-2		
MODULE 2:						(6) CO-1 BTL-2 (7)		
			es of testing, laser effec			(6) CO-1 BTL-2		
						(6) CO-1 BTL-2 (7)		
System perfo	orman	ce testing, System (	outdoor test & measu	urement instrum		(6) CO-1 BTL-2 (7) CO-1 BTL-2		
System perfo	orman	ce testing, System (		urement instrum		(6) CO-1 BTL-2 (7) CO-1 BTL-2		
System perfo	orman	ce testing, System (	outdoor test & measu	urement instrum		(6) CO-1 BTL-2 (7) CO-1 BTL-2 (5) CO-2 BTL-3		
System performance  MODULE 3:  Laser testing  MODULE 4:	issue	ce testing, System o	outdoor test & measu er safety standards, la	rement instrum	ents.	(6) CO-1 BTL-2 (7) CO-1 BTL-2 (5)		
System performance  MODULE 3:  Laser testing  MODULE 4:	issue	ce testing, System o	outdoor test & measu	rement instrum	ents.	(6) CO-1 BTL-2 (7) CO-1 BTL-2 (5) CO-2 BTL-3 (5)		

Power Measurement, Noise Figure and Phase Noise measurement, Frequency measurements (Spectrum Analysis), Gain Compression and Intermodulation, Network Analysis.					
MODULE 6:		(6)			
Microwave subsys	Microwave subsystem/system characterization techniques. HPM safety tools, safety standards.				
REFERENCE BOOKS					
1.	"An Introduction to Microwave Measurements", by Ananjan Basu.				

COURSE T	ITLE	ADVANCED ANALYTICAL TECHNIQUES/LAB TESTING CREDIT					3	
COURSE CO	ODE	DT	ГА-3740	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0	
Version	n		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT	SCHEME							
First Perio		Assignments/		Surprise Test / Quiz	Attendance	ESE		
15%			15%	10%	5%	5%	50%	
Course Object	tive	chara The c	acterization b course provid	ve of the course is to by all the conventiona des understanding or c techniques, chroma	Iwellestablished the material ch	I techniques uso naracterization	ed worldwide.	
Course Outcome		Upon c	completion o	f this course, the stu	dents will be ab	le to		
		2.Apply		rent characterization analytical technique ner etc.	•	aterial organic,	/inorganic/	
CO, PO Maj	pping	2.Apply nanoma	appropriate aterial/polym	analytical technique ner etc.	foraparticular m			
CO, PO Map	pping PO-1	2.Apply nanoma	appropriate aterial/polym	analytical technique ner etc.  PO-3 PO-4	foraparticular m	PO-6	PO-7	
CO, PO Map CO CO-1	pping PO-1	2.Apply nanoma	r appropriate aterial/polym	PO-3 PO-4	foraparticular m	PO-6 -	PO-7 -	
CO, PO Mar CO CO-1 CO-2	PO-1 3 3	2.Apply nanoma	appropriate aterial/polym	analytical technique ner etc.  PO-3 PO-4	foraparticular m	PO-6	PO-7 - 2	
CO, PO Map co co-1 co-2 MODULE 1:	pping PO-1 3 3	2.Apply nanoma	r appropriate aterial/polym	PO-3 PO-4	foraparticular m	PO-6 -	PO-7 -	
CO, PO Map co co-1 co-2 MODULE 1:	PPING PO-1 3 3 :	2.Apply nanoma	r appropriate aterial/polym PO-2 2	PO-3 PO-4	foraparticular m	PO-6 -	PO-7 - 2 (4)	
CO, PO Mar CO CO-1 CO-2 MODULE 1: Instrumenta	pping PO-1 3 3: al Analys	2.Apply nanoma	r appropriate aterial/polym PO-2 2 2 tative analysis	PO-3 PO-4	foraparticular m	PO-6 -	PO-7 - 2 (4) CO-1 BTL-2	
CO, PO Mar CO CO-1 CO-2 MODULE 1: Instrumenta	pping PO-1 3 3 : al Analys	2.Apply nanoma	r appropriate aterial/polym PO-2 2 2 tative analysis	PO-3 PO-4	foraparticular m	PO-6 -	PO-7 - 2 (4) CO-1 BTL-2 (4) CO-1	
CO, PO Map CO CO-1 CO-2 MODULE 1: Instrumenta MODULE 2: Genesis of MODULE 3: Polymeric T	pping PO-1 3 3 : al Analys : instrum	2.Apply nanoma  I  Z  sis: Qualit  nental ar  ues: Rhee Gravimet	PO-2 2 tative analysis nalysis, hyph ology Technicry (TG), Differ	PO-3 PO-4	PO-5 - 1	PO-6 - 1	PO-7 - 2 (4) CO-1 BTL-2 (4) CO-1 BTL-2	
CO, PO Map co CO-1 CO-2 MODULE 1: Instrumenta  MODULE 2: Genesis of  MODULE 3: Polymeric T Techniques:	pping PO-1 3 3 : al Analys : instrum : Techniqu Thermo	2.Apply nanoma  I  Z  sis: Qualit  nental ar  ues: Rhee Gravimet	PO-2 2 tative analysis nalysis, hyph ology Technicry (TG), Differ	PO-3 PO-4	PO-5 - 1	PO-6 - 1	PO-7 - 2 (4) CO-1 BTL-2 (4) CO-1 BTL-2 (8)	
CO, PO Map CO CO-1 CO-2 MODULE 1: Instrumenta MODULE 2: Genesis of MODULE 3: Polymeric T Techniques: Scanning Ca MODULE 4: Chromatogra	pping PO-1 3 3 : al Analys : instrum : Techniqu Thermo alorimet : aphic Te	2.Apply nanoma  I  Z  Sis: Quality  mental are  ues: Rhee Gravimettry (DSC)  chniques	PO-2 2 2 tative analysis nalysis, hyph ology Technitry (TG), Differ	PO-3 PO-4	PO-5 - 1  ght determinations (DTA), and Different points (DTA)	PO-6 - 1	PO-7 - 2 (4) CO-1 BTL-2 (4) CO-1 BTL-2 (8) CO-2 BTL-3	

	Ultra Violet-Visible Spectroscopy UV-VIS, Infra-Red spectroscopy (IR), Nuclear nance (NMR), Mass spectroscopy, Atomic Absorption Spectroscopy (AAS).	CO-1,2 BTL-3
MODULE 6:		(4)
XRD and SEM	techniques, Sensitivity studies	CO-3 BTL-3
REFERENCE BOO	KS	
1.	"Fundamentals of molecular spectroscopy" by C. N. Banwell. Publisher : McG	raw Hills.
2.	"Introduction to Spectroscopy" by Donald L. Pavia, Gary M. Lampman, an Kriz. Publisher: Cengage Learning, 2014.	nd George S.
3.	"Chromatography: Concepts and Contrasts" by James M. Miller. Publisher: W	iley.
4.	"Chromatography: Principles and Instrumentation", by Mark F. Vitha. Publi	sher: Wiley.
5.	"Elements of X-Ray Diffraction" by B.D. Cullity Deceased, S.R. Stock. Publisher	: Pearson.
6.	"Electron Microscopy: Principles and Fundamentals" by S. Amelinckx, Dirk van Landuyt, Gustaaf van Tendeloo. Publisher: Wiley.	c van Dyck, J.
7.	"Polymer Characterization: Physical Techniques", by Dan Campbell, Richard A R. White 2nd Edition. Publisher CRC Press.	. Pethrick, Jim

COURSE TI	TLE		SONAR SYSTEM ENGINEERING CREDITS					
COURSE CO	DDE	DTA-374	11	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0	
Version	Version1.0Approval Details23 ACM, 06.02.2021LEARNING LEVEL						BTL-3	
ASSESSMENT	SCHEME							
First Period Assessme		Second Peri Assessmo		Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE	
15%		15%		10%	5%	5%	50%	
Course Object	ive	acoustic p	rinciple	ne course is to prov s, sonar technolog new to sonar syste	gy and application	•		
Course Outcome		1. Know the 2. Have an in 3. Know about 4. Know the page sonar.	basic bu -depth ut the au ohysics l	f this course, the stuilding blocks of a rakinowledge on diffe mbiguity function a behind sound propagage acquired in this	idar system. rent types of signand its significance gation in water a	als that are used in radar signal p nd principle of o	processing.	
CO, PO Map	ping							
СО	PO-1	PO-2		PO-3 PO-4	PO-5	PO-6	PO-7	
CO-1	3	2			-	-	-	
CO-2	3	2			-	-	-	
CO-3	3	2			-	-	-	
CO-4	3	2						
CO-5	3	3			-	-	-	
	al devel	•		n of fundamental pri systemscritical to na		n tothedesign	(6) CO-1 BTL-2	
MODULE 2:							(6)	
·	•	ex aperture tl	neory, a	rray theory.			CO-1 BTL-2	
MODULE 3:							(5)	
Signal proce	essing						CO-2 BTL-3	
MODULE 4:							(6)	
							. ,	

Introduction to u	ndersea warfare and engineering acoustics.	CO-2				
		BTL-3				
MODULE 5:		(7)				
	Principles of optimal signal processing techniques for detecting signals in noise, maximum likelihood, Bayes risk.					
MODULE 6:		(6)				
Neyman-Pearson (ROCcurves).	and min-max criteria and calculations of their associated error probabilities	CO-3 BTL-3				
REFERENCE BOOKS						
1.	"Fundamentals of Radar, Sonar and Navigation Engineering", by K. K. Sharr	ma.				
2.	"Principles of Modern Radar: Advanced techniques", by editor William L. N	∕lel-vin.				
3.	"Principles of Modern Radar: Advanced techniques", by editor William L. N	∕lel-vin.				
4.	"Sonar for practicing engineers", by A. D. Waite.					
5.	"Underwater Acoustics: Analysis, Designand Performance of Sonar", by Rich Hodges.	n-ardP.				

## **SEMESTER II - ELECTIVE - 4 COURSES**

COURSE TIT	LE	UNMANNED AERIAL VEHICLE DESIGN CREDITS						3			
COURSE COI	DE	DTA-3	3742	COURSE CATEGO	RY	DE	L-T-P-S	3-0-0-0			
Version		1.0	1.0 Approval Details 23 ACM, 06.02.2021		-	LEVEL BTL-3					
ASSESSMENT S	ASSESSMENT SCHEME										
First Periodi Assessmer		Second Pe Assessi		Assignments/		Surprise Test / Quiz	Attendance	ESE			
15%		15%	%	10%		5%	5%	50%			
Course Objecti		process fo	r rapidly g	led to provide th growing fixed – v ability analysis, a	ving U	AV technology,	integrated wit	h its			
Course Outcon	Upon	a. Under b. Perfo	on of this course, erstand the desig orm the aerodyna erstand the perfo erstand the airwo	n requi amic ar ormano	irements, designalysis, performetes testing of the	gn parameters on ance and stabile UAVs.	lity analysis.				
CO, PO Mappi	ng										
СО	PO-1	PC	O-2	PO-3 F	PO-4	PO-5	PO-6	PO-7			
CO-1	3	2				-	-	-			
CO-2	3	2		-  -		-	-	-			
CO-3	3	2		-  -		-	-	-			
CO-4	3	2		<u> -  -</u>				-			
MODULE 1:								(6)			
_	•				_		ion	CO-1			
module 2:	aircra	arts and UA	UAV design Requirements, design parameters, design algorithms, Certification CO-1 approaches: aircrafts and UAVs. Airworthiness of aircrafts and UAVs.								
				or triffic 33 or all cr	arts an	d UAVs.		BTL-3			
Air safety issues. Handling qualities. Maneuverability requirements. Aircraft design; UAV								BTL-3 (6)			
•				aneuverability r			design; UAV	(6) CO-2			
system desig				aneuverability r			design; UAV	BTL-3 (6) CO-2 BTL-3			
system desig	gn. UA	V system i	dentificat	aneuverability r	equire	ments. Aircraft		(6) CO-2			
system desig	gn. UA	V system i	dentificat	laneuverability r ion	equire	ments. Aircraft		(6) CO-2 BTL-3 (7)			
system design MODULE 3:  UAV aerodyn MODULE 4:	gn. UA	N system i	dentificat es and pro	laneuverability r ion	equire nance	ments. Aircraft	nalysis.	(6) CO-2 BTL-3 (7) CO-2 BTL-			
system design MODULE 3:  UAV aerodyn MODULE 4:	gn. UA	N system i	dentificat es and pro	laneuverability r ion ppulsion, perforn	equire nance	ments. Aircraft	nalysis.	(6) CO-2 BTL-3 (7) CO-2 BTL- (6)			
MODULE 4: UAV project  MODULE 5:	namic	s, structure	es and pro	laneuverability r ion ppulsion, perforn	equire nance	ments. Aircraft and stability ar : aircrafts and	nalysis. of UAVs.	(6) CO-2 BTL-3 (7) CO-2 BTL- (6)			

MODULE 6:		(6)			
Wind Tunnel Testing, Aerodynamic Characterization through Wind Tunnel Testing.					
REFERENCE BOOK	S				
1.	"Introduction to Flight", by John D. Anderson				
2.	"Performance, Stability, Dynamics, and Control of Airplanes", by Bandu N. Pa	amadi.			
3.	"Aircraft performance and design", by John D. Anderson.				
4.	"Unmanned Aircraft Design A review of fundamentals", by Mohammad H. S	adraey.			
5.	"Aircraft Design : A Conceptual Approach", by Daniel P. Raymer.				
6.	"Unmanned Aircraft Systems: UAVs Design Development and Deployment", b	y Reg Austin.			
7.	"SmallUnmannedFixed-wingAircraftDesign:APracticalApproach",byAndrand James P.Scanlan.	rewJ.Keane			
8.	Literature / books suggested by respective course Lecturers.				

COURSE TIT	LE	NAVAL OCEAN ANALYSIS AND PREDICTION CREDIT						3
COURSE CO	DE	DT	A-3743	COURSE CATEGOR	Y	DE	L-T-P-S	3-0-0-0
Version			BTL-3					
ASSESSMENT S	ASSESSMENT SCHEME							
First Periodi Assessmer			l Periodical essment	Seminar/ Assignments/ Project		Surprise Test / Quiz	Attendance	ESE
15%			15%	10%		5%	5%	50%
Course Object	ive	Ocean. generat	They will lea	led to provide und rn methods of and an circulation pre VAFS).	alysi	is of ocean data	, to model Nav	al ocean, to
Course Outcor	me	1 2	L. Understa 2. Perform t 3. Understa	f this course, the and the design require aerodynamic and the performan	uirei analy ce te	ments, design p ysis, performan esting of the UA	arameters of U ce and stability Vs.	analysis.
CO, PO Mappi	ng							
СО	PO-	1	PO-2	PO-3 PC	<b>D-4</b>	PO-5	PO-6	PO-7
CO-1	3		2			-	-	-
CO-2	3		2			-	-	-
CO-3	3		2			-	-	-
MODULE 1:	<u> </u>			-  -		-		
		مامم ملايا	ha Indian Na		اء ما م	na na diationa avat	0.000	(6) CO-1
Advanced Kr	IOWIE	eage or ti	ne mulan Na	vy ocean analysis	anu	prediction syst	ems.	BTL-3
MODULE 2:								(5)
Naval Ocean	n Mod	deling Pro	ogram (NON	IP), Naval ocean d	lata	systems.		CO-2 BTL-3
MODULE 3:								(6)
Atmospheric	c forc	ing syste	ems, data ass	imilation systems	).			CO-2 BTL-
MODULE 4:								(6)
Optimal The (TOPS).	ermal	Interpol	ation System	(OTIS), Thermal (	Ocea	an Prediction Sy	stems	CO-3 BTL-3
MODULE 5:					_			(6)
		-		The atmospheric   ula for estimating	-		layer,	CO-3 BTL-3

MODULE 6:						
The global ocean circulation prediction system, Shallow Water Analysis and Forecast System (SWAFS), Knowledge of ocean eddies.  CO-4 BTL-3						
REFERENCE BOOKS						
1.	Indian Navy: Ocean of opportunities (Defence Series Books) Author: by PRANAV ZOPE					
2.	2. Elements of Ocean Engineering. Author Robert E. Randall					
3.	Ocean Modelling for Beginners - Using Open-Source Software. Author Jochen Kaempf.					
4.	Literature / books suggested by respective course Lecturers.					

COURSE TITI	LE	LLING &SIMU	JLATION OF LASER			CREDITS	3
COURSE COL	DE D	ГА-3744	L-T-P-S	3-0-0-0			
Version		1.0	Approval Details	23 A0 06.02.	-	LEARNING LEVEL	BTL-3
ASSESSMENT SCHEME							
First Periodi Assessmer		d Periodical sessment	Seminar/ Assignments/ Project Surprise Test / Quiz			Attendance	ESE
15%		15%	10%	5%	6	5%	50%
Course Objecti	interac lethali	ction with me ty modelling,	led to provide und tals and composite damage mechanisi formance evaluatio	materials, n & damag	physics ge thresh	based models nold measurem	for the
Course Outcon	Upon completion of this course, the students will be able to  1. Understand of the laser matter interaction.  2. Develop physics-based model for evaluation of effect of laser on metals and composites.  3. Understand the laser parameter measurement techniques.  4. Analyse the performance of high-power laser systems.					etals and	
MODULE 1:							(6)
со	PO-1	PO-2	PO-3 PO-	4 [	PO-5	PO-6	PO-7
CO-1	3	2	2 -	-		-	-
CO-2 CO-3	3	2	- 2	-		1 -	2
CO-4	3	2	2 2		<u> </u>	1	2
CO-4	3		2 2				
Laser beam composite m		cs, Laser letha	ality modeling & sir	nulation w	ith meta	Il targets &	CO-1 BTL-3
	d models for	· vulnerability	assessment, Effec	of laser o	n metals		CO-2
composite m							BTL-3
MODULE 3:							(6)
		cterization of r Interpretati	Damage Thresholon.	ds, Mechan	nisms of	Damage,	CO-2 BTL-
MODULE 4:							(6)
Analysis Too techniques.	ls for the Est	imation of Ha	azards, Laser paran	eters mea	suremer	nt	CO-3 BTL-3
MODULE 5:							(7)
Tools to ana	lyse and pro-	dict Lasar Suct	tem performance ι	ınder diffor	rent con	ditions like	CO-3
10013 to alla	iyac anu pre	uici Lasei Sys	tem periormance (	muci ulliel	CITE COIT	aitions like	BTL-3

land, sea air, etc	c.					
MODULE 6:	MODULE 6:					
Introduction of full scale end to end modeling of laser system performance.  CO-4 BTL-3						
REFERENCE BOOKS	5					
1.	"High Power Laser-Matter Interaction", by Mulser, Peter, Bauer, Dieter. Publisher : Springer.					
2.	Literature / books suggested by respective course Lecturers.					

COURSE TIT	LE	COMPL	JTATIONAL /	CREDITS	3				
COURSE COI	DE	DTA-3745 COURSE CATEGORY DE L-T-P-S							)
Version	Version 1.0 Approval Details						LEARNING LEVEL	BTL-3	
ASSESSMENT SCHEME									
First Periodi Assessmer		Second Periodical Assessment		Seminar/ Assignments/ Project		ise Test / Quiz	Attendance	ESE	
15%			15%	10%		5%	5%	50%	
Course Objecti	ive	numeri	cal methods	led to provide lear for solving system ence modelling.	_	•		•	,
Course Outcome  Upon completion of this course, the students will be able to  1. Understand the CFD analysis, fluid mechanics, heat transfer analysis, numerical modelling of fluids.  2. Generate numerical model related to fluid dynamics  3. To do the pre and post processing of CFD analysis.					llysis,				
CO, PO Mappi	ng								
СО	PO-1	1	PO-2	PO-3 PO	-4	PO-5	PO-6	PO-7	
CO-1	3		2			-	-	-	
CO-2	3		2	3 3		3	2	2	
CO-3	3		2	3 3		3	2	2	/=\
MODULE 1:									(5)
Introduction	n to f	luid mec	hanics & hea	it transfer.				CO-1 BTL-3	
MODULE 2:								DIL-3	(6)
	ton	umorical	analysis Die	scretization approa	chest fin	ita diffora	nce finite	CO-2	(0)
volume, finit			•	• •	ICHES. 1111	ite uillele	nice, mille	BTL-3	
MODULE 3:			a spectrar in	2011043,					(6)
		de for al	achraic caus	ations/systems of e	austions	Numaria	al sahamas	CO-2	<b>\</b> - <b>/</b>
				ystems and for flui	•	•	lai schemes	BTL-	
MODULE 4:	ic, po	ii abone e	The emptie 5	ysterns and for har	a aynann				(7)
CFD analysis									(1)
CI D allalysis	•							CO-3	
								BTL-3	
MODULE 5:									(6)
Numerical m	nodel	ling of co	mpressible	& in-compressible	flow. tur	bulence n	nodelling	CO-3	
		J 2. 30	1- 2-3.0.0					BTL-3	(3)
MODULE 6:									(6)

Grid generatio	CO-4 BTL-3				
REFERENCE BOOK	KS .				
1.	"ATextbookofHeatTransferPaperback", by S.P. Sukhatme. Publisher: Univer	-sitiesPress.			
2.	"An Introduction to Computational Fluid Dynamics: The Finite Volume Method", by H. Versteeg. Publisher: Pearson.				
3.	"Computational Fluid Dynamics the Basics with Applications", by John D. An-der Publisher: McGraw Hill Education	son, Jr.			
4.	"Fluid Mechanics: Volume 2: Foundations and Applications of Mechanics (Camb C. S. Jog. Publisher: Cambridge University Press; 3rd edi-tion.	oridge-iisc)", by			
5.	"Numerical Modeling and Computer Simulation", Edited by DraganCvetković, publisher intechopen.				
6.	Literature / books suggested by respective course Lecturers.				

Version   1.0   Approval Details   23 ACM,   LEARNING   BTL-3   3-0-0-0	COURSE TIT	LE	LAUNCH VEHICLE DESIGN & ANALYSIS					CREDITS	3	
ASSESSMENT SCHEME  First Periodical Assessment	COURSE COI	DE	DT	<b>4-3746</b>	COURSE CATEGOR	RY	DE	L-T-P-S	3-0-0-0	
First Periodical Assessment  Assessment  Second Periodical Assessment  15%  15%  15%  10%  5%  5%  50%  Course Objective  The course is intended to provide learning on the launch vehicle design and analysis, components and subsystems of the launch vehicle, propulsion systems.  Upon completion of this course, the students will be able to  1. Understand the launch vehicle requirements, its functioning. 2. Design and analysis of launch vehicles.  3. Understand the propellant requirement for launch vehicles.  CO, PO Mapping  CO  PO-1  PO-2  PO-3  PO-4  PO-5  PO-6  PO-7  CO-1  3  2	Version	Version 1.0 Approval Details						BTL-3		
Assessment Project Quiz Assessment Quiz Assessment Project Quiz Assessment Quiz Assessment Project Quiz Space	ASSESSMENT SCHEME									
Course Objective  The course is intended to provide learning on the launch vehicle design and analysis, components and subsystems of the launch vehicle, propulsion systems.  Upon completion of this course, the students will be able to  1. Understand the launch vehicle requirements, its functioning. 2. Design and analysis of launch vehicles. 3. Understand the propellant requirement for launch vehicles.  CO, PO Mapping  CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7  CO-1 3 2 2 3					Assignments/		•	Attendance	ESE	
Course Objective components and subsystems of the launch vehicle, propulsion systems.  Upon completion of this course, the students will be able to  1. Understand the launch vehicle requirements, its functioning. 2. Design and analysis of launch vehicles.  3. Understand the propellant requirement for launch vehicles.  CO, PO Mapping  CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7  CO-1 3 2 2	15%			15%	10%		5%	5%	50%	
Course Outcome  1. Understand the launch vehicle requirements, its functioning. 2. Design and analysis of launch vehicles. 3. Understand the propellant requirement for launch vehicles.  CO, PO Mapping  CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7  CO-1 3 2 2	Course Objecti	ive			•	_		•		,
CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2 CO-2 3 2 3 2 3 - CO-3 3 2 CO-3 3 2 - CO-3 BTL-3  MODULE 1:  (6)  Introduction to propulsion for launch vehicles, beginning with mission energy requirements and an overview of current and proposed launch propulsion devices.  MODULE 2:  Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid.  MODULE 3:  Liquid and nuclear rocket motor propulsion systems.  MODULE 4:  (7) Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5:  (6) FE modelling: Idealization, Discretization, Meshing and Post Processing.	Course Outcor	ne	1. 2.	Understand Design and a	the launch vehicle nalysis of launch v	requ vehicl	uirements, its fu les.	nctioning.		
CO-1 3 2 2	CO, PO Mappi	ng								
CO-2 3 2 2 3 - 2		PO-1	L	PO-2	PO-3 PO	<b>D-4</b>	PO-5	PO-6	PO-7	
CO-3 3 2 2 (6)  MODULE 1: (6)  Introduction to propulsion for launch vehicles, beginning with mission energy requirements and an overview of current and proposed launch propulsion devices.  MODULE 2: (5)  Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid.  MODULE 3: (7)  Liquid and nuclear rocket motor propulsion systems.  MODULE 4: (7)  Advanced cycles and concepts are presented. Design of components and subsystems  MODULE 5: (6)  FE modelling: Idealization, Discretization, Meshing and Post Processing.									-	
MODULE 1:  Introduction to propulsion for launch vehicles, beginning with mission energy requirements and an overview of current and proposed launch propulsion devices.  MODULE 2:  Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid.  MODULE 3:  Liquid and nuclear rocket motor propulsion systems.  MODULE 4:  Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5:  (6)  FE modelling: Idealization, Discretization, Meshing and Post Processing.  CO-1 BTL-3  CO-2 BTL-3  (7)  CO-2 BTL-3  CO-3 BTL-3  CO-3 BTL-3										
Introduction to propulsion for launch vehicles, beginning with mission energy requirements and an overview of current and proposed launch propulsion devices.  MODULE 2: (5)  Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid.  MODULE 3: (7)  Liquid and nuclear rocket motor propulsion systems.  MODULE 4: (7)  Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5: (6)  FE modelling: Idealization, Discretization, Meshing and Post Processing.  CO-3 BTL-3  CO-3 BTL-3					<u>    -                                 </u>		<u>  -</u>			6)
requirements and an overview of current and proposed launch propulsion devices.  MODULE 2:  Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid.  MODULE 3:  Liquid and nuclear rocket motor propulsion systems.  CO-2 BTL-3  CO-2 BTL-3  CO-2 BTL-3  CO-2 BTL-3  CO-2 BTL-3  CO-3 BTL-3  MODULE 4:  Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5:  (6)  FE modelling: Idealization, Discretization, Meshing and Post Processing.		to ni	ronulsior	n for launch	vehicles heginnin	o wit	th mission ener	gv		<b>-</b>
MODULE 2:  Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid.  MODULE 3:  Liquid and nuclear rocket motor propulsion systems.  MODULE 4:  Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5:  (6)  FE modelling: Idealization, Discretization, Meshing and Post Processing.		•	•			_		<b>-</b> .		
breathing and solid.  MODULE 3:  Liquid and nuclear rocket motor propulsion systems.  MODULE 4:  Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5:  (6)  FE modelling: Idealization, Discretization, Meshing and Post Processing.	•				· ·				(!	5)
MODULE 3:  Liquid and nuclear rocket motor propulsion systems.  MODULE 4:  Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5:  FE modelling: Idealization, Discretization, Meshing and Post Processing.  (7)  CO-2 BTL-1  CO-2 BTL-2  CO-3 BTL-3	Performance	e ana	lysis, ope	erating chara	cteristics and pro	pella	ant selection cri	teria for air	CO-2	
Liquid and nuclear rocket motor propulsion systems.  MODULE 4:  Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5:  (6)  FE modelling: Idealization, Discretization, Meshing and Post Processing.		nd sol	id.						BTL-3	
Liquid and nuclear rocket motor propulsion systems.  MODULE 4:  Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5:  FE modelling: Idealization, Discretization, Meshing and Post Processing.  CO-3 BTL-3	MODULE 3:								()	7)
Advanced cycles and concepts are presented. Design of components and subsystems  CO-3 BTL-3  MODULE 5:  (6)  FE modelling: Idealization, Discretization, Meshing and Post Processing.  CO-3 BTL-3	Liquid and n	uclea	r rocket	motor prop	ulsion systems.					
MODULE 5:  FE modelling: Idealization, Discretization, Meshing and Post Processing.  CO-3 BTL-3 BTL-3	MODULE 4:									(7)
FE modelling: Idealization, Discretization, Meshing and Post Processing.  CO-3 BTL-3	Advanced cycles and concepts are presented. Design of components and subsystems									
FE modelling: Idealization, Discretization, Meshing and Post Processing.  BTL-3	MODULE 5:									(6)
	FE modelling	g: Ide	alization	, Discretizati	on, Meshing and	Post	Processing.			
	MODULE 6:								_	5)

Tracking and co	CO-4 BTL-3	
REFERENCE BOOK	S	
1.	"Design of Rockets and Space Launch Vehicles", by Don Edberg, Willie Co American Institute of Aeronauti cs & Ast. (August 21, 2020)	osta. Publisher :
2.	"Modern Engineering for Design of Liquid Propellant Rocket Engine Astronautics and Aeronautics)", by Dieter K Huzel, David H Huang. Pu (American Institute of Aeronautics & Astronautics); Revised, Subse-quent edi	ıblish-er : AIAA
3.	"Fundamentals of Astrodynamics 1st Edition", by Roger R. Bate, Dona Publisher: The American Design Ethic, MIT, USA.	ald D. Mueller.
4.	"Commercial Launch Vehicle Design", by Nickolay Mykola Zosimovych. Pub-lis Lambert Academic Publishing.	her: Lap
5.	"Space Vehicle Design, Second Edition", by Michael D. Griffin and James R. Frenc American Institute of Aeronautics and Astronautics, Inc.	ch. Publisher The
6.	Literature / books suggested by respective course Lecturers.	

COURSE	TITLE	ACQUISITION, TRA	CREDITS	3		
COURSE	CODE	DTA-3747	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
Versio	Version 1.0 Approval Details 23 ACM, 06.02.2021				LEARNING LEVEL	BTL-3
ASSESSMEN	NT SCHEN	ΛE				
First Peri Assessn		Second Periodical Assessment	Seminar/ Assignments/ Project Surprise Test / Quiz		Attendance	ESE
15%	6	15%	10%	5%	5%	50%
Course Obj	jective		nded to provide learni elopment of tracking a	•	, ,	
		1. Understan	ion of this course, the d the concepts and ba d the system configur	sic systems requ	irements track	· .
Course Out	tcome	introduction to 3. Understan	e design of stabilized posome more advance d the control system a lized in the design of the control system and the design of th	d concepts. and algorithm ted	king systems, a	
CO, PO Ma		introduction to 3. Understan	e design of stabilized posome more advanced the control system a	d concepts. and algorithm ted	king systems, a	
		introduction to 3. Understan commonly uti	e design of stabilized posome more advanced the control system a	d concepts. and algorithm ted	king systems, a	
CO, PO Ma	pping	introduction to 3. Understan commonly uti	e design of stabilized posome more advance d the control system a lized in the design of t	d concepts. and algorithm ted racking systems.	king systems, a	ractices
CO, PO Ma	pping PO-:	introduction to a understan commonly uti	e design of stabilized posome more advance d the control system a ized in the design of t	d concepts.  and algorithm tectors systems.  PO-5	king systems, a chniques and p	ractices
CO, PO Ma <sub>l</sub> CO CO-1	pping PO-:	introduction to 3. Understan commonly util	e design of stabilized posome more advanced the control system a ized in the design of the posterior of the	d concepts.  Ind algorithm tectors systems.  PO-5  1	king systems, a chniques and p	ractices
CO, PO Ma CO CO-1 CO-2	pping PO-	introduction to 3. Understan commonly util	e design of stabilized posome more advanced the control system a ized in the design of the posterior of the	d concepts.  Ind algorithm tector racking systems.  PO-5  1  1	PO-6	PO-7 -
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE	pping PO-: 3 3 3 1:	introduction to 3. Understan commonly utiling PO-2  2 2 2 2	e design of stabilized posome more advanced the control system a ized in the design of the posterior of the	d concepts.  Ind algorithm tec racking systems.  PO-5  1  1  1	PO-6	PO-7
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE	pping PO-: 3 3 3 1: on, track	introduction to 3. Understan commonly utiling PO-2  2 2 2 2	PO-3 PO-4	d concepts.  Ind algorithm tec racking systems.  PO-5  1  1  1	PO-6	PO-7 (6)
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE Acquisition	pping PO-: 3 3 3 1: con, track	introduction to 3. Understan commonly utiling PO-2  2 2 2 2 ing, and pointing (A	PO-3 PO-4	d concepts.  Ind algorithm tec racking systems.  PO-5  1  1  1  v systems	PO-6	PO-7 (6) CO-1 BTL-3 (6)
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE Acquisitio	pping PO-3 3 3 1: con, track 2: cacking ar	introduction to 3. Understan commonly utiling PO-2  2 2 2 2 ing, and pointing (A	PO-3 PO-4	d concepts.  Ind algorithm tec racking systems.  PO-5  1  1  1  v systems	PO-6	PO-7 (6) CO-1 BTL-3 (6)
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE Acquisitio	pping PO-3 3 3 3 1: on, track 2: acking aaty of est	introduction to 3. Understan commonly utilized and pointing (Augustian and pointing (Augustian and related mathematical a	PO-3 PO-4	d concepts.  Ind algorithm tec racking systems.  PO-5  1  1  1  v systems	PO-6	PO-7 (6) CO-1 BTL-3 (6)
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE Acquisition MODULE Target traprobabilit MODULE	pping PO-3 3 3 1: on, track 2: acking alty of est 3:	introduction to 3. Understan commonly utilized and pointing (Augustian and pointing (Augustian and related mathematical a	PO-3 PO-4 PO-5 PO-4 PO-6 PO-7 PO-7 PO-7 PO-7 PO-8 PO-8 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9	d concepts.  Ind algorithm tec racking systems.  PO-5  1  1  1  v systems	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE Acquisition MODULE Target traprobabilit MODULE	pping PO-: 3 3 3 1: on, track 2: acking and ty of est 3: algorithm	introduction to 3. Understan commonly utilized and policing, and pointing (And related mathematimation, detection of the state of the s	PO-3 PO-4 PO-5 PO-4 PO-6 PO-7 PO-7 PO-7 PO-7 PO-8 PO-8 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9	d concepts.  Ind algorithm tec racking systems.  PO-5  1  1  1  v systems	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3 (6)
CO, PO Maj CO CO-1 CO-2 CO-3 MODULE Acquisition MODULE Target tra probabilit MODULE	pping PO-3 3 3 3 1: on, track 2: acking anty of est 3: algorithm 4:	introduction to 3. Understan commonly utiling PO-2  2 2 2 ing, and pointing (And related mathemation, detection of the common of	PO-3 PO-4 PO-5 PO-4 PO-6 PO-7 PO-7 PO-7 PO-7 PO-8 PO-8 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9	d concepts.  Ind algorithm tector racking systems.  PO-5  1  1  1  r systems  t, the Johnson cr	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3 (6)
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE Acquisition MODULE Target tra probabilit MODULE Tracking a	pping PO-3 3 3 3 1: on, track 2: acking and ty of est 3: algorithm 4: c counter	introduction to 3. Understan commonly utiling PO-2  2 2 2 ing, and pointing (And related mathemation, detection of the common of	PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-5 PO-6 PO-1 PO-1 PO-1 PO-1 PO-1 PO-1 PO-1 PO-1	d concepts.  Ind algorithm tector racking systems.  PO-5  1  1  1  r systems  t, the Johnson cr	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3 (7) CO-3 BTL-3
CO, PO Major CO CO-1 CO-2 CO-3 MODULE Target traprobabilit MODULE Tracking a MODULE Electronic MODULE	pping PO-3 3 3 3 1: on, track 2: acking and ty of est 3: algorithm 4: c counte	introduction to 3. Understan commonly utiling PO-2  2 2 2 ing, and pointing (And related mathemation, detection of the common of	PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-5 PO-6 PO-1 PO-1 PO-1 PO-3 PO-4 PO-1 PO-3 PO-4 PO-4 PO-3 PO-4 PO-4 PO-6 PO-7 PO-6 PO-7 PO-8 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9	d concepts.  Ind algorithm tector racking systems.  PO-5  1  1  1  r systems  t, the Johnson cr	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3 (6) CO-2 BTL- (7)

MODULE 6:		(5)		
Doppler and Ele	CO-4 BTL-3			
REFERENCE BOOKS				
1.	"Acquisition, Tracking, Pointing, and Laser Systems Technologies XXI (Pro-ceedings of SPIE)" 30 October 2007 by Steven L. Chodos (Editor), William E. Thompson (Editor).			
2.	"Acquisition, Tracking, and Pointing, January 2017 In book: Free Space Optical Communication", by Hemani Kaushal, Vk Jain and SubratKar. Publisher: Springer India.			
3.	Literature / books suggested by respective course Lecturers.			

COURSE TIT	LE		ACQUISITION ANALYSIS	I, TRACKING & POST		CREDITS	3		
COURSE CO	DE	DT	A-3748	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0		
Version			1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3		
ASSESSMENT	SCHEN	1E							
	First Periodical Second Periodical Assessment Seminar/ Assessment Seminar/ Assignments/ Project Quiz			Attendance	ESE				
15%			15%	10%	5%	5%	50%		
Course Object	ive			led to provide learn llibration, Generatio	_		ht trials,		
Course Outcome		1.	Understand instruments Understand acquisition s	on of this course, the the interfaces used to real-world signal the Sensors and tra oftware ost flight analysis.	in data acquisitio s.	n and standalo			
CO, PO Mappi	ng								
СО	PO-	1	PO-2	PO-3 PO-4	PO-5	PO-6	PO-7		
CO-1	3		2		1	-	-		
CO-2	3		2	1 -	1	-	-		
CO-3	3		2		2	2	2		
MODULE 1:							(4)		
Importance	of Fli	ght Trials	s in Missile D	evelopment, Faciliti	es, Safety Requir	ements.	CO-1		
							BTL-3		
MODULE 2:							(6)		
Methods of	Meas	suremen	t. Introduction	on to Measuring Inst	ruments: Functio	nal elements	CO-2		
of an instrui			,	Ü			BTL-3		
MODULE 3:							(6)		
Static and D their respon	•	ic Chara	cteristics, Ze	ro, First and Second	order of Instrum	ents and	CO-2 BTL-		
MODULE 4:							(5)		
Calibration	of Ins	truments	5.				CO-3 BTL-3		
MODULE 5:							(8)		
		sducers:	Passive and	Active types, their u	ses in measurem	ent of	CO-3		
				e, flow and tempera			BTL-3		
30001010101	ه.، ∞	, •	, pressur	-, and tempero					

MODULE 6:		(7)				
Methods for po	CO-4 BTL-3					
REFERENCE BOOKS						
1.	"Advances in Missile Guidance, Control, and Estimation: 47 (Automation and Control Engineering)", by editors S.N. Balakrishnan, A. Tsourdos, B.A. White.					
2.	"CalibrationHandbookofMeasuringInstruments1stEdition",byAlessandroBrunelli. Publisher International Society of Automation.					
3.	"Calibration Book", by Janne Kivilaakso, Antero Pitkäkoski Jori Valli, Mike Johnson, Nobuo Inamoto Arja Aukia Masaki Saito. Publisher: VaisalaOyj.					
4.	"Sensors and Transducers", by Patranabis D. Publisher: Prentice Hall India Le Limited.	arning Private				
5.	"Sensors and Transducers Paperback", by Ian Sinclair. Publisher: Elsevier.					
6.	Literature / books suggested by respective course Lecturers.					

COURSE TITLE AIR INDEPENDENT PROPULSION AND BATTERIES CREDITS							CREDITS		3	
COURSE COD	DE	DT	A-3749	COURSE CATEG	ORY	ı	DE	L-T-P-S	s	3-0-0-0
Version			1.0	Approval Det	ails		ACM, 2.2021	LEARNIN LEVEL	_	BTL-3
ASSESSMENT SCHEME										
First Periodic Assessmen			l Periodical essment	Seminar/ Assignment Project		_	se Test / uiz	Attenda	nce	ESE
15%			15%	10%		5	5%	5%		50%
Course Objecti	ve			led to provide cles, power req		_		•	•	•
Course Outcom	ne	1.	Understand	on of this cours the requireme analysis Energy	nts of	air inde	pendent	propulsio	•	
CO, PO Mappin										
СО	PO-1	L	PO-2	PO-3	PO-4		PO-5	PO-6	<b>i</b>	PO-7
CO-1 CO-2	3		2	3	-		2	2		2
MODULE 1:	<u> </u>			<u> </u>	-					(6)
	to H	ybrid Ele	ectric Vehicle	s: Impact of m	odern	drive-ti	rains on e	energy		CO-1 BTL-3
MODULE 2:										(7)
Hybrid Electr			-	ction, various h	nybrid	drive-tı	ain topo	logies, po	wer	CO-2 BTL-3
MODULE 3:										(7)
				electric drive-t		pologie	s, power	flow cont	trol	CO-2 BTL-
MODULE 4:										(6)
Configuration	n and	d control	of DC Moto	onents used in r drives, Induct nce Motor drive	ion M	otor dri	ves, Pern	nanent		CO-3 BTL-3
MODULE 5:										(6)
Energy Stora Vehicles.	ge: lı	ntroduct	ion to Energ	y Storage Requ	iireme	nts in H	ybrid and	d Electric		CO-3 BTL-3
MODULE 6:										(6)
analysis, Sup storage and	MODULE 6:  Battery based energy storage and its analysis, Fuel Cell based energy storage and its analysis, Super Capacitor based energy storage and its analysis, Flywheel based energy storage and its analysis, Hybridization of different energy storage devices.  REFERENCE BOOKS								CO-4 BTL-3	

1.	"Hybrid Electric Vehicles: Principles and Applications with Practical Perspec-tives", by Chris Mi, M. Abul Masrur. Publisher: Wiley.
2.	"Modern Electric, Hybrid Electric, and Fuel Cell Vehicles: Fundamentals, Theo-ry, and Design, Second Edition (Power Electronics and Applications Series)", by Mehrdad Ehsani, YiminGao, Ali Emadi, Publisher: Standards media.
3.	Literature / books suggested by respective course Lecturers.

COLUDER	TLE	NCED DIGITA NOLOGIES & S	CREDITS	3								
COURSE CO	DDE D	TA-3750	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0						
Version	Version1.0Approval Details23 ACM, 06.02.2021LEARNING LEVEL					BTL-3						
ASSESSMENT	SCHEME											
First Period Assessme		nd Periodical sessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE						
15%		15%	10%	5%	5%	50%						
The objective of this course is to provide knowledge on the engineering principles, theories and practices of a digital communication system. The course will deal with the design principles of transmitter and receiver so as to establish a reliable communication link.  Upon completion of this course, the students will be able to  1. Understand the design digital communication systems.  2. Understand the transmitter, receiver communications system models, voice source coding—pulse code modulation, delta modulation and vocoders.  3. Understand the requirement of cellular communication.												
CO, PO Mapp												
СО	PO-1	PO-2	PO-3 PO		PO-6	PO-7						
CO-1	3	2	-  -	1	-	-						
CO-2	3	2		1	-	-						
	1 -		-		3 3 2 2 -							
MODULE 1: (6)												
	ligital commu	nication syste	m transmitter and	receiver commu	nications		(6)					
Design of d	_	nication syste	m, transmitter and	receiver commu	nications	CO-1 BTL-3	(6)					
	del	nication syste	m, transmitter and	receiver commu	nications	CO-1 BTL-3						
Design of d system mod MODULE 2	del :	•				CO-1 BTL-3	(6) (6)					
Design of d system mod MODULE 2	del :	•	m, transmitter and			CO-1 BTL-3						
Design of d system mod MODULE 2	del : ce coding– pu	•				CO-1 BTL-3 CO-2 BTL-3						
Design of d system mod MODULE 2 Voice source MODULE 3 Digital mod shift, Quad	del : ce coding– pu : dulation – Am	lse code mod plitude-shift, shift, Quadra		ulation, vocoders nase-shift, differe	ntial phase-	CO-1 BTL-3 CO-2 BTL-3	(6)					
Design of d system mod MODULE 2 Voice source MODULE 3 Digital mod shift, Quad	del : ce coding— pu : dulation — Am rature phase e amplitude n	lse code mod plitude-shift, shift, Quadra	ulation, delta mod Frequency-shift, Ph	ulation, vocoders nase-shift, differe	ntial phase-	CO-1 BTL-3 CO-2 BTL-3	(6)					
Design of d system mod MODULE 2 Voice source MODULE 3 Digital mod shift, Quad Quadrature MODULE 4	del : ce coding— pu : dulation — Am rature phase e amplitude n	lse code mod plitude-shift, -shift, Quadra nodulation	ulation, delta mod Frequency-shift, Ph	ulation, vocoders nase-shift, differe nd Minimum-shif	ntial phase- keying,	CO-1 BTL-3 CO-2 BTL-3	(8)					
Design of d system mod MODULE 2 Voice source MODULE 3 Digital mod shift, Quad Quadrature MODULE 4 Communication	del : ce coding— pu : dulation — Am rature phase e amplitude n :	lse code mod plitude-shift, -shift, Quadra nodulation	ulation, delta mod Frequency-shift, Ph ture phase-shift, ar	ulation, vocoders nase-shift, differe nd Minimum-shif	ntial phase- keying,	CO-1 BTL-3  CO-2 BTL-3  CO-2 BTL-  CO-3 BTL-3	(8)					
Design of d system mod MODULE 2 Voice source MODULE 3 Digital mod shift, Quad Quadrature MODULE 4 Communica Murphy	del : ce coding— pu : dulation — Am rature phase e amplitude n : ations channe	plitude-shift, -shift, Quadra nodulation	ulation, delta mode Frequency-shift, Ph ture phase-shift, an effects, fading and	ulation, vocoders nase-shift, differe nd Minimum-shif diversity, model	ntial phase- : keying, s of Egli and	CO-1 BTL-3  CO-2 BTL-3  CO-2 BTL-  CO-3 BTL-3	(8)					
Design of d system mod MODULE 2 Voice source MODULE 3 Digital mod shift, Quad Quadrature MODULE 4 Communica Murphy MODULE 5 Receivers –	del : ce coding— pu : dulation — Am rature phase e amplitude n : ations channe	plitude-shift, -shift, Quadra- nodulation el – Multipath	ulation, delta mod Frequency-shift, Ph ture phase-shift, ar	ulation, vocoders nase-shift, differe nd Minimum-shif diversity, model	ntial phase- : keying, s of Egli and	CO-1 BTL-3  CO-2 BTL-3  CO-2 BTL-  CO-3 BTL-3	(8)					

Introduction modulation	to cellular communication – CDMA, OFDM, MIMO, Introduction to digital standards.	CO-4 BTL-3					
REFERENCE BC	OOKS						
1.	"Communication Systems", by, Haykin, S. Publisher : John Wiley & Sons.						
2.	"Modern Digital and Analog Communication Systems", by, Lathi, B.P. and D Publisher: Oxford University Press.	ing, Z.					
3.	"Signal Processing for Wireless Communication Systems", by H. Vincent Tong Publisher: Springers	"Signal Processing for Wireless Communication Systems", by H. Vincent Poor, Lang					
4.	"Digital Communication: Fundamentals and Applications", by Sklar, B., a Dorling Kindersley.	"Digital Communication: Fundamentals and Applications", by Sklar, B., and Ray, P.K.					
5.	"Communication Systems: An Introduction to Signals and Noise in Electr Communication", by Carlson, A.B., Crilly, P.B. and Rutledge, J.C Publisher	"Communication Systems: An Introduction to Signals and Noise in Electrical					
6.	"Detection, Estimation and Modulation Theory Part I", by Van Trees, H.L Wiley Inter science.	. Pub-lisher :					
7.	"Information Theory, Coding and Cryptography", by Bose, R. Tata McGra	ıw-Hill.					
8.	"Digital Communication", by Barry, J.R., Lee, E.A. and Messerschmitt, D.G.	G.Kluwer.					
9.	"Principles of Digital Transmission: Wireless Applications", by Benedetto E. Publisher: Springer	, S. and Biglieri,					
10.	Literature / books suggested by respective course Lecturers.						

COURSE TIT	LE	TRAJECTORIES MODELLING & SIMULATION					CREDITS	3		
COURSE COI	DE	DT	A-3751	COURSE CATE	GORY	DE	L-T-P-S	3-0-0-0	)	
Version	Version 1.0 Approval Details 23 ACM, 06.02.2021					LEARNING LEVEL	BTL-3			
ASSESSMENT SCHEME										
First Periodi Assessmer			d Periodical essment	Seminar/ Assignments/ Project		Surprise Test / Quiz	Attendance	ESE		
15%			15%	10%		5%	5%	50%		
Course Objecti	ive		analysis, fligl	•		nderstanding of f	•			
Course Outcor	me	1. 2. 3.	Understand Evaluate and Understand	the flight traj d predict the f the practical i	ectorie light pe mplica	e students will be s design requirer erformance for d tions while traje ion for trajector	ments. lifferent traject ctory design.	ories.		
CO, PO Mappi	ng									
со	PO-	1	PO-2	PO-3	PO-4	PO-5	PO-6	PO-7		
CO-1	3		2	2	-	-	-	-		
CO-2	3		2	2	2	2	2	2		
CO-3	3		2	-	-		-	-		
CO-4	3		2	2	2	2	2	2	(6)	
Accuracy of		•	•	ations. Aerody otion, orbital		sizing-equations nics.	of motion.	CO-1 BTL-3		
MODULE 2:								T	(7)	
	•	•		-		vers, Maximizin	g missile	CO-2 BTL-3		
MODULE 3:	manc	e. Benei	its or night t	rajectory shar	nng.			BIL-3	(7)	
Flight perfor		•	ction of boos homing fligh		e, coas	t, steady descen	t, ballistic,	CO-2 BTL-	(7)	
MODULE 4:									(5)	
Practical implementation of integrated trajectory planning, Agility in maneuvering trajectories.								CO-3 BTL-3		
MODULE 5:									(5)	
computation	Multiplier theory and its use in solving practical problems covered from a real-time computational viewpoint, No-fly zones and engineering requirements, formulation as a mathematical mixture of state and decision-variable constraints.									

MODULE 6:		(6)			
Extensive MATLAB-based mini-projects.		CO-4 BTL-3			
REFERENCE BOOKS					
1.	"Flight Dynamics", by Robert F. Stengel. Publisher : Princeton University Press.				
2.	Literature / books suggested by respective course Lecturers.				

COURSE TIT	LE SENSO	SENSOR TECHNOLOGY				CREDITS	3	
COURSE CODE		TA-3752	52 COURSE CATEGORY		DE	L-T-P-S	3-0-0-0	
Version		1.0	Approval Details	s	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT S	SCHEME							
First Periodi Assessmer		nd Periodical sessment	Seminar/ Assignments/ Project		Surprise Test / Quiz	Attendance	ESE	
15%		15%	10%		5%	5%	50%	
Course Object	The main objective of the course is to provide learning on the basic physical princip and characteristic features in sensor technology, design, function and applications of different sensors.						· · · · · ·	
Course Outcor		<ol> <li>Upon completion of this course, the students will be able to</li> <li>Understand the basic principles of sensor systems required for satellites and tactical aircraft.</li> <li>Understand the atmospheric propagation and its impact on the performance of sensors</li> <li>Troubleshoot, repair/replace a faulty sensor in optimize process efficiency.</li> </ol>						
CO, PO Mappi	ng							
СО	PO-1	PO-2	PO-3 P	O-4	PO-5	PO-6	PO-7	
CO-1	3	2			-	-	-	
CO-2	3	2			-	-	2	
CO-3	3	2	-  -		2	2	2	
MODULE 1:							(6)	
Physical principles underlying the sensor systems needed for satellites and tactical aircraft, as well as limitations imposed by the atmosphere and operating environment on these systems and their communication links.							CO-1 BTL-3	
MODULE 2:							(5)	
Phased array and pulsed compressed radars, imaging synthetic aperture and inverse synthetic aperture radars.							CO-2 BTL-3	
MODULE 3:							(5)	
Atmospheric propagation of signal. Noise resources and thermal radiation.							CO-2 BTL-	
MODULE 4: (8)								
Principles of semiconductor devices. Optical and infrared imaging detector systems.							CO-3 BTL-3	
MODULE 5: (6)								
Detector resolution limitations and bandwidth requirements, Relationship between signals and noise.							CO-3 BTL-3	
3.0							-	

MODULE 6:					
The characteristics of critical sensor functions (including detection, estimation, imaging, and tracking).					
REFERENCE BOOKS	3				
1.	"Handbook of Modern Sensors", by Jacob Fraden. Publisher : Springer.				
2.	"Micro sensors, Principles and Applications", by J. W. Gardner. Publisher : Wiley.				
3.	"Semiconductor Sensors", by S. M. Sze. Publisher : Wiley.				
4.	Literature / books suggested by respective course Lecturers.				