

M. TECH. DEFENCE TECHNOLOGY

(Duration: 2 Years)

CURRICULUM and SYLLABUS

DEPARTMENT OF AERONAUTICAL ENGINEERING
HINDUSTAN INSTITUTE OF TECHNOLOGY AND SCIENCE

HINDUSTAN INSTITUTE OF TECHNOLOGY AND SCIENCE

Motto:

To Make Every Man a Success and No Man a Failure

Vision:

To be an International Institute of Excellence, providing a conducive environment for education with a strong emphasis on innovation, quality, research and strategic partnership blended with values and commitment to society.

Mission:

- To create an ecosystem that promotes learning and world class research.
- To nurture creativity and innovation.
- To instill highest ethical standards and values.
- To pursue activities for the development of the Society.
- To develop national and international collaborations with institutes and industries of eminence.
- To enable graduates to become future leaders and innovators.

Value Statement:

Integrity, Innovation, Internationalization.

M.Tech Defence Technology

ABOUT THE COURSE:

The M.Tech. in defence technology courses has been designed to produce Post Graduates who will have the necessary theoretical & experimental knowledge, skill and aptitude in various defence technologies areas and pursue them to carry out R&D in defence.

The students will be provided valuable exposure & knowledge for various state of the art defence systems and contemporary technologies through class lectures & main thesis work with the collaboration of DRDO. During the program, the students would be given opportunities in carrying out their main thesis work in DRDO labs, Defence PSUs & Private Defence Industries. This collaborative effort of DRDO, AICTE and Industries will provide required knowledge to the students and create job opportunities for them.

PROGRAM OBJECTIVE:

- To develop Post Graduates who have the necessary theoretical & experimental knowledge, skill and aptitude in defence technologies and systems and can get recruited in the various defence laboratories, defence public sector & private industries, ordnance factories and other similar sectors of the economy at national and international level.
- To contrive skilled manpower in the field of defence technologies.
- To enhance students" interaction with the senior, experienced manpower engaged in defence labs and defence industries and have real time knowledge / experience in the technology development, technology deployment and defence systems.
- To acquaint students for the needs of technologies related to defence & security of nation and to create zeal among students to pursue research and development for defence technologies.

PO1	Acquire technical competence, comprehensive knowledge and understanding the methodologies and technologies associated with land, air & naval defence systems. Apply knowledge to identify, formulate and analyse complex engineering problems.	Scholarship of Knowledge
PO2	Having an ability to apply knowledge of science, mathematics, engineering & technology for development of defence technologies.	Critical Thinking
PO3	Having an ability to design a component, subsystem or a system applying all the relevant standards and with realistic constraints, including operational and environmental.	Research Skill
PO4	Acquire the skills for uses of contemporary techniques, resources and modern engineering and IT tools	Usages of Modern Techniques
PO5	An ability to identify, investigate, understand and analyse complex problems, apply creativity, carry out research /investigation and development work to solve practical problems related to defence technological issues.	Design, Development & Solutions
PO6	Ability to communicate effectively in both oral and written contexts in the form of technical papers, project reports, design documents and seminar presentations.	Communication
P07	Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.	Individual &Team Work

PROGRAM OUTCOME:

PROGRAM STRUCTURE:

It is a 4-semester program with total 80 credits. It is having 4 specializations, as regard to the specializations, semester -1 will have common curriculum and semester 2 curriculum will be varied as per the specialization. Semester 3 & 4 includes dissertation and industrial training. The M.Tech. in Defence Technology will be having following specializations:

- 1. Combat Vehicle Engineering
- 2. Aerospace Technology
- 3. Communication Systems & Sensors
- 4. High Energy Materials Technology

Semester - 1:Courses will be same for all specializations.

Semester -2:Courses will be as per the selected specialization.

Semester - 3 &4:Projects and Industrial Training.

ELIGIBILITY CRITERIA:

Those who have pursued under graduation in following disciplines are eligible for taking up the M.Tech. Defence Technology courses:

1) Aerospace Engineering	26) Electronics and Computer Engineering
2) Aeronautical engineering	27) Electronics and Communication
	Engineering
3) Applied Electronics and	28) Electronics and Computer Science
Communication Engineering	
4) Applied Electronics and	29) Electronics and Control Systems
Instrumentation Engineering	
5) Chemical Technology	30) Electronics and Power Engineering
6) Chemical engineering	31) Electronics and Telecommunication
7) Computer Science & Engineering	32) Electronics, Instruments and Control
	Engineering
8) Computer and Communication	33) Electronics System Engineering
Engineering	
9) Computer Engineering	34) Instrumentation and Electronics
10) Computer Engineering and	35) Instrumentation Engineering
Applications	
11) Computer Networking	36) Marine Engineering
12) Computer Science and Information	37) Marine Technology
Technology	
13) Computer Science and Technology	38) Mechanical and Automation Engineering
14) Computer Technology	39) Mechatronics Engineering
15) Electrical and Computer Engineering	40) Mechanical engineering
16) Electrical and Electronics Engineering	41) Metallurgical and Materials Engineering

17) Electrical and Instrumentation Engineering	42) Military engineering
18) Electrical and Power Engineering	43) Optics and Opto-electronics
19) Electrical Engineering	44) Power Electronics Engineering
20) Electronics engineering	45) Radio, Physics and Electronics
21) Electrical, Electronics and Power	46) Software Engineering
Engineering	
22) Electronics and Communication	47) Structural Engineering
engineering	
23) Instrumentation engineering	48) Telecommunication Engineering
24) Electronics, Instrumentation and	
Control Engineering	
25) Electronics, Science and Engineering	

M.Tech - Defence Technology

			SEMESTER- I								
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	Р	С	S	тсн		
1	BS	MAA0704	Advanced Engineering Mathematics	4	0	0	4	1	4		
2	PC	DTB0701	Warfare Simulations & Strategies	4	0	0	4	1	4		
3	PC	DTB0702	Systems and warfare Platforms	4	0	0	4	1	4		
4	DE-I	DTB0751	Rockets and Missiles Fundamentals	3	0	0	3	1	3		
5	DE-I	DTB0753	Communication Technology	3	0	0	3	1	3		
6	DE-II	DTB0752	Autonomy and Navigation Technology	3	0	0	3	1	3		
			PRACTICAL								
7	PC	DTB0731	Warfare Simulations & Strategies Lab	0	0	2	2	0	2		
8	PC	DTB0732	Systems and Warfare Platforms Lab	0	0	2	2	0	2		
9	BS	DTA0701	Seminar	0	0	1	1	0	1		
			Total				23		23		
L	L – Lecture; T – Tutorial; P – Practical; C – Credit; S- Self Study; TCH- Total Contact Hours										

		SEN	MESTER- II (AEROSPACE TECHNOLOG	iY)					
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	P	C	S	тсн
1	BS	DTB0716	Aerospace System Configuration, Design & Simulation	4	0	0	4	1	4
2	PC	DTB0717	Guidance & control	4	0	0	4	1	4
3	PC	DTB0718	Aerospace Propulsion	4	0	0	4	1	4
4	DE	DTB0754	Structural Dynamics and Aero- Elasticity	3	0	0	3	1	3
6	DE	DTB0755	Elective 4	3	0	0	3	1	3
			PRACTICAL						
7	PC	DTB0741	Aerospace System Configuration, Design & Simulation Lab	0	0	2	2	0	2
8	PC	DTB0742	Guidance & control Lab	0	0	2	2	0	2

9	BS	DTA0701	Seminar	0	0	1	1	0	1
			Total				23		23
ı	L – Lecture ; T	– Tutorial ; P	- Practical; C - Credit; S- Self Study	; TCF	l- To	tal C	ontact	Hou	rs

		SEMESTER	- II (COMMUNICATION SYSTEMS & S	SENS	ORS)					
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	Р	С	s	тсн		
1	BS	DTD3703	Radar Technologies	4	0	0	4	1	4		
2	PC	DTD3704	Digital & satellite Communication and Navigation from Space	4	0	0	4	1	4		
3	PC	DTD3705	Tactical battlefield Communication & Electronic Warfare	4	0	0	4	1	4		
4	DE	DE	Elective 3	3	0	0	3	1	3		
6	DE	DE	Elective 4	3	0	0	3	1	3		
			PRACTICAL								
7	PC	DTD3791	Radar Technologies Lab	0	0	2	2	0	2		
8	PC	DTD3792	Digital & Satellite Communication and Navigation from Space Lab	0	0	2	2	0	2		
9	BS	DTD3796	Seminar	0	0	1	1	0	1		
			Total				23		23		
L	L – Lecture ; T – Tutorial ; P – Practical ; C – Credit; S- Self Study; TCH- Total Contact Hours										

	SEMESTER- III (COMMON FOR ALL SPECIALISATION)											
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	Р	С	S	тсн			
7	PC	DTA3797	Project - Phase 1	0	0	24	10	0	24			
8	PC	DTA3798	Internship	0	0	8	4	0	8			
Total 14												
L – Lecture ; T – Tutorial ; P – Practical ; C – Credit; S- Self Study; TCH- Total Contact Hours												

	SEMESTER- IV (COMMON FOR ALL SPECIALISATION)									
SL. NO	COURSE CATEGORY	COURSE CODE	NAME OF THE COURSE	L	Т	Р	С	S	тсн	

1	PC	DTA3799	Project - Phase 2	0	0	40	20	0	40
			Total				20		0
L	– Lecture : T	– Tutorial : P	- Practical ; C - Credit; S- Self Study	: TCF	l- To	tal C	ontact	Hou	rs

LIST OF DEPARTMENTAL ELECTIVES WITH GROUPING – SEMESTER WISE

SEM	COURSE CATEGORY	COURSE	NAME OF THE COURSE	L	Т	Р	С	S	тсн		
	ELECTIVE -1										
1	DE	DTB0751	Rockets & Missiles Fundamentals	3	0	0	3	1	3		
1	DE		Advanced Thermal Engineering	3	0	0	3	1	3		
1	DE		Numerical Methods for Science and Engineering	3	0	0	3	1	3		
1	DE	DTB0753	Communication Technology	3	0	0	3	1	3		
1	DE		Advanced Mechanical Engineering	3	0	0	3	1	3		
			ELECTIVE - 2	•							
1	DE	DTB0752	Autonomy and Navigation Technology	3	0	0	3	1	3		
1	DE		Optimization Theory & Applications	3	0	0	3	1	3		
1	DE		Military Electronics System Engineering	3	0	0	3	1	3		
1	DE		System Engineering and Analysis	3	0	0	3	1	3		
	ELECTIVE - 3										
2	DE	DTA-3730	Robotics (MSS, MCC)	3	0	0	3	1	3		
2	DE	DTA-3731	EMI/EMCIn Military Systems	3	0	0	3	1	3		

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2	DE	DTA-3732	Defence Electro-Optics and Imaging Systems	3	0	0	3	1	3
2	DE	DTA-3733	Structural Dynamics and Aero- Elasticity	3	0	0	3	1	3
2	DE	DTA-3734	Safety, Health & Hazard Management	3	0	0	3	1	3
2	DE	DTA-3735	Fundamental of Telemetry, Telecommand& Transponder	3	0	0	3	1	3
2	DE	DTA-3736	Jamming and ECM/ECCM Technologies	3	0	0	3	1	3
2	DE	DTA-3737	Software Defined Radios	3	0	0	3	1	3
2	DE	DTA-3738	Advanced Lightweight and Composite Structures	3	0	0	3	1	3
2	DE	DTA-3739	Test Methodologies for Dew Systems (Lasers & Microwave)	3	0	0	3	1	3
2	DE	DTA-3740	Advanced Analytical Techniques/Lab Testing	3	0	0	3	1	3
2	DE	DTA-3741	Sonar System Engineering	3	0	0	3	1	3
			ELECTIVE - 4						
2	DE	DTA-3742	Unmanned Aerial Vehicle Design	3	0	0	3	1	3
2	DE	DTA-3743	Naval Ocean Analysis and Prediction	3	0	0	3	1	3
2	DE	DTA-3744	Modelling &Simulation Of Laser Matter Interaction	3	0	0	3	1	3
2	DE	DTA-3745	Computational Aerodynamics	3	0	0	3	1	3
2	DE	DTA-3746	Launch Vehicle Design & Analysis	3	0	0	3	1	3
2	DE	DTA-3747	Acquisition, Tracking & Pointing Technology	3	0	0	3	1	3

2	DE	DTA-3748	Data Acquisition, Tracking & Post Flight Analysis	3	0	0	3	1	3
2	DE	DTA-3749	Air Independent Propulsion and Batteries	3	0	0	3	1	3
2	DE	DTA-3750	Advanced Digital Modulation Technologies & Standards	3	0	0	3	1	3
2	DE	DTA-3751	Trajectories Modelling & Simulation	3	0	0	3	1	3
2	DE	DTA-3752	Sensor Technology	3	0	0	3	1	3

SEMESTER – I

COURS	IRSE TITLE ADVANCED ENGINEERING MATHEMATICS									CREDITS	4			
COURS	E CODE		MA	A0704		COURSE CATEGORY			DE	L-T-P-S	4-0-0-0			
Vers	sion		1	1.0 Approval Details				ls	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3			
ASSESSM	ENT SCH	IEME												
First Periodical Assessment Second Periodical Assignments/ Project Surprise Test / Quiz Attended											ESE			
15% 15% 10% 5%									5%	50%				
Course Ol	bjective	To provide knowledge to the students about probability theory, algebra, solution Differential equations, Transform techniques, special functions & their application the areas with defence relevance.												
Course Outcome Upon completion of this course, the students will be able to 1. Know the methods for solving differential equations, generating functions. 2. Understand basic concepts of Fourier Transform, Laplace Transforms and some problems with periodic functions, step functions, impulse functions convolution. 3. Demonstrate MATLAB programming for engineering problems. 4. Understand the utilization of mathematical methods for solving problems has relevance to defence applications.														
CO, PO M	IAPPING	ì												
со	PO- 1	PO- 2	PO-	PO-	PO- 5	PO-	PO- 7							
CO-1	3	3	-	3	3	-	-							
CO-2	3	2	-	-	-	-	-							
CO-3	3	3	-	3	2	-	-							
CO-4	3	3	-	3	2	-	-							
			1:	Weakly	/ relate	ed, 2: Mo	oderately r	relate	d and 3: Strongly re	elated				
MODULE	1:										(7)			
Element Algebra		obabi	lity and	d Stati:	stics, o	compo	nents of	oper	ations research,	Linear	CO-1 BTL-3			
MODULE	2:										(7)			
	Ordinary Differential equations, Numerical methods for ODE and P.D.E. Generating functions, recurrence relations. BTL-3													
MODULE 3: (7)														
Transfor	m Tecl	hniqu	es, Fou	ırier se	eries, I	ourier	Transfor	rm, L	aplace Transfori	m	CO-2 BTL-3			
MODULE	4:										(6)			

·	s: Power series method, Frobenious method, Legendre equation, omials, Bessel equation, Bessel functions of first kind, Orthogonal	CO-3 BTL-3								
MODULE 5:	· · · ·									
Elements of Rar block designs.	Elements of Ramsey theory, theorems of Burnside and Polya, and balanced incomplete block designs. CO-3 BTL-3									
MODULE6:		(6)								
science and o	reas with defence relevance range from mathematics to computer perations research, applications in probability, game theory, network theory, and experimental design.	CO-4 BTL-4								
REFERENCE BOOKS										
1.	"Advanced engineering mathematics", by Kreyszig. Publisher: Wiley.									
2.	2. "Advanced engineering mathematics", by Jain/Iyenger. Publisher: Narosa.									
3. "Advanced engineering mathematics", by Taneja. Publisher: I K international .										
4. "Advanced engineering mathematics", by Alan Jeffery. Publisher: Academic Press.										
5.	"Advanced engineering mathematics", by Peter V. O"Neil. Publisher: Cen	gage Learning.								

COURS	E TITLE		V	VARF4	ARE SI	CREDITS	4					
COURS	E CODE		DTE	0701		COURS	SE CATEGORY	DE	L-T-P-S	4-0-0-0		
Ver	sion		:	1.0		Appr	oval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-4		
ASSESSM	ENT SCH	IEME										
	First Periodical Assessment Second Periodical Assessment Second Periodical Assignments/ Project Surprise Test / Quiz Attendance											
15	5%		1	5%			10%	5%	5%	50%		
Course Objective To provide knowledge to the students about warfare system and affluent them wi combat modeling using mathematical modeling.												
Course O	utcome		1. U 2. U 3. U	Inders Inders	tand t tand t tand t	the syst combat the war	tems used in simulation &	its will be able to warfare scenaric & modelling ulation & modell		factor		
CO, PO M	1APPING	3										
со	PO- 1	PO- 2	PO-	PO- 4	PO- 5	PO-	PO- 7					
CO-1	3	-	2	-	-	-	-					
CO-2	3	2	3	3	3	-	-					
CO-3	3	2	3	3	3	-	-					
			1:	Weakly	y relate	ed, 2: Mo	oderately relate	ed and 3: Strongly re	elated			
MODUL	E 1:									(7)		
Types of operation	•			ea, air;	Lifec	ycle: co	oncept, desig	n, pre-production	n, production,	CO-1 BTL-2		
MODUL	E 2:									(7)		
Military capabilities: air warfare, surface warfare, sub surface warfare, littoral warfare CO-2 BTL-2												
MODULE 3: (7)												
							g combat and ibat simulation	I their application	n in support	CO-2 BTL-3		
MODUL	E 4:									(7)		

War gaming/int	War gaming/interactive simulation, Lanchester"s equations, Mathematical models of										
combat.											
MODULE 5: (6)											
Mar gaming and	d combat modeling in practice, manual war gaming	CO-3									
war gaming and	d combat modeling in practice, manual war gaming.	BTL-4									
MODULE 6:		(6)									
Lluman factors	representation in war gaming and combat modeling	CO-3									
numan factors	representation in war gaming and combat modeling.	BTL-4									
REFERENCE BOOKS											
	"DefenseModeling, Simulation, and Analysis: Meeting the Challeng	e". Publish-er:									
1.	National Academies Press (October 22, 2006).										
2.	"Introduction to Electronic Warfare Modeling and Simulation" by Dav	vid L. Adamy".									
۷.	Publisher: Artech Print on Demand (October 31, 2002).										
"Engineering Principles of Combat Modeling and Distributed Simulation", by An											
dreasTolk (Editor), Old Dominion University. Publisher : John Wiley & Sons.											
4.	Literature / books suggested by respective course Lecturers.										

COURS	E TITLE	TLE SYSTEMS AND WARFARE PLATFORMS CREDITS									4			
COURS								L-T-P-S	4-0-0-0					
Vers	sion		:	1.0		Appr	oval Detai	ils	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3			
ASSESSM	ENT SCH	HEME												
First Pe Assess		I	Second Asse	Periodi ssment		Assi	eminar/ ignments Project	/	Surprise Test / Quiz	Attendance	ESE			
15	%		1	.5%			10%		5%	5%	50%			
Course Ol	1. To provide knowledge to the students about various types of military platforms used in air, naval & land warfare. 2. Students will also be apprised for weapon system and self-protection strategies and techniques.													
Course O	Course Outcome Upon completion of this course, the students will be able to 1. Understand types of warfare platform used for Army, Air and Marine and their design fundamentals. 2. Understand the weapon systems like guns, ordnance, missiles projectiles, mines/countermines, lasers, undersea weapons, air-launched weapons, anti-aircraft, anti-ship and anti-submarine.													
CO, PO N	IAPPING	3												
со	PO- 1	PO-	PO-	PO-	PO- 5	PO-	PO- 7							
CO-1	3	-	-	3	2	2	-							
CO-2	3	-	-	3	-	2	-							
			1:	Weakly	y relate	ed, 2: M	oderately	relate	ed and 3: Strongly re	elated				
MODULE	1:										(7)			
Types of operation	•		•	ea, air;	; Lifec	ycle: co	oncept, d	lesig	n, pre-productio	n, production,	CO-1 BTL-2			
MODULE	2:										(7)			
Ship design fundamentals: buoyancy, stability, ship resistance, survivability; damage control, NBCD, crew numbers, power requirements. Submarine design: buoyancy, stability, hull/tank design, air interdependence.														
MODULE	MODULE 3: (7)													
control	Mechanics of flight: fixed and rotary wing, straight and level flight of aircraft, aircraft control and movement, aircraft control surfaces, aerodynamics, power requirements, range; speed, ceiling, survivability, payload.													
MODULE	4:										(6)			

Military vehicle	fundamentals: tracked, wheeled, A, B and C vehicles.	CO-1 BTL-2	
MODULE 5:			(6)
mines/ counter	ns: guns, ordnance, missiles, rockets, bombs, sub- munitions, projectiles, rmines, lasers, undersea weapons, air-launched weapons, anti-aircraft, anti-ship, anti-submarine.	CO-2 BTL-2	
MODULE6:		((6)
	and Protection systems: Armour, smoke, chaff, decoys; Introduction to on, lab tests and flight trials.	CO-2 BTL-2	
REFERENCE BOOK	S		
1.	"Light And Heavy Vehicle Technology ", by Nunney. Publisher Elsevier.		
2.	"Practical approach to motor vehicle engineering and maintenance", by E et. Al. Publisher: Yesdee.	Bonnick Allan	l
3.	"Automotive Vibration Control Technology: Fundamentals, Materials, Con Simulation, and Applications", by Trelleborg	struction,	
4.	"An Introduction to Weapons Systems", by Yacov Bar-Shlomo. Publisher: Cre Independent Publishing Platform.	eate Space	
5.	"Heavy Vehicle Mechanics", by Ian Nicholson. Publisher: McGraw-Hill Educat	tion – Europe	·.
6.	"Military Laser Technology for Defense: Technology for Revolutionizing 21st Warfare", by Alastair D. McAulay. Publisher: Wiley-Interscience; 1st edition.	Century	

COURSE	COURSE TITLE WARFARE SIMULATIONS & STRATEGIES LAB CREDITS										
COURSE	COURSE CODE DTB0731 COURSE CATEGORY DE L-T-P-S										
Versi	on	1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3					
LIST OF EX	PERIMEN [*]	ΓS									
1.	1. Lab experiments will be added in consultation with DRDO labs considering the available facilities. CO-BTL-3										

COURS	E TITLE		SYS	2								
COURS	E CODE			0-0-2-0								
Vers	Version 1.0 Approval Details 23 ACM, LEARNING 06.02.2021 LEVEL									LEARNING LEVEL	BTL-3	
ASSESSM	SSESSMENT SCHEME											
	First Periodical Assessment Second Periodical Assignments/ Project Surprise Test / Quiz Attendance										ESE	
15	15% 15% 10% 5% 5%								50%			
Course Ol	bjective					1						
Course O	utcome			Upon	comple	etion of	this cou	ırse, the	e studen	ts will be able to		
CO, PO M	1APPING	3										
со	PO- 1	P(_	PO-	PO- 4	PO- 5	PO- 6	PO- 7				
CO-1												
CO-2												
CO-3												
1: Weakly related, 2: Moderately related and 3: Strongly related												
LIST OF EX	KPERIM	ENT	S									
1.		Lab experiments will be added in consultation with DRDO labs considering the available facilities.										CO- BTL-

SEMESTER I - ELECTIVE -1 COURSES

COURS	E TITLE			ROCKE	TS &	MISSIL	ES FUN	IDAMI	ENTALS	CREDITS	3		
COURS	E CODE		DTE	30751		COURSE CATEGORY			DE	L-T-P-S	3-0-0-0		
Vers	sion		:	1.0		Appr	oval De	tails	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3		
ASSESSM	ENT SCH	HEME											
First Pe Assess		1 .	Second Asse	Periodi ssment		Assi	eminar, gnmen Project		Surprise Test / Quiz	Attendance	ESE		
15% 15% 10% 5% 5%										5%	50%		
Course Ol	Course Objective To provide knowledge to the students about missile system, classification of missiles, aerodynamics of missiles, subsystems and missile trajectory.												
Course O	utcome		. Und inte	erstan gratior erstan	d basi n. d phy	cs of m	nissile p hind gu	hysics uided n	ts will be able to as well as the el nissiles and aero d in missiles.				
CO, PO N	1APPING	G											
со	PO- 1	PO- 2	PO-	PO- 4	PO- 5	PO- 6	PO- 7						
CO-1	3	-	-	2	2	-	-						
CO-2	3	-	-	2	2	-	-						
CO-3	-	-	3	2	2	-	-						
		I	1:	Weakly	/ relate	ed, 2: Mo	oderate	y relate	d and 3: Strongly re	elated			
MODUL	E 1:										(5)		
Basics o	f Missi	le Ph	ysics, Ir	itrodu	ction t	o Guid	ed Mis	siles, (Classification of I	Missiles.	CO-1 BTL-2		
MODUL	E 2:										(5)		
Missile Aerodynamic Configurations, Introduction to Missile System, Interrelationship between various Missile Sub-Systems. CO-2 BTL-2													
MODULE 3: (5)													
	Basic Characteristics of Guided Missile Systems, Missile System Reliability, Range dispersion and CEP Concept, CO-2 BTL-2												

MODULE 4:		(7)
Design, System	Layout and integration of Sub-Systems.	CO-3
		BTL-4
MODULE 5:		(7)
	nsformation, Transformation Matrices. Two, Three and Six DOF otion, Ballistic Missile Trajectory.	CO-3 BTL-3
MODULE6:		(7)
Effect of Curvat	ure of Earth, Rotation of Earth, Variation of Gravity on Missile Trajectory.	CO-3 BTL-2
REFERENCE BOOKS	S	
1.	"Fundamentals of Guided Missiles",by S. R. Mohan. Publisher: Defence Development Organisation.	Re-search and
2.	"Estimation and Prediction of Ballistic Missile Trajectories" by Jeffrey David R. Vaughan. Publisher: RAND (29 May 1996)	y A. Isaac-son,
3.	"Introduction to Modern Algebra and Matrix Theory", by O. Schreid Martin David, Melvin Hausner. Publisher: Dover Publications.	er, E. Sperner,

COURS	E TITLE			ADVA	NCED	CREDITS	3						
COURS	E CODE					COURS	E CATE	GORY	DE	L-T-P-S	3-0-0-0		
Vers	sion		1	1.0		Approval Details			23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3		
ASSESSM	ENT SCH	IEME											
First Pe Assess		S		Periodi ssment		Assi	eminar, gnmen Project	its/	Surprise Test / Quiz	Attendance	ESE		
15% 15% 10% 5%											50%		
Course Objectiv	Course Problems of the defence systems and thermal system design & simulation for the various air, land & naval defence systems utilized under different environmentations.												
Course Outcom	e	1. 2. 3.	Und Carr Und	erstan y out C	d ther CFD sind the	mal de mulatio concep	sign a	nd sim	students will be ulations for syste heat exchanger management re	em design. s, refrigeration			
Prerequis	ites:												
CO, PO N	1APPING	i											
СО	PO-	PO-	PO-	PO-	PO-	PO-	PO-						
CO-1	3	3	3	3	5 3	6	7	_					
	3	<u> </u>	-	3	3	<u> </u>	-	_					
CO-2	3		-	3	3	-	-						
	<u> </u>		1:	Weakly		d. 2: Ma	oderate	lv relate	ed and 3: Strongly re	elated			
MODUL	F 1:			- Tream,	relate	, =:		.,			(7)		
	therma		_	•				_	and simulation	, Heat	CO-1 BTL-3		
MODUL	E 2:										(7)		
Comput	CO-2 Computation fluid dynamics (CFD), Thermal Finite Element Analysis BTL-4												
MODUL	MODULE 3: (6)												
Heat Exc	change	rs for:	Heat	Exchar	nger N	 letworl	√ Desig	gn.			CO-2 BTL-4		
MODUL	E 4:										(5)		

Refrigeration, H	lumidifiers, Air Washers and Cooling Towers.	CO-2							
		BTL-4							
MODULE 5:		(6)							
Thermal manag vehicles etc.)	CO-3 BTL-4								
MODULE 6:	MODULE 6: (5)								
Thermal testing	CO-3								
systems.	BTL-4								
REFERENCE BOOKS	S								
1.	"Fundamentals of Heat and Mass Transfer", by Incropera and Dewitt. Pul Wiley.	olication: John							
2.	"Convective Heat and Mass Transfer", by W M Kays and M E Crawford. Pomos McGraw-Hill publishing Company.	ublisher:							
3.	"Thermal Radiation Heat Transfer" by J Siegel and R Howell. Publisher: El	sevier.							
4.	"Manohar Prasad, Refrigeration and Air Conditioning", 3rd Edition, New International, 2015.	Age							
5.	"Computational Fluid Dynamics – The Basics with Applications", by John Publisher :1st Edition, McGraw Hill, 2012.	D Anderson.							
6.	"Thermal System Design and Simulation", by P.L. Dhar, 1st Edition.								

COURS	E TITLE		NUMER	ICAL N	ЛЕТНО	DDS FO	R SCIENCE &	ENGINEERING	CREDITS	3				
COURS	E CODE					COURS	E CATEGORY	DE	L-T-P-S	3-0-0-0				
Ver	sion		:	1.0		Appr	oval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3				
ASSESSM	ENT SCH	IEME												
First Pe Asses	riodica sment	I	Second Periodical Assessment			Assi	eminar/ gnments/ Project	Surprise Test / Quiz	Attendance	ESE				
15	5%		1	.5%			10%	5%	5%	50%				
Course Objectiv	v e		 To provide knowledge to the students to develop numerical methods aided by technology to solve algebraic equations, calculate derivatives and integrals, curve fitting and optimization techniques. The course will also develop an understanding of the finite element analysis and computational fluid engineering. 											
 Use the numerical techniques (algorithms) to find the solution (appralgebraic equations and system of equations. Fit the data using interpolation technique and spline methods. Use to finite element analysis, interpretation of analysis results. Understanding of computational engineering process. 									roximate)					
CO, PO N	//APPING	3				•								
со	PO- 1	PO 2	- PO- 3	PO-	PO- 5	PO-	PO- 7							
CO-1	3	3	2	-	-	-	-							
CO-2	3	3	-	3	-	-	-							
CO-3	3	3	2	3	-	-	-							
CO-4	3	3	-	-	-	-	-							
		I.	1:	Weakly	y relate	ed, 2: Mo	derately relate	d and 3: Strongly re	elated					
MODUL	E 1:									(5)				
Introduction, solution of non-linear equations, solution of linear systems.														
MODUL	E 2:									(5)				
	ntroduction and polynomial approximation, curve fitting, Numerical applications & ntergradations, numerical optimization.													

MODULE 3:

(5)

Matrices and t stability of solu	ypes of linear systems, direct elimination methods, conditioning and	CO-3 BTL-3
Stubility of 3010	acions.	
MODULE 4:		(7)
	Finite Element Analysis (FEA) simulation software, Pre- and Post-	CO-4
-	ee mesh and Mapped mesh techniques, Quality checks on nodes and ndary conditions.	BTL-4
MODULE 5:	indaily conditions.	(7)
	o computational fluid engineering, Fundamental equations,	CO-4
Computational	Engineering Process.	BTL-3
MODULE6:		(7)
		CO-5
Fluid Simulatio	BTL-4	
REFERENCE BOOK	cs	
1.	"Numerical Methods for Scientific and Engineering Computation", by M. S.R.K. Iyengar. Publisher: New Age International Publishers.	K. Jain and
2.	"Applied Numerical Analysis", by Gerald & Wheatley. Publisher Addison	– Wesley.
3.	"Introductory Methods of Numerical Analysis", by, S.S. Sastry. Publisher: 5th Edition,New Delhi, 2009.	PHI Pvt. Ltd.,
4.	"Applied Numerical Methods Using MATLAB", by W.Y. Yang, W. Cao, T.S. Morris. Publisher: Wiley India Edn., 2007.	Chung and J.
5.	"Numerical Methods for Engineers with Programming and Software App Steven C. Chapra and Ra P. Canale. Publisher: Tata McGraw Hill, 2014 7th	
6.	"Finite Element Procedures", by K.J. Bathe, Prentice Hall of India.	
7.	"Finite Elements in Engineering", by Chandrupatla and Belegundu.	
8.	"Finite element Method", by J.N.Reddy.	

COUR	SE TITI	.E			CON	MUN	ICATIO	OGY	CREDITS	3		
COUR	SE COE	ÞΕ		DTB	0753		COURS	E CATE	GORY	DE	L-T-P-S	3-0-0-0
Ve	rsion			1	L.O		Approval Details			23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSM	ENT SC	НЕМЕ										
First P Asse	eriodi ssmen		Se		Periodi ssment		Seminar/ Assignments/ Project			Surprise Test / Quiz	Attendance	ESE
1	15%			1	5%			10%		5%	5%	50%
Course Objective Course Objective Course Objective To provide knowledge to the students about communication system designal communication of bandwidth and signal-to-noise ratio of a signal, digital communication systems, performance evaluation, explain the concepts of link budget and multiple accesses as it applies to wireless communication.										ommunication		
Course Outcome Upon completion of this course, the students will be able to 1. Understand communication system design methodologies, communication system architecture, analogue & digital modulation techniques. 2. Computation of data rates, bandwidth, BER. 3. To carry out the link budget analysis.									unication			
CO, PO N	/IAPPIN	IG										
со	PO- 1	PO-	-2	PO- 3	PO- 4	PO- 5	PO- 6	PO- 7				
CO-1	3	-		-	2	3	-	-				
CO-2	3	-		-	2	3	-	-				
CO-3	3	-		-	-	3	-	-				
			[1: W	/eakly r	elated,	2: Mod	erately	related	and 3: Strongly re	lated	
MODUL	E 1:					•						(6)
		on Co	mm	unicat	tion Sy	stems	, Basic	s of w	reless	channel behavio	or.	CO-1
												BTL-2
MODUL	.E 2:											(6)
Digital c	lata co	ommı	unic	ation	systen	ıs, dig	ital sig	naling	techni	ques.		CO-1
												BTL-2
MODUL	.E 3:											(5)
Data rat	tes an	d ban	dwi	dth ca	lculati	on in	digital	data c	ommu	nication system	s.	CO-2 BTL-3
MODUL	FΔ·											(7)
		error	and	d BER	calcula	ation.	Modul	ation t	echno	logies (analogue	e & digital).	CO-2
Voice so	-											BTL-3

MODULE 5:		(7)							
Communication information syst	CO-1,2 BTL-3								
MODULE 6:	MODULE 6: (5)								
Link budget calc	CO-3 BTL-3								
REFERENCE BOOKS									
1.	"Fundamentals of communication systems," by Proakis and Salehi. Publ Pearson.	isher:							
2.	"Communication Systems", by Simon Haykin and Michael Moher. Publis	"Communication Systems", by Simon Haykin and Michael Moher. Publisher: Wiley.							
3.	"Modern digital and analog communication systems," by B.P. Lathi and Publisher: Oxford University Press.	Zhi Ding.							

COURS	E TITLE		А	DVAN	CED I	ИЕСНА	NICAL	IEERING	CREDITS	3	
COURS	E CODE					COURS	E CATE	GORY	DE	L-T-P-S	3-0-0-0
Vers	sion		1	0		Appr	oval De	tails	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSM	ENT SCH	IEME			•						
First Pe Assess		I S	econd I Asses	Periodi ssment		Seminar/ Assignments/ Project			Surprise Test / Quiz	Attendance	ESE
15% 15%							10%		5%	5%	50%
Course Objective To provide knowledge to the students about different methods of mechanical system analysis, mechanical simulation soft-ware and use of computational techniques for structural and fluid dynamics.								•			
Course O	Course Outcome 1. Understand mechanical analysis software and carry out mathematical modeling for simulation of phenomena behind the structural and fluid dynamics. 2. Carry out design & finite element analysis of components of systems and subsystems. 3. Carry out the CFD analysis.								nics.		
CO, PO M	1APPING	3									
со	PO-	PO-	PO-	PO-	PO-	PO-	PO-				
CO-1	3	2	3	3	5 3	6	7				
CO-2	3	2	_	3	3	_	_				
CO-3	3	2	_	3	3	-	_				
			1:	Weakly	/ relate	d, 2: Mo	derate	ly relate	ed and 3: Strongly re	elated	
MODUL	E 1:		(5)	•	•	•		•	<u> </u>		
Introduc		tools		echani	ical de	esign &	analys	sis			CO-1
											BTL-2
MODUL	E 2:	(7)									
Stress e	nginee	ring –	theory	/ & sin	nulatio	on, me	chanic	s of sol	ids		CO-1 BTL-2
MODUL	E 3:										(7)
Finite el	ement	meth	ods in	struct	ural d	ynamic	s, Stru	ctural i	integrity		CO-2
											BTL-3
MODUL											(5)
Fluid me	echanic	CS									CO-2
MODUL	F 5:										BTL-3 (7)
	_ •										(*)

Communitational	fluid dunancias	CO-3						
Computational	nuid dynamics	BTL-3						
MODULE 6:		(5)						
Component design, Applied materials and corrosion CO-BTL-								
REFERENCE BOOKS								
1.	"An Introduction to Computational Fluid Dynamics: The Finite Volume Method "by H. Versteeg. Publisher: Pearson.							
2.	"Computational Fluid Dynamics the Basics with Applications", by Joh Publisher: McGraw Hill Education (1 July 2017)	n D. Ander Jr.						
3.	"Fluid Mechanics: Volume 2: Foundations and Applications of Mechanic iisc)" by C. S. Jog. Publisher: Cambridge University Press.	cs (Cam-bridge-						
4.	Fundamentals of Machine Component Design", by Robert C. Juvinall, Ku Publisher: John Wiley & Sons	rt M. Marshek.						

SEMESTER I - ELECTIVE - 2 COURSES

COURS	E TITLE	Α	UTONO	OMY A	ND N	AVIGA	TION T	ECHNO	DLOGY	CREDITS	3
COURS	E CODE		DTB	0752		COURS	SE CATE	GORY	DE	L-T-P-S	3-0-0-0
Vers	sion		1	1.0		Appr	oval Det	ails	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSM	ASSESSMENT SCHEME										
First Periodical Second Per Assessment Assessm					Seminar/ Assignments/ Project			Surprise Test / Quiz	Attendance	ESE	
15	5%		1	5%			10%		5%	5%	50%
Course Objective To provide knowledge to the students about technology of modern navigati systems, particularly satellite-based systems, UAV guidance systems, GPS, SLAM.								_			
Course O	Course Outcome Upon completion of this course, the students will be able to Describe the basic principle of operation of a global navigation satellite system Understand the navigation systems and derive the navigation equations. Carry out path planning the UGV / UAV. Solve the equations for calculating a position estimate from a given satellite constellation.							tions.			
CO, PO M	CO, PO MAPPING										
со	PO- 1	PO- 2	PO-	PO-	PO- 5	PO-	PO- 7				
CO-1	3	-	2	-	3	-	-				
CO-2	3	-	3	-	3	-	-				
CO-3	3	-	2	-	3	-	-				
CO-4	3	-	-	-	3	-	-				
			1:	Weakly	/ relate	ed, 2: Mo	oderatel	y relate	d and 3: Strongly re	elated	
MODUL	E 1:										(6)
Introduc guidance			_	_		•		uidanc	e approaches: co	onventional	CO-1 BTL-3
MODUL	E 2:										(7)
				_			٠.		ce- and coordina gon the surface	•	CO-2 BTL-3
MODUL	E 3:										(7)
Geomet for UGV	_				ng and	d follov	ving, ar	nd opti	mal guidance; p	ath planning	CO-3 BTL-3

MODULE 4:		(5)						
Navigation app System (GPS)	roaches: navigation systems, Understanding the Global Positioning	CO-1,3 BTL-3						
MODULE 5:		(6)						
GNSS (Global N	CO-3 BTL-3							
MODULE 6: (5								
SLAM (Simultar avoidance.	CO-4 BTL-3							
REFERENCE BOOK	S							
1.	"Global Navigation Satellite Systems: Insights Into GPS", by Bhatta, B., Global Compass, and Others. Publisher: BS Publications, New Delhi 2010.	onass, Galileo,						
2.	"Global Positioning Systems, Inertial Navigation, and Integration", by Gre Weill, L. R., Andrews, A. P., Publisher: John Wiley & Sons, New York, 2006							
3.	"GNSS – Global Navigation Satellite Systems", by Verlag Wien. Hofmann- Lichtenegger, H., Wasle, E. Publisher: Springer 2008.	Wellenhof, B.,						
4.	"Global Positioning System Theory and Practice", Hofmann-Wellenhof, B Lichtenegger, H., Verlag Wien, Collins, J. Publisher: Springer 2001.	.,						

COURSE TITLE	OPTIN	/IIZATIO	N THE	ORY &	APPLICA	ATION	IS	CREDITS	3	
COURSE CODE				COURS	E CATEG	ORY	DE	L-T-P-S	3-0-0-0	
Version		1.0		Appr	oval Deta	ails	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT SCH	EME									
First Periodical Assessment		nd Period sessmen		Seminar/ Assignments/ Project			Surprise Test / Quiz	Attendance	ESE	
15%		15%			10%		5%	5%	50%	
 Course Objective To cover the concepts of optimization methods and algorithms developed for solving various types of optimization problems. Apply the mathematical results and numerical techniques of optimization theoretical and applied research areas. 										
Course Outcome	1. U production of the product	 Upon completion of this course, the students will be able to Understand mathematical modeling and the formulation of optimization problems. Create programs based on different optimization algorithms using IT tools, such as MATLAB etc. Understand theory about linear programming, integer programming, and stochastic programming Understand the process of finalizing design of engineering systems by applying the numerical optimization. 								
Prerequisites:										
CO, PO MAPPING										
CO PO-	PO- PO)- PO-	PO-	PO-	PO-					
1	2 3	4	5	6	7					
CO-1 3		-	1	-	-					
CO-2 3	- 2	-	3	-	-					
CO-3 3	- 2	-	3	-	-					
CO-4 3		-	-	-	-					
		1: Weakl	y relate	ed, 2: Mo	oderately	relate	d and 3: Strongly r	elated		
MODULE 1:									(
Introduction to	optimizat	ion, class	ical op	timizat	ion tech	nique			CO-1	
									BTL-1	

 $Linear\ programming\ \&non-linear\ programming\ and\ dimensional\ minimization\ methods.$

BTL-2

MODULE 3:		(7)								
Non coordinatio	n optimization techniques, coordinated optimization techniques, gramming.	CO-2 BTL-3								
MODULE 4:	MODULE 4: (6)									
Dynamic programming, integer programming, stochastic programming.										
MODULE 5:	,	(5)								
Solution of a variety of design problems in mechanical engineering, using numerical optimization techniques.										
MODULE6: (5)										
Additional Topic	cs: multi-objective, optimization, game theory, optical control theory.	CO-4 BTL-2								
REFERENCE BOOKS	5									
1.	"Numerical Optimization", by Jorge Nocedal and Stephen J.Write. Publish 2006.	ner: Springer,								
2.	"Practical methods of Optimization" by R.Fletcher. Publisher: Wiley, 198	7.								
3.	"Iterative method for optimization" by C. T. Kelley. Publisher: SIAM, 1999	Э.								
4.	"Introduction to Nonlinear Optimization:Theory, Algorithm, and Application MATLAB. MOS-SIAM Series on Optimization", by Amir Becker.	ionwith								
5.	"Dynamic Programming and Optimal Control (Volumel) " by Dimitri P. Be Publisher: Athena Scientic, 2005.	rtsekas.								
6.	Optimization Theory and Applications", by SS Rao.									

COURS	E TITLE	M	ILITAR	Y ELEC	CTRON	NICS SY	STEM	ENGIN	EERING	CREDITS	3
COURS	E CODE					COURS	SE CATE	GORY	DE	L-T-P-S	3-0-0-0
Vers	sion		1	1.0		Approval Details			23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSM	ENT SCH	IEME									
First Pe Assess		I S	Second Periodical Assessment			Assi	eminar gnmen Project	its/	Surprise Test / Quiz	Attendance	ESE
15	15% 15% 10% 5% 5%							5%	50%		
Course Ol	ojective	re	quiren	nent fo	or mili	tary er	vironr	nent, g	about the learni eneration of sys s on the electron	tem requireme	•
Upon completion of this course, the students will be able to 1. Understand the military electronics systems. 2. Generate system design requirements as per mission needs & operational requirements. 3. To create digital simulation models. 4. Understand the limitations of the COTS available electronics systems. 5. Evaluate the radiation effects on the performance of electronics systems.									tems.		
CO, PO M	APPING	i									
со	PO- 1	PO- 2	PO-	PO-	PO- 5	PO-	PO-				
CO-1	1	1	1	1	1	1	1				
CO-2	3	-	-	2	-	-	-	-			
CO-3	3	-	2	-	-	-	-	-			
CO-4 CO-5	3	-	-	3	-	- _	-				
	3				L	1 2 24					
MODIII	F 4		1:	vveakiy	y relate	:a, 2: IVI	oaerate	iy relate	d and 3: Strongly re	eiated	/=\
MODUL		ا علم د		A 10 - 1				التعميلة	ada fantle e de 1		(5)
integrat				_	_		pts an	a metr	ods for the desi	gn and	CO-1 BTL-2
MODUL	E 2:										(5)
Familiar defense	•		system	s engi	neerir	ng proc	ess th	rough o	ase studies of re	epresentative	CO-2 BTL-2
MODUL		<u> </u>									(6)
	ntroduction to methods used for determination of system requirements from mission cO-2 needs and operational requirements.										

MODULE 4: (7)									
Digital simulation	CO-3 BTL-4								
MODULE 5: (7)									
Limitations of c electrostatic br	CO-3 BTL-3								
MODULE 6: (6)									
Radiation effect military integra	CO-4 BTL-3								
REFERENCE BOOKS									
1.	"Introduction to Electronic Defense Systems", by Neri Filippo. Publisher: Artech House Publishers.								
2.	"Military Handbook of Electronic Reliability design", by US Department of Defence.								
3.	"Defence Electronics Standards and Quality Assurance", by Ray Tricker. Pub-: Elsevier								
4.	"Handbook of Defence Electronics and Optronics: Fundamentals, Technologies and Systems", by Anil K. Maini. Publisher: John Wiley & Sons Ltd								
5.	"Digital Simulation Methods", by M.G. Hartley. Publisher: P. Peregrinus Ltd								
6.	6. "Analysis and Simulation of Noise in Nonlinear Electronic Circuits and Systems", By Alper Demir. Publisher: Springer.								

COURS	E TITLE	S	SYSTEM ENGINEERING & ANALYSIS							CREDITS	3	
COURSE CODE						COURSE CATEGORY			DE	L-T-P-S	3-0-0-0	
Version			1.0			Approval Details			23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT SCHEME												
First Periodical Assessment		1 5	Second Periodical Assessment			Seminar/ Assignments/ Project			Surprise Test / Quiz	Attendance	ESE	
15%			15%			10%			5%	5%	50%	
Course Ol	bjective	To provide knowledge to the students about the military systems engineering, system requirements, basics of system design, architecture, operational requirements, system reliability and management.										
Course O	Course Outcome Upon completion of this course, the students will be able to 1. Understand the system design requirements, architecture, functional requirements 2. Generate the system requirements documents as per the requirement analysis. 3. Understand the system reliability, maintainability, usability issues. 4. Carry out the system reliability analysis.											
CO, PO MAPPING												
со	PO-	PO-	PO-	PO-	PO-	PO-	PO-					
	1	2	3	4	5	6	7					
CO-1	3	-	-	-	-	-	-					
CO-2	3	3	-	-	-	-	-					
CO-3	3	3	2	-	-	-	-					
CO-4	3	3	-	-	4	-	-					
			1:	Weakly	y relate	ed, 2: Mo	oderate	ly relate	d and 3: Strongly re	elated		
MODUL	E 1:										(5)	
Fundamentals of systems engineering and system architecting of weapon system, system engineering. standards 15288, requirements analysis, functional analysis and allocation, preliminary system architecture.												
MODUL			, , ,								(5)	
1	Systems analysis, system design, and the basics of test and evaluation, Introduction to combat systems, CO-2 BTL-3											
MODULE 3: (6)												
System	System development phases (Conceiving, Designing, Implementing, and Operating), BTL-											
MODULE 4: (7)												

Techniques of system design and assessment for operational feasibility, including co-3								
reliability, maintainability, usability (including human factors and human performance). BTL-3								
MODULE 5:		(7)						
Supportability	and producibility, System cost assessment and effectiveness estimation.	CO-3						
	and productionity, system cost assessment and effectiveness estimation.	BTL-3						
MODULE 6:		(6)						
Reliability analy	sis and management (basic tools and methods of reliability for							
developing com	plex systems including electronic components, mechanical components,	CO-4						
and software), r	redundancy, graceful degradation, fault tolerance, MTBF.	BTL-3						
REFERENCE BOOKS								
1.	"The Engineering Design of Systems: Models and Methods", by Buede D.	M.2.						
<u> </u>	Publisher: John Wiley & Sons Inc.							
2.	"Systems engineering fundamentals", by Defense Acquisition University I	Pressfort						
	Belvoir, Virginia							
3.	"System Analysis Design and Development", by Charles S. Wasson. Publis	her : Wiley						
	Series in System Engineering and Management.							
4.	"Principles of Planned Maintenance", by Clifton R H. Publisher: McGraw I	Hill, New York.						
5.	"An introduction to Reliability and Maintainability Engineering", by Ebling	g CE. Tata Mc						
J.	Graw Hill.							
6.	"Reliability Engineering", by Srinath L S. Publisher: Affiliated East-West P	ress Limited,						
0.	New Delhi, 2002.							
7.	"Engineering Maintainability", by Dhillon B S. Publisher: Prentice Hall of	India.						

SEMESTER – II (AEROSPACE TECHNOLOGY)

COURSE TIT	TLE	AEROSI SIMULA		EM CONFIGURAT	TION, D	ESIGN &	CREDITS	4
COURSE CO	DDE			COURSE CATEGOR	Υ	BS	L-T-P-S	4-0-0-0
Version			1.0	Approval Details		3 ACM, .02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEM	IE						
First Period	lical	Second	l Periodical	Seminar/	Surp	rise Test /	Attendance	ESE
Assessme		_	essment	Assignments/		Quiz		
				Project				
15%			15%	10%		5%	5%	50%
Course Object	tive	The ma	in objective	of the course is	to provid	de knowled	dge to the stud	ents about the
			-	ues of aerospace	•		_	
		-	-	will also learn ab	•	•		_
		•	•	ation of aircraft ar		_	•	, ,
Course Outco	me	•		of this course, the stu		· ·		
				e concept of mi			its design requ	uirements and
			cess.	•	,		0 1	
		•		ospace vehicle ar	nd articu	ılate its b	enefits in writt	en and verbal
		forr	_	opace remote a.			eneries in write	en and versa
				e methods for a	ro-plast	ic analysis	computationa	l fluid analysis
				n aero-dynamics.	.io ciast	ic arranysis,	, computationa	i ilala allalysis
				•	nd +a a	ir oir to	around wooner	s system IIAV
				e air to air, grou	iliu to a	ir, air to g	ground weapor	i system, uav
CO, PO Mapp	·	ШО	unted GW a	na ucavs.				
СО, РО Марр	PO-1	1	PO-2	PO-3 PO)-4	PO-5	PO-6	PO-7
CO-1	3		1	3 -	/- 4	-	2	2
CO-2	3		3	3 2		2	3	2
CO-3	3		1	- -		-	-	-
C0-4	3		1			-	-	-
MODULE 1:								(6)
Introduction	n (aero	o-elastic	phenomena	and design requi	rements), Introduc	tion to	CO-1
missiles & s	ystem	s, Desigr	n process.					BTL-3
MODULE 2:								(6)
	•			d aerodynamic stif		atic aero-e	elasticity:	CO-2
torsional divergence, Structural vibration and modal analysis.							BTL-3	
MODULE 3: (7)								(7)
The say that the sadd of the sound and sound as the same says and							CO-2	
important design parameters, Methods for aero-elastic analysis, Computational fluid						BTL-3		
	dvanc	es in aer	o dynamics	(Hypersonic Flow	s and Ae	rodynamic	Heating).	
MODULE 4:								(7)
Aircraft per	forma	nce (crui	ising, climb,	descent, takeoff,	landing,	maneuver,	flight path).	CO-3
								BTL-3

MODULE 5:		(7)					
System's stability & control, aerodynamics control, Introduction to dynamic stability,							
first and second	order responses, Equations of motion and modal characteristics.	BTL-3					
MODULE6:		(7)					
Introduction to	o air to air, ground to air, air to ground weapon systems, UAV mounted	CO-4					
GW and UCAV	S.	BTL-4					
REFERENCE BOOKS	3						
1.	"Aircraft design: a conceptual approach", by D. Raymer						
2.	"Flight Dynamics Principles", by Michael V. Cook						
3.	"IntroductiontoStructuralDynamicsandAeroelasticity",byDeweyH.Hodge	s,G.AlvinPierce					
4.	4. "Airplane Aerodynamics and Performance", by Chuan Tau Edward Lan						
5. "Fundamentals of Structural Dynamics", by Roy R. Craig Jr., Andrew J. Kurdila.							
6.	Literature / books suggested by respective course Lecturers.						

COURSE TITLE	GUIDA	GUIDANCE & CONTROL CREDITS						
COURSE CODE			COURSE CATEGORY	PC	L-T-P-S	4-0-0-0		
Version		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3		
ASSESSMENT SCHEME								
First Periodica Assessment		d Periodical essment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE		
15%		15%	10%	5%	5%	50%		
Course Objective	e fundan	nental of sa	e of the course is to stellite navigation, SS integration and m	navigation math	nematics, princ			
Course Outcome	1. Uno pos 2. Uno 3. Dev	derstand th sitioning. derstand var velop mathe	of this course, the student e principles of sat ious aspects of design matical model of mis ation for aircraft/mis	tellite navigation ning a navigation sile dynamics.	n system.			
CO, PO Mapping	3							
со	PO-1	PO-2	PO-3 PO-4	PO-5	PO-6	PO-7		
CO-1	3	-		-	-	-		
CO-2	3	-	2 -	2	-	-		
	3	2	3 -	3	2	2		
	3	3	3 3	3	2	3		
MODULE 1:						(6)		
Introduction t	o Navigatio	n, Navigatior	Mathematics.			CO-1 BTL-3		
MODULE 2:						(7)		
GNSS: fundam Inertial Naviga	ation, Advar	nced satellite	ellites: Fundamentals Navigation, Principlonge Positioning, Sate	es of radio Positi	oning,	CO-2 BTL-3		
MODULE 3:						(6)		
	Errors and Geometry, Dead Reckoning, Attitude, and Height Measurement, Feature matching, INS/GNSS Integration. CO-2 BTL-3							
MODULE 4: (6)								
Missile Contro Control.	Missile Control Methods: Aerodynamic and Thrust Vector Control, Polar and Cartesian Co-3 BTL-3							
MODULE 5:						(8)		
Mathematical Roll Rate Stab	_	of Missile Dyr	namics; Missile Actua	ators and Sensor	s. Roll and	CO-3 BTL-3		
MODULE6:						(7)		

Design and Ar MATLAB	Design and Analysis of Lateral Autopilots, 6 DOF simulation for aircraft/missile using MATLAB						
REFERENCE BOOK	S						
1.	"ModernInertialTechnologyNavigation,Guidance,andControl",byAnthon 2012. Publisher:Springer New York.	yLawrence					
2.	"The Global Positioning System & Inertial Navigation", by Jay Farrell. Published Education (16 December 1998).	er : McGraw-Hill					
3.	"MATLAB for Engineering Applications", by William Palm. Publisher: McGraw-H4th edition (February 6, 2018).	Iill Education;					
4.	"Global Navigation Satellite Systems, Inertial Navigation, and Integration", by Andrews, A. P., Bartone, C. G. (2013). Publisher: John Wiley and Sons Inc.	y Grewal, M. S.,					
5.	"Principles of GNSS, inertial and multi-sensor integrated navigation systems" D. Publisher: ArtechHouse.	, by Groves, P.					
6.	"Optimal State Estimation", by Kalman, H Infinity.						
7.	"Nonlinear Approaches", by Simon, D. (2006). Publisher: Wiley-Interscienc	e					
8.	Literature / books suggested by respective course Lecturers.						

COURSE TIT	LE	AEROSI	AEROSPACE PROPULSION CREDITS						
COURSE CO	DE			COURSE CATEGOR	Υ	PC	L-T-P-S	4-0-0-0	
Version			1.0	Approval Details		23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT S	ASSESSMENT SCHEME								
First Period Assessme			l Periodical essment	Seminar/ Assignments/ Project		Surprise Test / Quiz	Attendance	ESE	
15%			15%	10%		5%	5%	50%	
Course Object	ive	differer systems	nt criteria fo	e of the course is or the selection a f propulsion syste system.	and	evaluation of	different types	of propulsion	
Course Outcor	me	 Kno syst Uno Uno 	owledge abo tem. derstanding	of this course, the stud out thermodynam of Rocket motor d of different desig	nics Iesig	and fluid dyn gn		·	
CO, PO Mappi	ng								
со	PO-1		PO-2	PO-3 PC	D-4	PO-5	PO-6	PO-7	
CO-1	3		2	1 -		-	-	-	
CO-2	3		2	1 -		-	-	-	
CO-3	3		2	1 -			-	- (7)	
MODULE 1:	n 0. m	odo of o	noration of	various propulsior	0.614	stoms basis		(7) CO-1	
thermodyna			•	various propuisioi	пэу	sterris, basis		BTL-3	
MODULE 2:		<u> </u>	7,1141111001					(8)	
Rocket moto		_	•	urbine Engine des	ign,	GT engine effic	iency, GT	CO-2 BTL-3	
MODULE 3:								(6)	
Aircraft perf	orma	nce, jet (engine perfo	rmance.				CO-2 BTL-3	
MODULE 4: (7)									
_	Jet engine control (compressor performance, axial turbine performance, Fuel systems & co-3 pumps, airframe fuel systems, hydro-mechanical fuel metering, Electronics engine control) CO-3 BTL-3								
MODULE 5:								(6)	
System integ	System integration CO-3 BTL-3								
MODULE6:								(6)	

Computational fluid dynamics (flow modelling strategies, physical modelling, finite difference equations, etc.)						
REFERENCE BOOKS						
1.	"Rocket Propulsion Elements", by George Paul Sutton and Oscar Biblarz. Pub-lis Wiley & Sons	sher: John				
2.	"Modern Engineering for Design of Liquid-Propellant Rocket Engines: Progre Astronautics and Aeronautics Series" by Dieter K. Huzel, David H. Huang.	essin				
3.	"An Introduction to Computational Fluid Dynamics: The Finite Volume Method Versteeg. Publisher: Pearson; 2nd edition.	d" by H.				
4. "Computational Fluid Dynamics the Basics with Applications" by John D. An-derson, Jr. Publisher: McGraw Hill Education (1 July 2017)						
5.	"Fluid Mechanics: Volume 2: Foundations and Applications of Mechanics", by C Publisher: Cambridge University Press; 3rd edition.	C.S.Jog.				

COURSE	TITLE	AEROSPACE SYSTEM	AEROSPACE SYSTEM CONFIGURATION, DESIGN & CREDITS SIMULATION LAB								
COURSE	CODE		COURSE CATEGORY	DE	L-T-P-S	0-0-2-0					
Versi	Version 1.0 Approval Details 23 ACM, 06.02.2021					BTL-3					
LIST OF EX	PERIMEN [*]	rs									
1.	1. Lab experiments will be added in consultation with DRDO labs considering the available facilities.										

COURSE	TITLE	GUIDA	CREDITS	2			
COURSE	CODE		COURSE CATEGORY	DE	L-T-P-S	0-0-2-0	
Versi	on	1.0	Approval Details 23 ACM, 06.02.2021		LEARNING LEVEL	BTL-3	
LIST OF EXI	PERIMENT	rs					
1.							

SEMESTER- II (COMMUNICATION SYSTEMS & SENSORS)

COURSE CODE DTD3703 COURSE CATEGORY DE L-T.P-S 4-0-0	COURSE TITLE		Radar	Technologie	s			CREDITS	3
ASSESSMENT SCHEME First Periodical Assessment	COURSE CODE		DTD37	03	COURSE CATEGO	ORY	DE	L-T-P-S	4-0-0-0
Second Periodical Assessment Assessment Assignments Assignments Project Assignments Quiz Attendance ESE	Version	/ersion 1.0 Δnnroval Details							BTL-3
Assessment	ASSESSMENT S	SCHEN	1E						
The main objective of the course is to provide knowledge to the students about learning on the radar systems, radar parameters, radar environment, theory of detection and design of radar elements, different types of radars & their application. Upon completion of this course, the students will be able to 1. Understand the design of radar systems, solve range equations. 2. Apply appropriate mathematical and computer models relevant to radar systems to calculate system performance, and assess the limitations of particular cases 3. Understand the major components of a modern radar system 4. Learn basic radar signal processing techniques. 5. Understand advanced radar techniques. 6. Know the major functions and applications of a modern radar systems. CO, PO Mapping CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2 1 1 - 1 - 1		dical			Assignments/		•	Attendance	ESE
Learning on the radar systems, radar parameters, radar environment, theory of detection and design of radar elements, different types of radars & their application. Upon completion of this course, the students will be able to	15%		15%		10%		5%	5%	50%
1. Understand the design of radar systems, solve range equations. 2. Apply appropriate mathematical and computer models relevant to radar systems to calculate system performance, and assess the limitations of particular cases 3. Understand the major components of a modern radar system 4. Learn basic radar signal processing techniques. 5. Understand advanced radar techniques. 6. Know the major functions and applications of a modern radar systems. CO, PO Mapping CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2 1 - 1	Course Object	ive	learnin	g on the ra	adar systems,	radar	parameters, ra	ıdar environm	ent, theory of
CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2 1 - 1 - - - CO-2 3 2 1 - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - - -	 Understand the design of radar systems, solve range equations. Apply appropriate mathematical and computer models releasystems to calculate system performance, and assess the particular cases Understand the major components of a modern radar system Learn basic radar signal processing techniques. Understand advanced radar techniques. 				nge equations. er models rele nd assess the radar system	limitations of			
CO-1 3 2 1 - 1	CO, PO Mappi	ng							
CO-2 3 2 1	со	PO-	1	PO-2	PO-3	PO-4	PO-5	PO-6	PO-7
CO-3	CO-1	3		2	1	-	1	-	-
CO-4 3	CO-2	3		2	1	-	-	-	-
CO-5 3 2 1				2	1	-	-	-	-
CO-6 3 2 1				_					
MODULE 1: Introduction to RADAR, Radar parameters/definitions, radar equations. MODULE 2: Radar cross section (RCS) & Theory of detection, Clutter. MODULE 3: CO-1 BTL-3 CO-2 BTL-3 CO-2 CO-2 CO-2 CO-2 CO-2 BTL-3							-	-	-
Introduction to RADAR, Radar parameters/definitions, radar equations. MODULE 2: Radar cross section (RCS) & Theory of detection, Clutter. MODULE 3: CO-1 BTL-3 CO-2 BTL-3 CO-2 CO-2 BTL-3 CO-2 CO-2 CO-2 BTL-3		3		2	1	-	-	-	- (6)
Radar cross section (RCS) & Theory of detection, Clutter. MODULE 3: CO-2 BTL-3 (6) CO-2 CO-2 CO-2		to R	ADAR, R	adar parame	eters/definition	s, rada	ar equations.		CO-1
Radar cross section (RCS) & Theory of detection, Clutter. MODULE 3: CO-2 BTL-3 (6) CO-2 CO-2 CO-2	MODULE 2:								(6)
Atmospheric propagation, Surveillance and Tracking Radar, Radar Designs	Radar cross section (RCS) & Theory of detection Clutter								
Atmospheric propagation, Surveillance and Tracking Radar, Radar Designs	MODULE 3:								(6)
	Atmospheric	c pro _l	pagation	, Surveillanc	e and Tracking	Radar	, Radar Designs.		
MODULE 4: (7)	MODULE 4:								(7)

Radar elements switch & Radar	CO-3 BTL-3						
MODULE 5:		(7)					
micro-doppler p	and networks, Radar signal processing chain, Pulse compression and processing, Tracking algorithms	CO-3 BTL-3					
MODULE 6:		(8)					
•	adar, Data processing for phased array radar, Airborne radar, imaging ic aperture radar, inverse synthic aperture radar, adaptive array	CO-4 BTL-3					
REFERENCE BOOKS							
1.	"Introduction to Radar Systems", by M.I. Skolnik. Publisher: Tata Mcgra 2001.	aw hill edition,					
2.	"Radar Systems Analysis and Design using MATLAB", by B.R.Mahafza. Press, 2013.	Publisher CRC					
3.	"Monopulse Principles and Techniques", by S.M.sherman and D.K.Bart Artech house, 2011	on. Publisher :					
4.	"Fundamentals of Radar Signal Processing", by M.A.Richards. Publishe hill.	r Tata Mcgraw					
"Ground Penetrating Radar: Theory and Applications",by, Editor: H.M. Jolt. Publisher: Elsevier.							
6. "Radar, Sonar And Navigation Engineering", by K. K Sharma. Publisher: S K Kataria8 Sons.							
7. Literature / books suggested by respective course Lecturers.							

COLUDES TITLE		Digital & satellite Communication and						NEDITC .	2	
COURSE TITLE		Navigation from Space					CF	REDITS	3	
COURSE CODE DTD3704				COURSE CATEGO	DRY	DE	L-	T-P-S	4-0-0-0	
Version		1.0		Approval Details	5	23 AC		EARNING EVEL	BTL-3	
ASSESSMENT S	SCHEN	ΛE								
First Period Assessment	dical	Second Assessm	Periodical nent	Seminar/ Assignments/ Project		Surprise Test Quiz	t / A	ttendance	ESE	
15%		15%		10%		5%	59	%	50%	
Course Objecti	ive	analogu commu	ue and digi	of the course tal communic ystems, modu es.	ation	systems, o	ptical	communic	ation, s	atellite
Course Outcon	me	1. 2. 3. 4.	Understand Evaluate the Design the a Understand	this course, the the communical performance of nalogue and di and analyse the the different ty	ation to of com gital c e sign	echniques nmunication s ommunication al transmission	systen on syst on effe	ns tems ects		
CO, PO Mappi	ng	l								
СО	PO-	1	PO-2	PO-3	PO-4	PO-5		PO-6	PO-7	7
CO-1	3		2	-	-	-		-	-	
CO-2	3		3	3	3	3		2	3	
CO-3	3		2	3	2	2		2	2	
CO-4 CO-5	3		2	-	2	2		1	-	
MODULE 1:	<u> </u>				-	-				(6)
	a cor	mmunica	tions system	and their relat	tionsh	ip to system	perfor	mance.	CO-1 BTL-3	(0)
MODULE 2:									L	(7)
•	Free space optical communication, Fiber optics communication, Wireless/cellular communications.						CO-2 BTL-3			
MODULE 3:	MODULE 3: (7)									
Fundamental concepts such as current/voltage relationships, time and frequency domains, power spectral density, random signals, Communications system components and functions, analog and digital communications systems,										
MODULE 4:										(7)
Modulation transmission and reception; baseband and passband digital modulation; system, noise, transmission lines, waveguides and antennas, FEC techniques for mitigating channel errors. CO-3 BTL-3										

MODULE 5:		(7)				
and RF system	ffects on signal transmission; end-to-end path calculations for wire/coax, as including terrestrial ground links and satellite communications, Spread ecpt of frequency hoping.	CO-3 BTL-3				
MODULE 6:		(6)				
Navigation te Galileo	chniques from space regarding functioning of GPS, GLONASS, IRNSS &	CO-4 BTL-3				
REFERENCE BOO	KS	I				
1.	"Satellite communication", by T. Pratt, C. W. Bostian, J. E.Allnut. Publish and sons	er: John Willey				
2.	"Satellite Communications Systems: systems, techniques and techn Maral, M. Bousquet, Z. Sun. Publisher:John Willy and sons	nology", by G.				
3.	"Digital Communications: Fundamentals and Applications", B. Sklar . Prentice-Hall, Inc					
4.	4. "Understanding of GPS/GNSS: Principles and Applications", by E. Kaplan and C. Hegarty Publisher: Artech House Publishers.					
5.	Literature / books suggested by respective course Lecturers.					

COURSE TITLE		Tactical battlefield Communication & Electronic Warfare					CREDITS	3	
COURSE CODE	<u> </u>	DTD3705		COURSE CATEGO	DRY DE		L-T-P-S	4-0-0-0	
Version 1.0				Approval Details	23	ACM,	LEARNING LEVEL	BTL-3	
ASSESSMENT	SCHEN	1E			<u> </u>			1	
First Periodical Assessment		Second Assessm	Periodical nent	Seminar/ Assignments/ Project	Surp Quiz	rise Test /	Attendance	ESE	
15%		15%		10%	5%		5%	50%	
Course Object	tive	techniq against links, co and jam	ues for sett ground to ell phone lin nming perfor		pt and jam communion control li	ming links cation signa nks, techni	for Electronic als, UAV comi ques for pred	Warfare mand and	(EW) data
		1.	Understand	this course, the nature of ta	actical batt	lefield com			
Course Outco	me	3. 4.	Calculate th tactical com links.	requirements e requirement e requirement im. Signals incl	for interce s for emit luding wea	ption of tac ter location pon contro	n, intercept a ol link, UAV lii	nd jammir	_
CO, PO Mappi		3. 4.	Calculate the Calculate the tactical come links.	e requirements e requirement im. Signals incl	for interce s for emit luding wea	ption of tac ter location pon contro	n, intercept a ol link, UAV lii	nd jammir	_
		3. 4. 5.	Calculate the Calculate the tactical come links.	e requirements e requirement im. Signals incl	for interce s for emit luding wea	ption of tac ter location pon contro	n, intercept a ol link, UAV lii	nd jammir	_
CO, PO Mappi CO	ing	3. 4. 5.	Calculate the Calculate the tactical com links. Use various	e requirements e requirement im. Signals incl tools to perforr	for interce s for emit luding wea m electroni	ption of tac ter location pon contro c warfare c	n, intercept a ol link, UAV lii alculations	nd jammii nks, Cell p	_
CO, PO Mappi CO CO-1	ing PO-	3. 4. 5.	Calculate the Calculate the tactical comlinks. Use various	e requirements e requirement im. Signals incl tools to perforr	for interce s for emit luding wea m electroni	ption of tac ter location pon contro c warfare c	n, intercept a ol link, UAV lint alculations	nd jammii nks, Cell p	_
CO, PO Mappi CO CO-1 CO-2	PO-	3. 4. 5.	Calculate the Calculate the tactical comlinks. Use various PO-2 2	e requirements e requirement im. Signals incl tools to perforr PO-3 -	for interces for emits for emits wear for emits wear for emits wear for electronic for electroni	ption of tacter location pon control c	n, intercept a old link, UAV lint alculations PO-6 -	nd jammii nks, Cell p PO-7	_
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4	PO-	3. 4. 5.	Calculate the Calculate the Calculate the tactical combines. Use various PO-2 2 3 3 2	e requirements e requirement im. Signals incl tools to perforr PO-3	for interces for emit luding wear melectroni PO-4 - 2 2	ption of tacter location pon control c	PO-6 - 2 2 2	nd jammii nks, Cell p PO-7	_
CO, PO Mappi CO CO-1 CO-2 CO-3	ing PO-:	3. 4. 5.	Calculate the Calculate the tactical comlinks. Use various PO-2 2 3 3	e requirements e requirement im. Signals incl tools to perforr PO-3 3	for interces for emit luding wear melectroni PO-4 - 2	ption of tacter location pon control c	n, intercept a ol link, UAV link alculations PO-6 - 2 2	PO-7 - 3 1	_
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4	ing PO-1	3. 4. 5.	Calculate the Calculate the Calculate the tactical combines. Use various PO-2 2 3 3 2	e requirements e requirement im. Signals incl tools to perforr PO-3 3 2	for interces for emit luding wear melectroni PO-4 - 2 2	ption of tacter location pon control c	PO-6 - 2 2 2	PO-7 - 3 1	_
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1:	PO- 3 3 3 3 3	3. 4. 5.	Calculate the Calculate the Calculate the tactical comlinks. Use various PO-2 2 3 3 2 2	e requirements e requirement im. Signals incl tools to perforr PO-3 3 2	ror interces for emit luding wear melectroni PO-4 - 2 2 2 2	ption of tacter location pon control c	PO-6 - 2 2 2 2	PO-7 - 3 1	hone
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1:	PO- 3 3 3 3 3	3. 4. 5.	Calculate the Calculate the Calculate the tactical comlinks. Use various PO-2 2 3 3 2 2	e requirements e requirement im. Signals incl tools to perforr PO-3 3 2 2	ror interces for emit luding wear melectroni PO-4 - 2 2 2 2	ption of tacter location pon control c	PO-6 - 2 2 2 2	PO-7 - 3 1 1 1 CO-1	hone
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1: Radiometry	PO- 3 3 3 3 3	3. 4. 5.	Calculate the Calculate the Calculate the Calculate the tactical complex of the Calculation of the Calculati	e requirements e requirement im. Signals incl tools to perforr PO-3 3 2 2	ror interces for emit luding wear melectroni PO-4 - 2 2 2 2 ion, atmos	ption of tacter location pon control c	PO-6 - 2 2 2 2 2	PO-7 - 3 1 1 1 CO-1	hone (6)
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1: Radiometry	PO- 3 3 3 3 3 and p	3. 4. 5.	Calculate the Calculate the Calculate the Calculate the tactical complex of the Calculation of the Calculati	PO-3 3 2 2 mature generat	ror interces for emit luding wear melectroni PO-4 - 2 2 2 2 ion, atmos	ption of tacter location pon control c	PO-6 - 2 2 2 2 2	PO-7 - 3 1 1 1 CO-1 BTL-3	hone (6)
CO, PO Mappi CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1: Radiometry MODULE 2: Radar ES opstrategies, j. MODULE 3: Introduction characterist	PO- 3 3 3 3 3 and peration	3. 4. 5. oower ca onal use, ng of SA radar f electro	Calculate the Calculate the Calculate the Calculate the tactical complex of the Calculation of the Calculati	PO-3 3 2 2 2 cnature generate etection battle, interception Signal process	ror interces for emit luding wear melectronic PO-4 - 2 2 2 2 cion, atmos quiet rada	ption of tacter location pon control c	PO-6 - 2 2 2 2 2 tests.	PO-7 - 3 1 1 1 CO-1 BTL-3	(6)

Decision theory systems, error p	CO-3 BTL-3				
MODULE 5:			(7)		
•	k Issues, cell phone issues, Intercept links, Frequency hopping and other ial techniques for jamming LPI signals	CO-3 BTL-3			
MODULE 6:			(7)		
Introduction to	electronic counter measures and counter-counter measures.	CO-4 BTL-3			
1. "Tactical Battlefield Communications Electronic Warfare", by David Adamy 2008					
2. "Military Communications in the Future Battlefield", by Marko Suojanen.					
3. "Electronic Warfare for the Digitized Battlefield", by Michael Frater, Michael Ryan.					
4.	Literature / books suggested by respective course Lecturers.				

COURSE	TITLE	RADAR TECHNOLO	CREDITS	2		
COURSE	CODE	DTD3791	COURSE CATEGORY	PC	L-T-P-S	0-0-2-0
Versi	ion	1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
LIST OF EX	PERIMEN	rs				
2.		experiments will be a ilable facilities.	dded in consultation v	with DRDO labs co	onsidering the	CO- BTL-

COURSE TITLE		DIGITAL & SATELLITE COMMUNICATION AND CRED NAVIGATION FROM SPACE LAB						
COURSE CODE	DTD3792	COURSE CATEGORY	PC	L-T-P-S	0-0-2-0			
Version	1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3			
LIST OF EXPERIME	NTS							
	b experiments will be a vailable facilities.	added in consultation v	with DRDO labs co	onsidering the	CO- BTL-			

SEMESTER II - ELECTIVE - 3 COURSES

	TTLE	Robotio	cs (MSS, MC	C)		CREDITS	3
COURSE C	ODE	DTA-3730 COURSE CATEGORY DE			L-T-P-S	3-0-0-0	
Version			1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMEN [*]	T SCHEN	1E					
First Periodical Assessment			l Periodical essment	Seminar/ Assignments/ Project Surprise Test / Quiz		Attendance	ESE
15%			15%	10%	5%	5%	50%
Course Obje	ctive	coordin sensors	ate transfor and devices	o a broad range of to mation and kinema , robot applications f this course, the stu	atics, trajectory and economics a	planning, conti nalysis.	•
		1. Use	•	bra and Lie algebra			robots.
Course Outc		rob 3. Cald 4. To	oots. culate the Ja do the path _l	orward kinematics cobian for serial and planning for a robot e tools for analysis a	I parallel robot. ic system.		al and parallel
CO, PO Map	ping	rob 3. Cald 4. To 0 5. To 0	oots. culate the Ja do the path I use software	cobian for serial and planning for a robot e tools for analysis a	I parallel robot. ic system. nd design of robo	otic systems.	
CO, PO Map	ping PO-1	rob 3. Cald 4. To 0 5. To 0	ots. culate the Ja do the path use software	cobian for serial and planning for a robot	I parallel robot. ic system. nd design of robo		PO-7
CO, PO Map CO CO-1	ping PO-1	rob 3. Cald 4. To 0 5. To 0	oots. culate the Ja do the path use software	cobian for serial and planning for a robot e tools for analysis at PO-4	I parallel robot. ic system. id design of robo PO-5	PO-6	PO-7
CO, PO Map CO CO-1 CO-2	ping PO-1	rob 3. Cald 4. To 0 5. To 0	ots. culate the Ja do the path use software	cobian for serial and planning for a robot e tools for analysis a	I parallel robot. ic system. nd design of robo	otic systems.	
CO, PO Map CO CO-1 CO-2 CO-3	ping PO-1	rob 3. Cald 4. To 0 5. To 0	ots. culate the Ja do the path use software PO-2 2 3	cobian for serial and planning for a robot e tools for analysis as PO-3 PO-4 - 2 2	I parallel robot. ic system. id design of robo PO-5	PO-6	PO-7
CO, PO Map CO CO-1 CO-2 CO-3 CO-4	ping PO-1 3 3 3 3	rob 3. Cald 4. To 0 5. To 0	oots. culate the Ja do the path use software PO-2 2 3 2	cobian for serial and planning for a robot e tools for analysis at PO-4 2 2 2	I parallel robot. ic system. id design of robo PO-5 - 2 -	PO-6 - 2 -	PO-7 - 2 -
CO, PO Map	ping PO-1 3 3 3 3 3 3 3 3	rob 3. Cald 4. To 0 5. To 0	pots. culate the Ja do the path use software PO-2 2 3 2	cobian for serial and planning for a robot e tools for analysis at PO-4 2 2 2 2 2	I parallel robot. ic system. id design of robo PO-5 2 - 2 2	PO-6 - 2 - 2	PO-7 - 2 - 1
CO, PO Map CO CO-1 CO-2 CO-3 CO-4 CO-5	ping PO-1 3 3 3 3 3 3 1:	rob 3. Calc 4. To c 5. To c	PO-2 2 3 2 3	cobian for serial and planning for a robot e tools for analysis at PO-4 2 2 2 2 2	PO-5 - 2 - 2 3	PO-6 - 2 - 2 2 2	PO-7 - 2 - 1 2
CO, PO Map CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1	ping PO-1 3 3 3 3 1: ttals of	rob 3. Cald 4. To 0 5. To 0	PO-2 2 3 2 2 3 seed robotic so	PO-3 PO-4 2 2 2 2 3 3 3	PO-5 - 2 - 2 3 areas of locomot	PO-6 - 2 - 2 2 2	PO-7 - 2 - 1 2 (7)
CO, PO Map CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1	ping PO-1 3 3 3 3 L: stals of ion, gra	rob 3. Cald 4. To 0 5. To 0	PO-2 2 3 2 2 3 seed robotic so	cobian for serial and planning for a robot e tools for analysis and PO-4	PO-5 - 2 - 2 3 areas of locomot	PO-6 - 2 - 2 2 2	PO-7 - 2 - 1 2 (7)
CO, PO Map CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1 Fundamen manipulati MODULE 2	ping PO-1 3 3 3 3 1: stals of ion, gra 2:	rob 3. Cald 4. To 0 5. To 0	PO-2 2 3 2 2 3 seed robotic syensory perce	cobian for serial and planning for a robot e tools for analysis and PO-4	PO-5 - 2 - 2 3 areas of locomoration.	PO-6 - 2 - 2 2 2	PO-7 - 2 - 1 2 (7) CO-1 BTL-3 (5)
CO, PO Map CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1 Fundamen manipulati MODULE 2 Kinematics	ping PO-1 3 3 3 3 L: stals of ion, gra 2: s, dynar	rob 3. Cald 4. To 0 5. To 0	PO-2 2 3 2 2 3 sed robotic syensory perce	PO-3 PO-4 2 2 3 3 ystems covering the ption, and teleopera	PO-5 - 2 - 2 3 areas of locomoration.	PO-6 - 2 - 2 2 tion,	PO-7 - 2 - 1 2 (7) CO-1 BTL-3 (5)
CO, PO Map CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1 Fundamen manipulati MODULE 2 Kinematics	ping PO-1 3 3 3 3 L: stals of ion, grading, grad	rob 3. Cald 4. To 0 5. To 0	PO-2 2 3 2 2 3 sed robotic syensory perce	PO-3 PO-4 2 2 2 2 3 3 3 ystems covering the ption, and teleopera	PO-5 - 2 - 2 3 areas of locomoration.	PO-6 - 2 - 2 2 tion,	PO-7 - 2 - 1 2 (7) CO-1 BTL-3 (5)
CO, PO Map CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1 Fundamen manipulati MODULE 2 Kinematics controller	ping PO-1 3 3 3 3 L: stals of ion, grader, gra	rob 3. Cald 4. To 0 5. To 0	PO-2 2 3 2 2 3 sed robotic syensory perce	PO-3 PO-4 2 2 2 2 3 3 3 ystems covering the ption, and teleopera	PO-5 - 2 - 2 3 areas of locomoration.	PO-6 - 2 - 2 2 tion,	PO-7 - 2 - 1 2 (7) CO-1 BTL-3 (5)
CO, PO Map CO CO-1 CO-2 CO-3 CO-4 CO-5 MODULE 1 Fundamen manipulati MODULE 2 Kinematics controller system des MODULE 3	ping PO-1 3 3 3 3 L: stals of ion, grades, dynar archite sign. 3:	rob 3. Calc 4. To c 5. To c I Iland-bases asping, see mics, ma cture, m	PO-2 2 3 2 2 3 seed robotic seensory perceenipulability, otion planni	PO-3 PO-4 2 2 2 2 3 3 ystems covering the ption, and teleopera	PO-5 PO-5 2 2 3 areas of locomoration.	PO-6 - 2 - 2 2 tion, ramming, n, Control	PO-7 - 2 - 1 2 (7) CO-1 BTL-3 (5)

MODULE 4:		(7)				
Modelling Cont Derivative (PID)	CO-3 BTL-3					
MODULE 5:		(7)				
Feedback Contr	ol System, Motion and path planning, Collision avoidance and navigation	CO-3 BTL-3				
MODULE 6:		(6)				
Fundamental of	Fundamental of AI, Programming methods for robotics, Human-Robot interaction.					
REFERENCE BOOK	S					
1.	Text Book: Introduction to Robotics by S.K. Saha (Tata McGraw-Hill, New 2008, 1st Reprint 2009)	Delhi, India				
2.	"Introduction to Robitcs: Mechanics and Control", by Craig, J.J. Publisher Delhi.	: Pear-son,				
3.	"Fundamentals of Robotics: Analysis and Control" by Schilling Robert I. Pub-lisher:					
4.	"An Introduction to Robotics Analysis Systems Applications" by Niku Saeed B					
5.	Stuart Russell and Peter Norvig, Publisher: Prentice Hall					
6.	Literature / books suggested by respective course Lecturers.					

COURSE TIT	ΓLE	EMI/EN	ИС in Militar	ry Systems		CREDITS	3
COURSE CO	DE	DTA-37	'31	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
Version 1.0			1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEN	ΛE					
			l Periodical essment	Seminar/ Assignments/ Project Surprise Test / Quiz		Attendance	ESE
15%			15%	10%	5%	5%	50%
Course Object	techniques for prevention of electronic equipment through good E techniques – grounding, shielding, cable management, and power i troubleshooting techniques, EMI/EMC standards. Upon completion of this course, the students will be able to 1. Understand the concept of EMI / EMC protection of equipment 2. Identify and prevent the common EMI/EMC problems in milital					and power in e to of equipment lems in military	terface design,
СО, РО Марр		5.	Learn gener	EMI/EMC troubleshoate EMI/EMC require	ements documer	it.	
CO	PO-	1	PO-2	PO-3 PO-4	PO-5	PO-6	PO-7
CO-2	3		2		2	2	2
CO-2	3		2			-	
CO-4	3		2		2	2	3
CO-5	3		3	2 -	2	3	3
MODULE 1:				<u> </u>			(6)
	uplin		-	C and EMP, Classifica mena and effects, Tr	· · · · · · · · · · · · · · · · · · ·		CO-1 BTL-3
MODULE 2:							(6)
•			•	ems, Non-ideal Beha II measurements, EM	•		CO-2 BTL-3
MODULE 3:							(6)
and shieldir	EMI Control Methods: Conducted and radiated emissions and susceptibility, Crosstalk and shielding, Grounding, Bonding, Filtering, EMI gasket, Isolation transformer, opto isolator; Faraday cage, isolation of shelters					CO-2 BTL-	
MODULE 4:							(5)
		_	tions: Nation ectrum con	nal and Intentional s versation;	tandardizing orga	anizations,	CO-3 BTL-3

MODULE 5:	MODULE 5: (7						
EMC Design and selection and m	CO-3 BTL-3						
MODULE 6:		(6)					
,	EMC analysis and detection techniques: Using tools for signal integrity analysis, Study eye diagrams for communication systems.						
REFERENCE BOOKS	S						
1.	"EMI/EMC Computational Modeling Handbook", by brucearchambeault, Ramahi, et al.	Omar M.					
2.	"EMI/EMC Computational Modeling Handbook: 630 (The Springer International Series in Engineering and Computer Science)", by Bruce R. Archambeault, Omar M. Ramahi, et al.						
3.	"A practical approach to electromagnetic compatibility", by Chetan Katha	alay					
4.	Literature / books suggested by respective course Lecturers.						

COURSE TIT	LE	Defenc	e Electro-Op	tics and Imaging Sy	stems	CREDITS	3
COURSE CO	DE	DTA-37	32	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
Version			1.0	Approval Details 23 ACM, 06.02.2021		LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEN	1E					
			l Periodical essment	Seminar/ Assignments/ Project Surprise Tes Quiz		Attendance	ESE
15%			15%	10%	5%	5%	50%
Course Object	ive	current student applicat	and future s to light o tion.	rse is to provide an electro-optic and n application of electro-optic fthis course, the stu	imaging devices ectro- optics and	. Course will dimaging syst	also to enable
Course Outco	me	 Understand the technology and principles underpinning electro-o systems. Apply their knowledge to practical electro-optic design and acquis lems. Understand the trade-offs in electro-optic systems design. 					
CO, PO Mappi	ng						
СО	PO-	1	PO-2	PO-3 PO-4	PO-5	PO-6	PO-7
CO-1	3		2		-	-	-
CO-2	3		3	2 1	2	2	2
CO-3	3		2	2 -	- -		-
MODULE 1:							(6)
Principles of	radio	ometry, T	The human e	eye, Visible band opt	ical sighting syste	ems.	CO-1
MODULE 2:							BTL-3
WIODULE 2:							(6) CO-2
Camera syst	ems,	Image in	itensifiers, M	1issile seekers.			BTL-3
MODULE 3:							(6)
Electro-opti	c cou	ntermea	sures.				CO-2 BTL-
MODULE 4:							(7)
Thermal ima	Thermal imagers, II cameras, Hyper-spectral imaging, Digital image processing. CO-3 BTL-3						
MODULE 5:							(5)
							CO-3
EO sensors f	or La	sers and	iaser DEW				BTL-3

MODULE 6:		(6)				
Electro-optic protection measures. CO-4 BTL-3						
REFERENCE BOOKS	5					
1.	"Systems engineering analysis of electro-optical and Infra red system", b Wolfgang Arrasmith.	y William				
2.	"Introduction to Infrared and Electro-Optical Systems", by Author Ronald Ronald G. Driggers.	d G. Driggers				
3.	"Handbook of Defence Electronics and Optronics: Fundamentals, Techno Systems", by Author(s): Anil K. Maini	logies and				
4.	"Building Electro-Optical Systems: Making It all Work", by Author Philip C	C. D. Hobbs.				
5.	"Electro-Optical Instrumentation: Sensing and Measuring with Lasers", by Author Silvano Donati.					
6. "Electro-optical systems design, Analysis and testing", by Author Michael C. Dudzik.						
7.	Literature / books suggested by respective course Lecturers.					

COURSE TIT	LE	Structu	ral Dynamic	s and Aero-Elastici	ty		CREDITS	3	
COURSE CO	DE	DTA-37	'33	COURSE CATEGORY		DE	L-T-P-S	3-0-0-0	١
Version		1.0		Approval Details		3 ACM, .02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT	SCHEN	ΛE							
First Periodical Assessment		Second Periodical Assessment		Seminar/ Assignments/ Project	Surp	rise Test / Quiz	Attendance	ESE	
15%			15%	10%		5%	5%	50%	
Course Object	ive	comput various	ational anal	ended to provide ysis, Different met a related to vibrati acture.	nods of	analysis, I	Mathematical r	nodeling of	the
Course Outco	me	1. 2.	Understand Understand	f this course, the st vibrations and fluid of different design a m dynamic analysis	dynam spects	ics behind t related to l	the aerospace s oading in aeros	•	١.
CO, PO Mappi	ing								
со	PO-	1	PO-2	PO-3 PO-	4	PO-5	PO-6	PO-7	
CO-1	3		2			-	-	-	
CO-2	3		2			-	-	-	
CO-3	3		2	2 2		2	2	2	4-1
MODULE 1:								T	(6)
Principles a	nd me	ethods of	computation	nal structural dyna	mics ar	ıd vibratioi	n analysis.	CO-1 BTL-3	
MODULE 2:								BIL-3	(6)
		unamia a	nalucia usias	the finite element	motha	d Calaulat	ion of model	CO-2	(6)
parameters		yriaiiic a	illalysis usili	g the finite element	metho	u, Calculat	ion or modal	BTL-3	
MODULE 3:								1	(6)
System dyn	amic	•		uperposition, frequ chniques, Fatigue a	-	sponse, m	odel	CO-2 BTL-	-
MODULE 4:		. actarar	5,110110313 100	ques, rangue u	, 515.				(7)
	n to a		•	vnamic Loading, Be	nding N	loment, Se	ectional	CO-3	(7)
properties (,, ACI	51511, V 1	. Diagraili,					BTL-3	
MODULE 5:									(5)
Basic theory	of lii	near elas	tic fracture r	nechanics; strain e	nergy re	elease rate	;	CO-3	
•	Basic theory of linear elastic fracture mechanics; strain energy release rate; BTL-3								

MODULE 6:		(6)			
Applications to delamination crack growth in polymer composite laminates, Damage tolerance issues in composites CO-4 BTL-3					
REFERENCE BOOK	S				
1.	"Elements of vibration analysis", by Leonard Meirovitch. Publisher : McG Inc.,US; 2nd edition (1 March 1986)	raw-Hill			
2.	"Finite Element Analysis Theory And Application With ANSYS", by Moaveni Publisher: Pearson Education; 3rd edition (1 January 2011)				
3.	"Mechanical Vibrations SI Edition Sixth Edition", by Singiresu S. Rao. Publisher: Pearson				
4.	"Elements of Fracture Mechanics", by Prashant Kumar. Publisher : McGraw Hill Education.				
5.	"Introduction to Structural Dynamics and Aeroelasticity", by Dewey H. Ho Alvin Pierce. Publisher: Cambridge University Press.	odges and G.			
6.	Literature / books suggested by respective course Lecturers.				

COURSE T	ITLE	Safety,	3					
COURSE CO	ODE	DTA-37	734	COURSE CATEGO	RY	DE	L-T-P-S	3-0-0-0
Versior	Version1.0Approval Details23 ACM, 06.02.2021LEARNING LEVEL						BTL-3	
ASSESSMENT SCHEME								
First Periodical Second Periodical Assignme Assessment Assessment Project					Surp	rise Test / Quiz	Attendance	ESE
15%			15%	10%		5%	5%	50%
Course Objec	ctive	safety l	nealth and h	es of the course azard management of the	nt. The c	ourse will	provide unders	tanding on the
Course Outco	ome	1. 2.	Understand Handle toxic	f this course, the chemical safety si cliquids & gases, e the NBC warfare	tandards, xplosives	fire safety,	hazard manage	
CO, PO Mapp								
СО	PO-	1	PO-2	PO-3 P	0-4	PO-5	PO-6	PO-7
CO-1	3		2			-	1	2
CO-2 CO-3	3		2			1	2 2	2
MODULE 1								(6)
Chemical S Laboratori	afety: es, Sto	rage of h	•	ations of chemica emicals, Compat nt	-			CO-1 BTL-3
MODULE 2	:							(4)
Fire triangl	e and	Handling	g of Toxic, Inc	dustrial Gases				CO-2 BTL-3
MODULE 3	:							(7)
	_			ZAN techniques, I ardous materials;		manufactu	re, Hazard	CO-2 BTL-
MODULE 4	:							(7)
Warfare: Classifications of explosives based on hazards, Nuclear, biological and chemical warfare safety; CO-3 BTL-3								
								_
MODULE 5	:							(6)
		ant of bo	man factors	. Health & Enviro	amont sci	Foty		

MODULE 6:		(6)			
Nano materials safety (Toxicology study) co- BTL-					
REFERENCE BOOKS	S				
1.	"Occupational Health and Safety Management A Practical Approach", by Reese. Publisher: CRC Press.	Charles D.			
2.	"Occupational and Environmental Safety and Health", Arezes, P.M., Baptista, J.S., Barroso, M.P., Carneiro, P., Cordeiro, P., Costa, N., Melo, R.B., Abreu dos Santos Baptista, J.M., Perestrelo, G. (Eds.). Publisher: Springers, 2019				
3.	"Handbook of Occupational Safety and Health", by S. Z. Mansdorf. Publis	her : Wiley.			
4.	"Institution of Chemical Engineers", by Trevor Kletz"Hazop and Hazan				
5.	"Handbook Of Toxicology Of Chemical Warfare Agents", by Ramesh C. Go Edition Elsevier, 2015	upta 2 nd			
6.	"Nanomaterials Safety Toxicity And Health Hazards", by Shyamasree Gho	osh De Gruyter.			
7.	"Hazardous Chemicals Handbook", by Phillip Carson, Clive Mumford Butt Heinemann.	terworth-			
8.	Literature / books suggested by respective course Lecturers.				

COURSE TIT	LE	FUND		F TELEMETRY,		COMMAND &	CREDITS	3	
COURSE COI	<u> </u>	DTA-37		TRANSPONDEI COURSE CATEG		DE	L-T-P-S	3-0-0-0	
Version	JE	DIA-57	1.0	Approval Deta		23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT SCHEME									
First Periodi Assessmer			d Periodical essment	Seminar/ Assignment Project	s/	Surprise Test / Quiz	Attendance	ESE	
15%			15%	10%		5%	5%	50%	
Course Objecti	ve	the sate	ellite commu		etry,	e to provide kno modulation tech	_		
Course Outcon	ne	1. 2. 3.	Satellite con Overall cont data. Determinati processing, a Proper cont	nmunication an rol of satellites on of the satell and transmittin rol of satellite t	d rela throu ite's e g of ra hroug	dents will be ableted technologie gh collection, property act location the anging signals. In the reception, ansmitted from	s. Tocessing, and toc	otion,	n of
CO, PO Mappir	ng								
СО	PO-	1	PO-2	PO-3	PO-4	PO-5	PO-6	PO-7	
CO-1	3		2	-	-	-	-	-	
CO-2	3		2	-	-	-	-	-	
CO-3	3		2	-	2	2	2	2	
CO-4	3		2	-	2	2	2	3	
MODULE 1:								1	(6)
Fundamenta schemes.	l of s	atellite (communicati	on, different m	odula	tion and multipl	exing	CO-1 BTL-3	
MODULE 2:									(6)
Telemetry, D	ata ⁻	Transmis	sion, Metho		n, Tir	Access Technique Division and Idding Schemes.		CO-2 BTL-3	
MODULE 3:									(6)
Satellite Pac	Satellite Packet Communications, Tracking and Telemetry. CO-2 BTL-								
MODULE 4:								1	(6)
Doppler and	Elec	tro-Optio	cal methods	of tracking, Airl	oorne	Missile.		CO-3 BTL-3	

MODULE 5:		(6)				
Signal Processing: Processing of Signal, Data Acquisition and Reduction.						
BTL						
MODULE 6:		(6)				
Introduction to satellite communication, transponders.						
REFERENCE BOOKS	S					
1.	"Spacecraft TT&C and Information Transmission Theory and Technologies", by, Jiaxing Liu.Publisher: Springer, 2014					
2.	"Introduction to PCM Telemetering Systems", by Stephen Horan. Publish	er: CRC Press				
3.	"Satellite Communications Systems: Systems, Techniques and Technology", by Gerard Maral, Michel Bousquet, Zhili Sun. Publisher: Wiley, 2020					
4.	"Satellite Communications", by Timothy Pratt, Jeremy F. Allnutt, 3rd Edition Publisher:					
5.	"Principles of Modern Communication Systems", by Samuel O. Agbo , Ma Sadiku 2017	atthew N. O.				
6.	Literature / books suggested by respective course Lecturers.					

	ITLE	J	AMMING AN	D ECM/ECCM TECHI	NOLOGIES	CREDITS	3	
COURSE CO	ODE		DTA-3736 COURSE CATEGORY DE L-T-P-S					
Version	n		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT	SCHEME							
First Perio			nd Periodical ssessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE	
15%			15%	10%	5%	5%	50%	
Course Object	tive	jamr	ming, different	uous interference, fa types of jamming syste	ems, ECM technic	ques, and ECCI	•	
Course Outcome				oncept of electronic a				
Course Outco	me	electr	onic jamming erstand the dif	rinciples and the prac g technology ferent types of electro				
Course Outco		electr 3.Und	onic jamming erstand the dif	g technology				
		electr 3.Und	onic jamming erstand the dif	g technology				
CO, PO Mar co co-1	pping PO-1	electr 3.Und	erstand the difures. PO-2	rechnology ferent types of electro PO-3 PO-4	nic counter meas	ures and counter	r–counter	
CO, PO Mar CO CO-1 CO-2	PO-1 3 3	electr 3.Und	erstand the diffures. PO-2 2	PO-3 PO-4	PO-5	PO-6	PO-7	
CO, PO Mar CO CO-1 CO-2 CO-3	PO-1 3 3 3	electr 3.Und	erstand the difures. PO-2	rechnology ferent types of electro PO-3 PO-4	nic counter meas	ures and counter	PO-7	
CO, PO Map CO CO-1 CO-2 CO-3 MODULE 1: Principals of Through, Co	pping PO-1 3 3 5 FElectro	electr 3.Und measu	PO-2 2 2 ck(EA),Jammin	PO-3 PO-4	PO-5 mingTypesBurn-	PO-6	PO-7 (7) CO-1 BTL-2	
CO, PO Map CO CO-1 CO-2 CO-3 MODULE 1: Principals of Through, Co	PO-1 3 3 3 FElectro	electr 3.Und measu micAtta mming,	PO-2 2 2 ck(EA),Jammin	PO-3 PO-4	PO-5	PO-6	PO-7 (7) CO-1 BTL-2 (6)	
CO, PO Map co co-1 co-2 co-3 MODULE 1: Principals of Through, Co MODULE 2: RepeaterJa	pping PO-1 3 3 3 ifElectro	electr 3.Und measu micAtta mming,	PO-2 2 2 ck(EA),Jammin	PO-3 PO-4	PO-5	PO-6	PO-7 (7) CO-1 BTL-2	
CO, PO Map co co-1 co-2 co-3 MODULE 1: Principals of Through, Co MODULE 2: RepeaterJa	pping PO-1 3 3 3 FElectro overJar mmingling vs. N	electr 3.Und measu micAtta mming,	PO-2 2 2 ck(EA),Jammin	PO-3 PO-4	PO-5	PO-6	PO-7 (7) CO-1 BTL-2 (6) CO-1 BTL-2	
CO, PO Map CO CO-1 CO-2 CO-3 MODULE 1: Principals of Through, Co MODULE 2: RepeaterJa lobe Jamm MODULE 3:	pping PO-1 3 3 3 ifElectro overJar ing vs. N	electr 3.Und measu micAtta mming, Equatio Main lob	PO-2 2 2 ck (EA), Jammin Range Decept ns, Noise Jamming. Jamming, Self-	PO-3 PO-4	PO-5	PO-6 nder, Side	PO-7 (7) CO-1 BTL-2 (6)	

Infrared Count	ermeasures (IRCM), Off-Board ECM Systems, Communications	CO-2			
Countermeasu	BTL-3				
MODULE 5:		(6)			
	al Jamming System, Shipboard Self-Defense System, EA/Susceptibility against ns. Search Radar Counter-Countermeasures, Tracking Radar.	CO-1,2 BTL-3			
MODULE 6:		(6)			
Counter-Counte Countermeasu	rmeasures, Infrared Counter-Countermeasures, Communications Counter- ires.	CO-3 BTL-3			
REFERENCE BOO	KS	1			
1.	"Electronic Countermeasure and Electronic Counter-Countermeasure", by Zohuri.	yBahman			
2.	"Fundamentals of Electronic Warfare 2001", by S.A. Vakin , L.N. Shustov, R.H. I	Dunwell.			
3.	"Fundamentals of Electronic Warfare 2001", by S.A. Vakin , L.N. Shustov, R.H. Dunwell.				
4.	"Electronic Warfare & Radar Systems Engineering Handbook" 2013, Naval Center Weapons Division.	AirWarfare			
5.	"EW 101: A First Course in Electronic Warfare (Artech House Radar Library)	,1st Edition			

COURSE TI	TLE	SOFT	WARE DEFINE	D RADIOS	CREDITS	3		
COURSE CO	DDE	D	DTA-3737 COURSE CATEGORY DE L-T-P-S					
Version	l		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT	SCHEME							
First Period Assessme			nd Periodical sessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE	
15%			15%	10%	5%	5%	50%	
Course Outcor		Upon 1.Und 2.Und 3.Gair	completion of an knowledge of	of this course, the st oncept, application alog RF components of digital hardware ar	udents will be ab of SDRs. as front end block	le to k in implementa s development	ation of SDR. techniques.	
CO, PO Map	ping	4.Gaii	Tkilowieuge c	of software developr	Territion embedde	eu wireless syst	ems.	
со	PO-1		PO-2	PO-3 PO-4	PO-5	PO-6	PO-7	
CO-1	3		2		-	-	-	
CO-2	3		2		-	-	-	
CO-3	3		2		-	-	-	
CO-4	3		2		-	-	- (5)	
MODULE 1:							(6)	
		-		chitecture, SDR enab	ers,advantage/		CO-1	
disadvanta	ges, Ap	plicatio	ns.				BTL-2	
MODULE 2:							(6)	
and non-lin	ear ba	ndwidtl	h efficient mo	ckseparation, digital r odulations. Bandwid eanderrorprobabili	th and power eff		CO-1 BTL-2	
MODULE 3:							(6)	
	SDRHardware, super-heterodynearchitecture, homodynearchitecture, advantages & CO-2 disadvantages, Software for SDR, Processing architecture for SDR. BTL-3							
MODULE 4:							(6)	
code divisio	n techn	iques as	well as carrier	n, multiple access tecl sensing, Wireless ser eranalogue signal pr	sor networks and	beam	CO-2 BTL-3	

processing						
MODULE 5:		(7)				
Sourceandchannelcoding (Sourceandchannelcoding, sampling, entropy, data compression, voice coding, block and convolution coding, turbo coding, space-time coding and trellis coding).						
MODULE 6:		(5)				
Case studies in so	Case studies in software radio design, Introduction and a Historical perspective					
REFERENCE BOOKS						
1.	"Software Radio, (A modern approach to radio engineering)", by Jeffery H.Red PHI PTR.	ed Publisher :				
2.	"RF and Digital Signal Processing for Software Defined Radio", by John J. Rouphael. 2. Publisher: Elesiver.					
3.	"Digital Techniques in Frequency Synthesis", by B.G.Golderg. Publisher: McGra	w-Hill.				
4.	"Multirate Signal Processing", by N.J. Fliege. Publisher: John Wiley and sons					

	ITLE		NCED LIGHT CTURES	WEIGHT AND COMP	CREDITS	3	
COURSE C	ODE		DTA-3738	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
Version			1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEME	Ē					
First Perio Assessm			nd Periodical ssessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE
15%			15%	10%	5%	5%	50%
Course Object	tive	com mat of st und	posite mate hematical mo ructures used erstaticandd	erials, their manuodels & design structured by the structure of this course, the students of this course, the students of this course, the students of the stu	ifacturing tech ures made of cor ike missiles and a dingcrashandbir	iniques and mposites. Basic of the sircrafts& their dstrike willalso	to develop understanding performance
Course Outcome		1. Und	derstandthed	esign of advanced struc	tures and lightwe	iaht matarials fo	raerosnace
		mater 2. Und comp	ials. derstand the I ositeand met	numericalandanalytic tallic components. to solve real enginee	calskillsin struct		•
CO, PO Ma _l	oping	mater 2. Und comp	ials. derstand the I ositeand met Ily knowledge	numericalandanalytic tallic components. to solve real enginee	calskills in struct ring problems.	ural mechanics	for both
CO, PO Ma _l	pping PO-1	mater 2. Und comp	ials. derstand the ositeand metally knowledge	numerical and analytic tallic components.	calskillsin struct		•
CO, PO Ma _l CO CO-1	poping PO-1	mater 2. Und comp	ials. derstand the i ositeand met ly knowledge PO-2 2	numerical and analytic tallic components. to solve real enginee	ring problems. PO-5	ural mechanics PO-6 -	for both PO-7
CO, PO Maj CO CO-1 CO-2	pping PO-1	mater 2. Und comp	ials. derstand the ositeand metally knowledge	numericalandanalytic tallic components. to solve real enginee	calskills in struct ring problems.	ural mechanics	for both
CO, PO Ma _l CO CO-1	PO-1 3 3 3	mater 2. Und comp	ials. derstand the ositeand metoly knowledge PO-2 2	numericalandanalytic tallic components. to solve real enginee PO-3 PO-4 2 2 2	ring problems. PO-5 - 2	PO-6	PO-7
CO, PO Maj CO CO-1 CO-2 CO-3 MODULE 1:	PO-1 3 3 3 trength	mater 2. Und comp 3.App	ials. derstand the i ositeand met oly knowledge PO-2 2 2 2	numericalandanalytic tallic components. to solve real enginee PO-3 PO-4 2 2 2	ring problems. PO-5 - 2 2	PO-6 - 2 2	PO-7 - 2 2
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE 1:	PO-1 3 3 3 Compo	mater 2. Und comp 3.App	ials. derstand the i ositeand met oly knowledge PO-2 2 2 2	PO-3 PO-4 2 2 2 2 2	ring problems. PO-5 - 2 2	PO-6 - 2 2	PO-7 - 2 2 2 (6)
CO, PO Map CO CO-1 CO-2 CO-3 MODULE 1: Review of S Reinforced	PO-1 3 3 3 trength Compo	mater 2. Und comp 3.App of Mate	rials. derstand the rosite and metally knowledge PO-2 2 2 2 2 erials, Introduct	PO-3 PO-4 2 2 2 2 2	PO-5 - 2 2 erials — Metal Allo	PO-6 - 2 2 2 oys and Fiber	FO-7 - 2 2 2 (6) CO-1 BTL-2
CO, PO Map CO CO-1 CO-2 CO-3 MODULE 1: Review of So Reinforced MODULE 2: Introductio	PO-1 3 3 3 trength Compo	mater 2. Und comp 3.App of Mate	rials. derstand the rosite and metally knowledge PO-2 2 2 2 2 erials, Introduct	PO-3 PO-4 2 2 2 tion to Aerospace Mat	PO-5 - 2 2 erials — Metal Allo	PO-6 - 2 2 2 oys and Fiber	FO-7 - 2 2 2 (6) CO-1 BTL-2 (7)
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE 1: Review of S Reinforced MODULE 2: Introductio Corrugated	PO-1 3 3 3 trength Compo	of Mate	PO-2 2 2 2 2 crials, Introductions of constructions	PO-3 PO-4 2 2 2 tion to Aerospace Mat	PO-5 - 2 - 2 erials — Metal Allo	PO-6 - 2 2 oys and Fiber Truss, and	FO-7 - 2 2 2 (6) CO-1 BTL-2 (7)
CO, PO Mal CO CO-1 CO-2 CO-3 MODULE 1: Review of S Reinforced MODULE 2: Introductio Corrugated	PO-1 3 3 3 trength Compo	of Mate	PO-2 2 2 2 2 crials, Introductions of constructions	PO-3 PO-4 2 2 2 tion to Aerospace Mat	PO-5 - 2 - 2 erials — Metal Allo	PO-6 - 2 2 oys and Fiber Truss, and	FO-7
CO, PO Map CO CO-1 CO-2 CO-3 MODULE 1: Review of So Reinforced MODULE 2: Introductio Corrugated MODULE 3: Introductio	PO-1 3 3 3 trength Compo	of Mater	PO-2 2 2 2 2 crials, Introductions of constructions	PO-3 PO-4 2 2 2 tion to Aerospace Mat	PO-5 - 2 - 2 erials — Metal Allo	PO-6 - 2 2 oys and Fiber Truss, and	For both PO-7 - 2 2 2 (6) CO-1 BTL-2 (7) CO-1 BTL-2 (6) CO-2 BTL-3

MODULE 5:		(5)			
Material Consti	tutive Relations.	CO-1,2 BTL-3			
MODULE 6:		(5)			
Failure Theories;	Fatigue theory.	CO-3 BTL-3			
REFERENCE BOOKS					
1.	"Composite Structures Safety Management", by Dr. Bjorn Backman. Publisher Science.	r: Elsevier			
2.	"Composite Structures: Design, Mechanics, Analysis, Manufacturing and Testing", by Manoj Kumar Buragohain. Publisher: CRC Press.				
3.	"Lightweight Composite Structures in Transport: Design, Manufacturin and Performance", by James Njuguna Woodhead Publishing, 2016.	ng, Analy-sis			
4.	"Structural and Stress Analysis", by T.H.G. Megson. Publisher: Butterworth-	Heinemann.			

COURSE CODE DTA-3739 COURSE CATEGORY DE	COURSE TI	TLE	-	3				
ASSESSMENT SCHEME First Periodical Assessment Second Period	COURSE CO	DE	[DTA-3739	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
First Periodical Assessment Second Periodical Assessment Assignments/ Project 15% 15% 10% 5% 5% 50% The course is intended to provide learning on the testing requirements, characterization, system performance testing procedures, test setups, safety standards, safety tools of laser and microwave based DEW systems. Upon completion of this course, the students will be able to 1.Understand the characterization and testing requirements of DEW systems. 2.Carry out the indoors & outdoors system performance testing. 3.Understand the safety issues, safety standards, handling high power sources. CO, PO Mapping CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2	Version			1.0	Approval Details			BTL-3
Assessment Quiz Assessment Qui	ASSESSMENT S							
The course is intended to provide learning on the testing requirements, characterization, system performance testing procedures, test setups, safety standards, safety tools of laser and microwave based DEW systems. Course Outcome			_		Assignments/	•	Attendance	ESE
Course Objective characterization, system performance testing procedures, test setups, safety standards, safety tools of laser and microwave based DEW systems. Course Outcome	15%			15%	10%	5%	5%	50%
1. Understand the characterization and testing requirements of DEW systems. 2. Carry out the indoors & outdoors system performance testing. 3. Understand the safety issues, safety standards, handling high power sources. CO, PO Mapping	Course Object	ive	char	racterization,	system performa	nce testing prod	cedures, test s	•
CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2			1.Und	lerstand the cl ry out the indo	haracterization and oors & outdoors syst	testing requireme em performance	ents of DEW sys testing.	
CO-1 3 2 1 1 1 2 CO-3 3 2 2 - 1 1 1 2 CO-3 3 2 2 CO-3 - 2 MODULE 1: (6) Testing requirements of DEW system, types of testing, laser effect testing on target, system output testing. (7) System performance testing, System outdoor test & measurement instruments. (7) MODULE 3: (5) Laser testing issues, Laser safety, Laser safety standards, laser safety tools. (5) MODULE 4: (5) Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. (CO-2 BTL-3) MICROWAVE System testing Impedance measurement, S-Parameters and the Smith Chart. (CO-2 BTL-3)						T = = =		T
CO-2 3 2 1 1 1 2 CO-3 3 2 2 2 MODULE 1: (6) Testing requirements of DEW system, types of testing, laser effect testing on target, system output testing. MODULE 2: (7) System performance testing, System outdoor test & measurement instruments. MODULE 3: (5) Laser testing issues, Laser safety, Laser safety standards, laser safety tools. MODULE 4: (5) Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3								PO-7
CO-3 3 2 2 MODULE 1: CO-1 BTL-2 MODULE 2: (7) System performance testing, System outdoor test & measurement instruments. CO-1 BTL-2 MODULE 3: (5) Laser testing issues, Laser safety, Laser safety standards, laser safety tools. CO-2 BTL-3 MODULE 4: (5) Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3								-
MODULE 1: Testingrequirements of DEW system, types of testing, laser effect testing on target, system output testing. MODULE 2: System performance testing, System outdoor test & measurement instruments. MODULE 3: Laser testing issues, Laser safety, Laser safety standards, laser safety tools. MODULE 4: MODULE 4: Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. MICO-2 BTL-3 MICO-2 BTL-3						1	1	
Testing requirements of DEW system, types of testing, laser effect testing on target, system output testing. MODULE 2: System performance testing, System outdoor test & measurement instruments. MODULE 3: Laser testing issues, Laser safety, Laser safety standards, laser safety tools. CO-2 BTL-3 MODULE 4: Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3		<u> </u>			-	-		
outputtesting. MODULE 2: System performance testing, System outdoor test & measurement instruments. CO-1 BTL-2 MODULE 3: Laser testing issues, Laser safety, Laser safety standards, laser safety tools. CO-2 BTL-3 MODULE 4: (5) Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3			+	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \				
MODULE 2: System performance testing, System outdoor test & measurement instruments. MODULE 3: Laser testing issues, Laser safety, Laser safety standards, laser safety tools. MODULE 4: Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3 MIL-3			ISOIDE	w system, type	es or testing, laser ene	cttestingontarget	., system	
System performance testing, System outdoor test & measurement instruments. MODULE 3: Laser testing issues, Laser safety, Laser safety standards, laser safety tools. MODULE 4: Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3 MICROWAVE SYSTEM TESTING IMPEDANCE MEASUREMENT, S-Parameters and the Smith Chart. CO-2 BTL-3	<u> </u>	ııg.						
MODULE 3: Laser testing issues, Laser safety, Laser safety standards, laser safety tools. MODULE 4: Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3 MICROWAVE SYSTEM TESTING IMPEDANCE MEASUREMENT, S-Parameters and the Smith Chart. BTL-3								
Laser testing issues, Laser safety, Laser safety standards, laser safety tools. MODULE 4: Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. BTL-3 CO-2 BTL-3	System per	formar	nce test	ting, System o	utdoor test & meas	urement instrum	ents.	
MODULE 4: Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3	MODULE 3:							(5)
MODULE 4: Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3	Laser testin	g issue	s. Lase	r safety. Lasei	r safety standards.	aser safety tools.		CO-2
MODULE 4: Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3		5 -5 -6	, =5.00	22,, 2000.	,	1 1111111111111111111111111111111111111		
Microwave system testing Impedance measurement, S-Parameters and the Smith Chart. CO-2 BTL-3	MODULE 4:							
BTL-3		vstem t	esting lı	mpedance mea	asurement. S-Parame	eters and the Smith	Chart.	
		,		p = 1 = 1.10	2, 2		· · · · · · · · · · · · · · · · · · ·	
(//	MODULE 5:							(7)

Power Measurement, Noise Figure and Phase Noise measurement, Frequency measurements (Spectrum Analysis), Gain Compression and Intermodulation, Network Analysis.						
MODULE 6:		(6)				
Microwave subsys	Microwave subsystem/system characterization techniques. HPM safety tools, safety standards.					
REFERENCE BOOKS						
1.	"An Introduction to Microwave Measurements", by Ananjan Basu.					

COURSE T	ITLE	ADVAN	NCED ANALY	CREDITS	3		
COURSE CO	ODE	DTA	A-3740	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0
Version	1		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEME						
First Period Assessmo			Periodical essment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE
15%		1	15%	10%	5%	5%	50%
Course Object	tive	charac The co	cterization b ourse provid	ye of the course is to y all the conventiona les understanding or c techniques, chroma	Iwellestablished the material ch	I techniques uso naracterization	ed worldwide.
Course Outcome		Upon co	ompletion o	f this course, the stu	dents will be abl	le to	
	-	2.Apply	rstand differ	ent characterization analytical technique ner etc.	•		/inorganic/
CO, PO Mar	oping	2.Apply a	rstand differ appropriate iterial/polym	analytical technique ner etc.	foraparticular m	aterial organic,	
CO, PO Mar	oping PO-1	2.Apply ananomat	rstand differ appropriate iterial/polym	analytical technique ner etc. PO-3 PO-4	foraparticular m	aterial organic,	PO-7
CO, PO Map CO CO-1	poping PO-1	2.Apply a nanomate	rstand differ appropriate terial/polym	analytical technique ner etc. PO-3 PO-4	foraparticular m	aterial organic, PO-6	PO-7 -
CO, PO Map CO CO-1 CO-2	PO-1 3	2.Apply ananomat	rstand differ appropriate terial/polym	analytical technique ner etc. PO-3 PO-4	foraparticular m	aterial organic,	PO-7 - 2
CO, PO Map co CO-1 CO-2 MODULE 1:	PO-1 3 3	2.Apply ananomate	rstand differ appropriate terial/polym	analytical technique ner etc. PO-3 PO-4	foraparticular m	aterial organic, PO-6	PO-7 -
CO, PO Map co co-1 co-2 MODULE 1:	PO-1 3 3 Analys	2.Apply ananomate	rstand differ appropriate terial/polym	analytical technique ner etc. PO-3 PO-4	foraparticular m	aterial organic, PO-6	PO-7 - 2 (4)
CO, PO Mar CO CO-1 CO-2 MODULE 1: Instrumenta	PO-1 3 3	2.Apply a nanomate Policy 2 2 sis: Qualita	rstand differ appropriate aterial/polymero-2	analytical technique ner etc. PO-3 PO-4	foraparticular m	aterial organic, PO-6	PO-7 - 2 (4) CO-1 BTL-2
CO, PO Mar CO CO-1 CO-2 MODULE 1: Instrumenta	PO-1 3 3 instrum	2.Apply a nanomate Policy 2 2 sis: Qualita	rstand differ appropriate aterial/polymero-2	analytical technique ner etc. PO-3 PO-4	foraparticular m	aterial organic, PO-6	PO-7 - 2 (4) CO-1 BTL-2 (4) CO-1
CO, PO Map CO CO-1 CO-2 MODULE 1: Instrumenta MODULE 2: Genesis of MODULE 3: Polymeric T	PO-1 3 3 instrum echniqu Thermo	2.Apply a nanomate 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	rstand differ appropriate aterial/polyments and series analysis alysis, hyphology Technicy (TG), Differ	analytical technique ner etc. PO-3 PO-4	PO-5 - 1	PO-6 1 on; Thermal	PO-7 - 2 (4) CO-1 BTL-2 (4) CO-1 BTL-2
CO, PO Mar CO CO-1 CO-2 MODULE 1: Instrumenta MODULE 2: Genesis of MODULE 3: Polymeric T Techniques:	PO-1 3 3 instrum Gechniqu Thermo	2.Apply a nanomate 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	rstand differ appropriate aterial/polyments and series analysis alysis, hyphology Technicy (TG), Differ	PO-3 PO-4	PO-5 - 1	PO-6 1 on; Thermal	PO-7 - 2 (4) CO-1 BTL-2 (4) CO-1 BTL-2 (8)
CO, PO Mar CO CO-1 CO-2 MODULE 1: Instrumenta MODULE 2: Genesis of MODULE 3: Polymeric T Techniques: Scanning Ca MODULE 4: Chromatogra	PO-1 3 3 al Analys instrum fechniqu Thermo	2.Apply a nanomal 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	rstand differ appropriate aterial/polyments and steel aterial at a second and second alysis. alysis, hyphology Technic (TG), Differ a second at a sec	PO-3 PO-4	PO-5 1 Sight determinations (DTA), and Different erformance Liquid	PO-6 - 1	PO-7 - 2 (4) CO-1 BTL-2 (4) CO-1 BTL-2 (8) CO-2 BTL-3

	Ultra Violet-Visible Spectroscopy UV-VIS, Infra-Red spectroscopy (IR), Nuclear nance (NMR), Mass spectroscopy, Atomic Absorption Spectroscopy (AAS).	CO-1,2 BTL-3
MODULE 6:		(4)
XRD and SEM	techniques, Sensitivity studies	CO-3 BTL-3
REFERENCE BOO	KS	
1.	"Fundamentals of molecular spectroscopy" by C. N. Banwell. Publisher : McG	raw Hills.
2.	"Introduction to Spectroscopy" by Donald L. Pavia, Gary M. Lampman, an Kriz. Publisher: Cengage Learning, 2014.	nd George S.
3.	"Chromatography: Concepts and Contrasts" by James M. Miller. Publisher: W	iley.
4.	"Chromatography: Principles and Instrumentation", by Mark F. Vitha. Publi	sher: Wiley.
5.	"Elements of X-Ray Diffraction" by B.D. Cullity Deceased, S.R. Stock. Publisher	: Pearson.
6.	"Electron Microscopy: Principles and Fundamentals" by S. Amelinckx, Dirk van Landuyt, Gustaaf van Tendeloo. Publisher: Wiley.	c van Dyck, J.
7.	"Polymer Characterization: Physical Techniques", by Dan Campbell, Richard A R. White 2nd Edition. Publisher CRC Press.	. Pethrick, Jim

COURSE TI	TLE	so	SONAR SYSTEM ENGINEERING			CREDITS	3
COURSE CO	DDE	DTA-3741 COURSE CATEGORY DE					3-0-0-0
Version	l	1.0	Арі	proval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT	SCHEME						
First Period Assessme		Second Period Assessmen	dical As	Seminar/ signments/ Project	Surprise Test / Quiz	Attendance	ESE
15%		15%		10%	5%	5%	50%
Course Object	ive	acoustic pri	nciples, son	•	de an in-depth u and applicatio design.	_	
Course Outcome		1. Know the back 2. Have an in-day 3. Know about 4. Know the phasonar.	asic building lepth knowl the ambigu rysics behind	s blocks of a rad edge on differe ity function an d sound propag	dents will be ab lar system. ent types of signa d its significance ration in water ar ourse in real time	ıls that are used in radar signal p nd principle of o	processing.
CO, PO Map							
СО	PO-1	PO-2	PO-3	PO-4	PO-5	PO-6	PO-7
CO-1	3	2	-	-	-	-	-
CO-2	3	2	-	-	-	-	-
CO-3	3	2	-	-		-	-
CO-4	3	2	-	-	-	-	-
CO-5	3	3	-			-	-
		opment and disc ssive and active:		•	ciples that pertair val operation.	n tothedesign	(6) CO-1 BTL-2
MODULE 2:							(6)
Topics from	compl	ex aperture the	eory, array t	heory.			CO-1 BTL-2
MODULE 3:							(5)
Signal proce	ssing						CO-2 BTL-3
MODULE 4:							(6)
							(0)

Introduction to u	ndersea warfare and engineering acoustics.	CO-2				
		BTL-3				
MODULE 5:		(7)				
	Principles of optimal signal processing techniques for detecting signals in noise, maximum ikelihood, Bayes risk.					
MODULE 6:		(6)				
Neyman-Pearson (ROCcurves).	CO-3 BTL-3					
REFERENCE BOOKS						
1.	"Fundamentals of Radar, Sonar and Navigation Engineering", by K. K. Sharr	ma.				
2.	"Principles of Modern Radar: Advanced techniques", by editor William L. N	∕lel-vin.				
3.	"Principles of Modern Radar: Advanced techniques", by editor William L. Mel-vin.					
4.	"Sonar for practicing engineers", by A. D. Waite.					
5.	"Underwater Acoustics: Analysis, Designand Performance of Sonar", by Rich Hodges.	n-ardP.				

SEMESTER II - ELECTIVE - 4 COURSES

COURSE TI	TLE	UNMANNED AERIAL VEHICLE DESIGN CRED						3
COURSE CO	DE	DT	A-3742	COURSE CATEGORY	DE		L-T-P-S	3-0-0-0
Version			1.0	Approval Details	23 ACI 06.02.2	-	LEARNING BTL-3	
ASSESSMENT	SCHEN	ΛE						
First Period Assessme			d Periodical essment	Seminar/ Assignments/ Project	Surprise Quiz	-	Attendance	ESE
15%			15%	10%	5%		5%	50%
Course Objec	tive	process	s for rapidly $\mathfrak g$	ded to provide the growing fixed – wir ability analysis, air	g UAV techi	nology,	integrated wit	th its
Course Outcome Upon completion of this course, the students will be able to a. Understand the design requirements, design paramete b. Perform the aerodynamic analysis, performance and st c. Understand the performance testing of the UAVs. d. Understand the airworthiness and safety requirements					gn parameters on ance and stable UAVs.	ility analysis.		
CO, PO Mapp	ing							
СО	PO-	1	PO-2	PO-3 PO	4 P	0-5	PO-6	PO-7
CO-1	3		2		-		-	-
CO-2	3		2	- -	-		-	-
CO-3	3		2	- -	-		-	-
CO-4	3		2	- -	-		-	-
MODULE 1:	:							(6)
UAV design	Requ	irements	s, design par	ameters, design alg	orithms, Ce	rtificat	ion	CO-1
		afts and	UAVs. Airwo	orthiness of aircraft	s and UAVs	•		BTL-3
MODULE 2:	;							(6)
•		_	g qualities. M m identificat	laneuverability req ion	uirements. <i>i</i>	Aircraft	t design; UAV	CO-2 BTL-3
MODULE 3:	:							(7)
UAV aerody	/nami	cs, struct	tures and pro	opulsion, performa	nce and stal	oility ar	nalysis.	CO-2 BTL-
MODULE 4								(6)
UAV projec	t life c	cycles. St	ages of Aircr	aft design. Initial si	zing: aircraf	ts and	of UAVs.	CO-3 BTL-3
MODULE 5:								
THE STATE OF THE S	•							(5)

MODULE 6:		(6)			
Wind Tunnel Testing, Aerodynamic Characterization through Wind Tunnel Testing.					
REFERENCE BOOK	S				
1.	"Introduction to Flight", by John D. Anderson				
2.	"Performance, Stability, Dynamics, and Control of Airplanes", by Bandu N. Pa	amadi.			
3.	"Aircraft performance and design", by John D. Anderson.				
4.	"Unmanned Aircraft Design A review of fundamentals", by Mohammad H. Sadraey.				
5.	"Aircraft Design : A Conceptual Approach", by Daniel P. Raymer.				
6.	"Unmanned Aircraft Systems: UAVs Design Development and Deployment", b	y Reg Austin.			
7.	"SmallUnmannedFixed-wingAircraftDesign:APracticalApproach",byAndrand James P.Scanlan.	rewJ.Keane			
8.	Literature / books suggested by respective course Lecturers.				

COURSE TIT	LE	NAVAL	OCEAN ANA	CREDITS	3			
COURSE CO	DE	DT	A-3743	COURSE CATEGOR	Y	DE	L-T-P-S	3-0-0-0
Version			BTL-3					
ASSESSMENT S	SCHEN	1E						
First Periodi Assessmen			l Periodical essment	Seminar/ Assignments/ Project		Surprise Test / Quiz	Attendance	ESE
15%			15%	10%		5%	5%	50%
Course Object	ive	Ocean. generat	They will lea	led to provide und rn methods of and an circulation pre- VAFS).	alysi	is of ocean data	, to model Nav	al ocean, to
Course Outcor	me	1 2	L. Understa 2. Perform t 3. Understa	f this course, the sond the design required he aerodynamic and the performan	uirei analy ice te	ments, design p ysis, performan esting of the UA	arameters of U ce and stability Vs.	analysis.
CO, PO Mappi	ng							
СО	PO-	1	PO-2	PO-3 PC	D-4	PO-5	PO-6	PO-7
CO-1	3		2			-	-	-
CO-2	3		2			-	-	-
CO-3	3		2			-	-	-
MODULE 1:			2	- -		-	-	(6)
	00146	das of th	ha Indian Na	uu aaaan analusis	and	prodiction suct	omes	CO-1
Auvanceu ki	IOWIE	euge or ti	ne mulan Na	vy ocean analysis	anu	prediction syst	ems.	BTL-3
MODULE 2:								(5)
Naval Ocean	n Mod	deling Pro	ogram (NON	IP), Naval ocean d	lata	systems.		CO-2 BTL-3
MODULE 3:								(6)
Atmospheric	c forc	ing syste	ems, data ass	imilation systems) .			CO-2 BTL-
MODULE 4:								(6)
Optimal The (TOPS).	Optimal Thermal Interpolation System (OTIS), Thermal Ocean Prediction Systems CO-3							
MODULE 5:								(6)
		-		The atmospheric _l ula for estimating	•		layer,	CO-3 BTL-3

MODULE 6:						
The global ocean circulation prediction system, Shallow Water Analysis and Forecast System (SWAFS), Knowledge of ocean eddies. BT						
REFERENCE BOOKS						
1.	Indian Navy: Ocean of opportunities (Defence Series Books) Author: by PRANAV ZOPE					
2.	2. Elements of Ocean Engineering. Author Robert E. Randall					
3.	Ocean Modelling for Beginners - Using Open-Source Software. Author Jochen Kaempf.					
4.	Literature / books suggested by respective course Lecturers.					

COURSE TIT	LE	ELLING &SIMU	JLATION OF LASER			CREDITS	3
COURSE COI	DE D	ГА-3744	L-T-P-S	3-0-0-0			
Version		1.0	Approval Details		ACM, 2.2021	LEARNING LEVEL	BTL-3
ASSESSMENT S	СНЕМЕ						
First Periodi Assessmer		d Periodical sessment	Seminar/ Assignments/ Project	·	e Test / uiz	Attendance	ESE
15%		15%	10%	5	%	5%	50%
Course Objecti	interac lethali	ction with me ty modelling,	led to provide und tals and composite damage mechanis formance evaluatio	materials n & dama	s, physics ge thres	based models hold measuren	for the
Course Outcon	1. 2. ne	Understand Developphy composites Understand	on of this course, the of the laser matter raics-based model for the laser parameter performance of high	interactio or evaluati r measure	n. on of effe ement tee	ect of laser on m chniques.	etals and
MODULE 1:							(6)
со	PO-1	PO-2	PO-3 PO	4	PO-5	PO-6	PO-7
CO-1	3	2	2 -		-	-	-
CO-2 CO-3	3	2	- 2		<u>-</u>	1 -	2
CO-4	3	2	2 2		2	1	2
CO-4	3		2				
Laser beam composite m		cs, Laser letha	ality modeling & si	nulation v	vith meta	al targets &	CO-1 BTL-3
_		r vulnerability	assessment, Effec	t of laser o	on metal:	s &	CO-2
composite m	naterials.						BTL-3 (6)
Measureme		cterization of ir Interpretati	Damage Threshol	ds, Mecha	nisms of	Damage,	CO-2 BTL-
MODULE 4:							(6)
Analysis Too techniques.	ls for the Est	imation of Ha	azards, Laser paran	neters mea	asureme	nt	CO-3 BTL-3
MODULE 5:							(7)
Tools to ana	lyse and nre	dict Laser Sve	tem performance (ınder diffa	erent con	nditions like	CO-3
10013 to arra	., se and pre	alet Laser sys	- Periormance (acr unit		IGIGIOTIS IINC	BTL-3

land, sea air, etc	c.				
MODULE 6:		(6)			
Introduction of full scale end to end modeling of laser system performance.					
REFERENCE BOOKS	5				
1.	"High Power Laser-Matter Interaction", by Mulser, Peter, Bauer, Dieter. Publisher : Springer.				
2.	Literature / books suggested by respective course Lecturers.				

COURSE TITI	LE	COMPL	JTATIONAL /	CREDITS	3				
COURSE COL	DE	DTA-3745 COURSE CATEGORY DE L-T-P-:						3-0-0-0)
Version	Version 1.0 Approval Details						LEARNING LEVEL	BTL-3	
ASSESSMENT S	CHEN	1E							
First Periodi Assessmen			l Periodical essment	Seminar/ Assignments/ Project	_	e Test / uiz	Attendance	ESE	
15%			15%	10%	5	%	5%	50%	
Course Objecti	ve	numeri	cal methods	ded to provide lear for solving system ence modelling.	_	•		•	,
Course Outcome Upon completion of this course, the students will be able to 1. Understand the CFD analysis, fluid mechanics, heat transfer analysis, numerical modelling of fluids. 2. Generate numerical model related to fluid dynamics 3. To do the pre and post processing of CFD analysis.						llysis,			
CO, PO Mappir	ng								
СО	PO-1	L	PO-2	PO-3 PO	-4	PO-5	PO-6	PO-7	
CO-1	3		2			-	-	-	
CO-2	3		2	3 3		3	2	2	
CO-3	3		2	3 3		3	2	2	/=\
MODULE 1:									(5)
Introduction	n to f	luid mec	hanics & hea	at transfer.				CO-1 BTL-3	
MODULE 2:								DIL-3	(6)
	to n	ımorical	analysis Die	scretization approa	chas: finit	a diffora	nce finite	CO-2	(0)
volume, finit			•	• •	CHES. IIIIIL	c unitere	nce, mile	BTL-3	
MODULE 3:		ciic ali	a spectrum						(6)
		da fan al			aa.t.:a.u.a	Nivenania		CO-2	(-)
				ations/systems of e ystems and for flui	•		cai schemes	BTL-	
MODULE 4:	ic, pa			ysterns and for har	a dynamic				/ 7 \
									(7)
CFD analysis	•							CO-3	
								BTL-3	
MODULE 5:									(6)
Numerical m	nodel	ling of co	mpressible	& in-compressible	flow turb	ulence n	nodelling	CO-3	
	.ouci	01 66	7.11p1 C331b1C		,	archice II		BTL-3	
MODULE 6:									(6)

Grid generation	/CAD, data analysis and uncertainties	CO-4 BTL-3
REFERENCE BOOKS	S	
1.	"ATextbookofHeatTransferPaperback", by S.P. Sukhatme. Publisher: Univer	-sitiesPress.
2.	"An Introduction to Computational Fluid Dynamics: The Finite Volume Metho Versteeg. Publisher: Pearson.	d", by H.
3.	"Computational Fluid Dynamics the Basics with Applications", by John D. An-der Publisher: McGraw Hill Education	son,Jr.
4.	"Fluid Mechanics: Volume 2: Foundations and Applications of Mechanics (Cambo. S. Jog. Publisher: Cambridge University Press; 3rd edi-tion.	oridge-iisc)", by
5.	"Numerical Modeling and Computer Simulation", Edited by DraganCvetk intechopen.	ović, publisher
6.	Literature / books suggested by respective course Lecturers.	

COURSE CODE DTA-3746 COURSE CATEGORY DE L-T-P-S 3-0-0-0	COURSE TITLE	LAUNC	H VEHICLE D	ESIGN & ANALYS	IS		CREDITS	3	
ASSESSMENT SCHEME First Periodical Assessment	COURSE CODE	DT	A-3746	COURSE CATEGOR	Υ	DE	L-T-P-S	3-0-0-0	
First Periodical Assessment Assessment 15% 15% 15% 10% 5% 5% 5% 50% Course Objective The course is intended to provide learning on the launch vehicle design and analysis, components and subsystems of the launch vehicle, propulsion systems. Upon completion of this course, the students will be able to 1. Understand the launch vehicle requirements, its functioning. 2. Design and analysis of launch vehicles. 3. Understand the propellant requirement for launch vehicles. CO, PO Mapping CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2 2 2 2 CO-2 3 2 2 2 CO-3 3 2 MODULE 1: (6) Introduction to propulsion for launch vehicles, beginning with mission energy requirements and an overview of current and proposed launch propulsion devices. MODULE 2: (5) Performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis, operating characteristics and propellant selection criteria for air performance analysis operating characteristics and propellant selection criteri	Version		1.0	Approval Details		•		BTL-3	
First Periodical Assessment Assessment Assessment Sproject Quiz Attendance ESE 15% 15% 10% 5% 5% 50% Course Objective The course is intended to provide learning on the launch vehicle design and analysis, components and subsystems of the launch vehicle, propulsion systems. Upon completion of this course, the students will be able to 1. Understand the launch vehicle requirements, its functioning. 2. Design and analysis of launch vehicles. 3. Understand the propellant requirement for launch vehicles. CO, PO Mapping CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2 2	ASSESSMENT SCH	HEME							
Course Objective The course is intended to provide learning on the launch vehicle design and analysis, components and subsystems of the launch vehicle, propulsion systems. Upon completion of this course, the students will be able to 1. Understand the launch vehicle requirements, its functioning. 2. Design and analysis of launch vehicles. 3. Understand the propellant requirement for launch vehicles. CO, PO Mapping CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2				Assignments/	•		Attendance	ESE	
Course Objective components and subsystems of the launch vehicle, propulsion systems. Upon completion of this course, the students will be able to 1. Understand the launch vehicle requirements, its functioning. 2. Design and analysis of launch vehicles. 3. Understand the propellant requirement for launch vehicles. CO, PO Mapping CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2 2	15%		15%	10%		5%	5%	50%	
Course Outcome 1. Understand the launch vehicle requirements, its functioning. 2. Design and analysis of launch vehicles. 3. Understand the propellant requirement for launch vehicles. CO, PO Mapping CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2 2	Course Objective	! I		•	•		•	•	is,
CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7 CO-1 3 2 2	Course Outcome	1. 2.	Understand Design and a	the launch vehicle analysis of launch v	requiren vehicles.	nents, its fu	ınctioning.		
CO-1 3 2 2	CO, PO Mapping								
CO-2 3 2 2 3 - 2				PO-3 PO	D-4	PO-5	PO-6	PO-7	
CO-3 3 2								-	
MODULE 1: Introduction to propulsion for launch vehicles, beginning with mission energy requirements and an overview of current and proposed launch propulsion devices. MODULE 2: Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid. MODULE 3: Liquid and nuclear rocket motor propulsion systems. MODULE 4: Advanced cycles and concepts are presented. Design of components and subsystems CO-3 BTL-3 MODULE 5: (6) EF modelling: Idealization, Discretization, Meshing and Post Processing.									
Introduction to propulsion for launch vehicles, beginning with mission energy requirements and an overview of current and proposed launch propulsion devices. MODULE 2: Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid. MODULE 3: CO-2 BTL-3 MODULE 3: (7) Liquid and nuclear rocket motor propulsion systems. MODULE 4: Advanced cycles and concepts are presented. Design of components and subsystems CO-3 BTL-3 MODULE 5: CO-3 BTL-3 CO-3 BTL-3 CO-3 BTL-3 CO-3 BTL-3 CO-3 BTL-3				<u> -</u>		<u> </u>			(6)
requirements and an overview of current and proposed launch propulsion devices. MODULE 2: Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid. MODULE 3: Liquid and nuclear rocket motor propulsion systems. CO-2 BTL-3 CO-2 BTL-3 CO-2 BTL-3 CO-2 BTL-3 CO-2 BTL-3 CO-3 BTL-3 MODULE 4: Advanced cycles and concepts are presented. Design of components and subsystems CO-3 BTL-3 MODULE 5: (6) CO-3 CO-3 CO-3 CO-3 CO-3 CO-3 CO-3 CO-		n propulsion	n for launch	vehicles heginnin	a with m	ission ana	cav	CO-1	(0)
MODULE 2: Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid. MODULE 3: Liquid and nuclear rocket motor propulsion systems. CO-2 BTL-3 CO-2 BTL-3 CO-2 BTL-3 CO-2 BTL-3 CO-3 BTL-5 MODULE 4: Advanced cycles and concepts are presented. Design of components and subsystems CO-3 BTL-3 MODULE 5: (6) EF modelling: Idealization, Discretization, Meshing and Post Processing.		•		, •	_		0,		
Performance analysis, operating characteristics and propellant selection criteria for air breathing and solid. MODULE 3: Liquid and nuclear rocket motor propulsion systems. MODULE 4: Advanced cycles and concepts are presented. Design of components and subsystems CO-2 BTL-3 CO-2 BTL- CO-2 BTL- CO-3 BTL-3 MODULE 5: (6)	•			от от от от от от от от			<u></u>		(5)
breathing and solid. MODULE 3: Liquid and nuclear rocket motor propulsion systems. MODULE 4: Advanced cycles and concepts are presented. Design of components and subsystems CO-3 BTL-3 MODULE 5: (6)	Performance a	analysis, ope	erating chara	acteristics and pro	pellant s	election cr	iteria for air	CO-2	
Liquid and nuclear rocket motor propulsion systems. CO-2 BTL- MODULE 4: Advanced cycles and concepts are presented. Design of components and subsystems CO-3 BTL-3 MODULE 5: (6)	breathing and	solid.	_	·				BTL-3	
Liquid and nuclear rocket motor propulsion systems. MODULE 4: Advanced cycles and concepts are presented. Design of components and subsystems CO-3 BTL-3 MODULE 5: (6)	MODULE 3:								(7)
Advanced cycles and concepts are presented. Design of components and subsystems CO-3 BTL-3 MODULE 5: (6) CO-3 CO-3 CO-3 CO-3 CO-3	Liquid and nuc	lear rocket	motor propi	ulsion systems.					
MODULE 5: EF modelling: Idealization, Discretization, Meshing and Post Processing. CO-3 CO-3	MODULE 4:								(7)
FF modelling: Idealization, Discretization, Meshing and Post Processing.	Advanced cycle	es and cond	epts are pre	sented. Design of	compon	ents and su	ubsystems		
FF modelling: Idealization, Discretization, Meshing and Post Processing.	MODULE 5:								(6)
DIL-3	FE modelling: I	Idealization	, Discretizati	on, Meshing and	Post Proc	essing.			
MODULE 6: (5)	MODULE 6:							II.	(5)

Tracking and co	ontrolling errors, Nonlinear analysis in FEM, Launch dynamic analysis.	CO-4 BTL-3
REFERENCE BOOK	S	
1.	"Design of Rockets and Space Launch Vehicles", by Don Edberg, Willie Co American Institute of Aeronauti cs & Ast. (August 21, 2020)	osta. Publisher :
2.	"Modern Engineering for Design of Liquid Propellant Rocket Engine Astronautics and Aeronautics)", by Dieter K Huzel, David H Huang. Pu (American Institute of Aeronautics & Astronautics); Revised, Subse-quent edi	ıblish-er : AIAA
3.	"Fundamentals of Astrodynamics 1st Edition", by Roger R. Bate, Dona Publisher: The American Design Ethic, MIT, USA.	ald D. Mueller.
4.	"Commercial Launch Vehicle Design", by Nickolay Mykola Zosimovych. Pub-lis Lambert Academic Publishing.	her: Lap
5.	"Space Vehicle Design, Second Edition", by Michael D. Griffin and James R. Frence American Institute of Aeronautics and Astronautics, Inc.	ch. Publisher The
6.	Literature / books suggested by respective course Lecturers.	

		ACQUISITION, TRA	CKING & POINTING				
COURSE TI	TLE	TECHNOLOGY			CREDITS	3	
COURSE CO	DDE	DTA-3747	COURSE CATEGORY	DE	L-T-P-S	3-0-0-0	
Version		1.0	Approval Details	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT	SCHEN	ΛE					
First Period Assessme		Second Periodical Assessment	Seminar/ Assignments/ Project	Surprise Test / Quiz	Attendance	ESE	
15%		15%	10%	5%	5%	50%	
Course Objec	tive		ded to provide learni lopment of tracking a	•	•	. •	
		1. Understand	ion of this course, the	sic systems requ	irements track	•	
Course Outco	ome	required in the introduction to 3. Understand	d the system configur de design of stabilized posome more advance d the control system a dized in the design of t	pointing and traced concepts. and algorithm tea	king systems, a	long with an	
CO, PO Mapp		required in the introduction to 3. Understand	e design of stabilized posome more advanced the control system a	pointing and traced concepts. and algorithm tea	king systems, a	long with an	
		required in the introduction to 3. Understand commonly util	e design of stabilized posome more advanced the control system a	pointing and traced concepts. and algorithm tecracking systems.	king systems, a	long with an	
CO, PO Mapp CO CO-1	ing	required in the introduction to 3. Understand commonly util	e design of stabilized possible some more advanced the control system a lized in the design of t	pointing and traced concepts. and algorithm tecracking systems.	king systems, a	long with an ractices	
CO, PO Mapp CO CO-1 CO-2	PO-	required in the introduction to 3. Understand commonly util	e design of stabilized posome more advanced the control system a ized in the design of the position of the pos	pointing and traced concepts. and algorithm tearscking systems. PO-5	king systems, a	long with an ractices	
CO, PO Mapp CO CO-1 CO-2 CO-3	PO-	required in the introduction to 3. Understand commonly util	e design of stabilized posome more advanced the control system a sized in the design of the posterior of the	pointing and traced concepts. and algorithm tectracking systems. PO-5 1	chniques and p PO-6 -	PO-7	
CO, PO Mapp CO CO-1 CO-2	PO-	required in the introduction to 3. Understand commonly util	e design of stabilized posome more advanced the control system a sized in the design of the posterior of the	pointing and traced concepts. and algorithm tearscking systems. PO-5 1 1	chniques and p PO-6 -	PO-7 (6)	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1	PO- 3 3 3	required in the introduction to 3. Understand commonly util	e design of stabilized posome more advanced the control system a sized in the design of the posterior of the	pointing and traced concepts. and algorithm tearscking systems. PO-5 1 1 1	chniques and p PO-6 -	PO-7	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1	PO- 3 3 3 :	required in the introduction to 3. Understand commonly util	e design of stabilized posome more advanced the control system a ized in the design of the posterior of the	pointing and traced concepts. and algorithm tearscking systems. PO-5 1 1 1	chniques and p PO-6 -	PO-7 (6) CO-1 BTL-3	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Acquisition	PO- 3 3 3 :: , track	required in the introduction to 3. Understand commonly util 1 PO-2 2 2 2 2 2 cing, and pointing (A	e design of stabilized posome more advanced the control system a sized in the design of the design o	pointing and traced concepts. and algorithm tectoracking systems. PO-5 1 1 1 y systems	PO-6	PO-7 (6)	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Acquisition MODULE 2 Target track	PO- 3 3 3 : , track	required in the introduction to 3. Understand commonly util 1 PO-2 2 2 2 2 2 cing, and pointing (A	e design of stabilized posome more advanced the control system a sized in the design of the design o	pointing and traced concepts. and algorithm tectoracking systems. PO-5 1 1 1 y systems	PO-6	PO-7 (6) CO-1 BTL-3 (6)	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Acquisition MODULE 2 Target track	PO- 3 3 3 : , track	required in the introduction to 3. Understand commonly util 1 PO-2 2 2 2 2 ing, and pointing (Aunderstand poi	e design of stabilized posome more advanced the control system a sized in the design of the design o	pointing and traced concepts. and algorithm tectoracking systems. PO-5 1 1 1 y systems	PO-6	PO-7 (6) CO-1 BTL-3 (6)	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Acquisition MODULE 2 Target trac probability MODULE 3	PO- 3 3 3 : , track	required in the introduction to 3. Understand commonly util 1 PO-2 2 2 2 2 ing, and pointing (August 1) and related mathemation, detection of the second common of the second co	PO-3 PO-4 TP) design for military	pointing and traced concepts. and algorithm tectoracking systems. PO-5 1 1 1 y systems	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3 (6)	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Acquisition MODULE 2 Target trac probability MODULE 3	PO- 3 3 3 : , track	required in the introduction to 3. Understand commonly util 1 PO-2 2 2 2 2 ing, and pointing (Aunderstand poi	PO-3 PO-4 TP) design for military	pointing and traced concepts. and algorithm tectoracking systems. PO-5 1 1 1 y systems	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Acquisition MODULE 2 Target trac probability MODULE 3	PO- 3 3 3 ; , track king a of est	required in the introduction to 3. Understand commonly util 1 PO-2 2 2 2 2 ing, and pointing (August 1) and related mathemation, detection of the second common of the second co	PO-3 PO-4 TP) design for military	pointing and traced concepts. and algorithm tectoracking systems. PO-5 1 1 1 y systems	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3 (6)	
CO, PO Mappe CO CO-1 CO-2 CO-3 MODULE 1 Acquisition MODULE 2 Target trace probability MODULE 3 Tracking alg	PO- 3 3 3 : , track : is sorithing:	required in the introduction to 3. Understand commonly util 1 PO-2 2 2 2 2 ming, and pointing (A mind related mathematimation, detection of minds, track filters, mu	PO-3 PO-4 TP) design for military	PO-5 1 1 y systems t, the Johnson cr	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3 (6)	
CO, PO Mappe CO CO-1 CO-2 CO-3 MODULE 1 Acquisition MODULE 2 Target trace probability MODULE 3 Tracking alg	PO- 3 3 3 : , track : soorith	required in the introduction to 3. Understand commonly util 1 PO-2 2 2 2 2 ming, and pointing (A mind related mathematimation, detection of minds, track filters, mu	PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-5 PO-6 PO-1 PO-1 PO-1 PO-1 PO-1 PO-1 PO-1 PO-1	PO-5 1 1 y systems t, the Johnson cr	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3 (6) CO-2 BTL- (7)	
CO, PO Mappe CO CO-1 CO-2 CO-3 MODULE 1 Acquisition MODULE 2 Target trace probability MODULE 3 Tracking alg MODULE 4 Electronic Co	PO- 3 3 3 : , track : sounte	required in the introduction to 3. Understand commonly util 1 PO-2 2 2 2 2 ming, and pointing (A mind related mathematimation, detection of minds, track filters, mu	PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-3 PO-4 PO-6 PO-7 PO-8 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9 PO-9	PO-5 1 1 y systems t, the Johnson cr	PO-6	PO-7 (6) CO-1 BTL-3 (6) CO-2 BTL-3 (7) CO-3 BTL-3	

MODULE 6:		(5)			
Doppler and Ele	ctro-Optical methods of tracking.	CO-4 BTL-3			
REFERENCE BOOKS					
1.	"Acquisition, Tracking, Pointing, and Laser Systems Technologies XXI (Pro-cee 30 October 2007 by Steven L. Chodos (Editor), William E. Thompson (Editor)	,			
2.	"Acquisition, Tracking, and Pointing, January 2017 In book: Free Space Optical				
3.	Literature / books suggested by respective course Lecturers.				

COURSE TI	ITLE		ITION, TRACKING	G & POST		CREDITS	3	
		FLIGHT ANALY	-					
Version		DTA-3748	COURSE CA		DE 23 ACM, 06.02.2021	L-T-P-S LEARNING LEVEL	3-0-0-0 BTL-3	
ASSESSMENT	SCHEN	ΛE						
First Period Assessme		Second Period Assessment	Assignm	nents/	Surprise Test / Quiz	Attendance	ESE	
15%		15%	109	%	5%	5%	50%	
Course Objec	ctive		•		ng on the various n & analysis of D		ht trials,	
		1. Unders	tand the interfac	ces used i	students will be n data acquisitio		ne	
Course Outco	ome	2. Unders acquisi	nents to real-wor tand the Sensors tion software ut Post flight and	s and tran	s. Isducers, Data ac	equisition hardv	ware and data	
CO, PO Mapp	oing	2. Unders acquisi 3. Carry o	tand the Sensors tion software ut Post flight and	s and tran	isducers, Data ac			
CO, PO Mapp	oing PO-	2. Unders acquisi 3. Carry o	tand the Sensors tion software ut Post flight and	s and tran	PO-5	PO-6	PO-7	
CO, PO Mapp CO CO-1	ping PO-	2. Unders acquisi 3. Carry o	tand the Sensors tion software ut Post flight and PO-3 -	s and tranalysis.	PO-5	PO-6 -	PO-7 -	
CO, PO Mapp	oing PO-	2. Unders acquisi 3. Carry o	tand the Sensors tion software ut Post flight and	s and tran	PO-5	PO-6	PO-7 -	
CO, PO Mapp CO CO-1 CO-2	PO-	2. Unders acquisi 3. Carry o PO-2 2 2	tand the Sensors tion software ut Post flight and PO-3 -	s and tranalysis.	PO-5 1	PO-6 -	PO-7 -	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1	PO-: 3 3 3 3 ::	2. Unders acquisi 3. Carry o PO-2 2 2 2 2	tand the Sensors tion software ut Post flight and PO-3 - 1	PO-4	PO-5 1	PO-6 2	PO-7 2	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1	PO-3 3 3 3 :	2. Unders acquisi 3. Carry o PO-2 2 2 2 2	tand the Sensors tion software ut Post flight and PO-3 - 1	PO-4	PO-5 1 2	PO-6 2	PO-7 2 (4	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Importance	PO-3 3 3 3 :	2. Unders acquisi 3. Carry of 2 2 2 2 ght Trials in Missurement, Introduction	PO-3 - 1 - sile Developmen	PO-4	PO-5 1 2	PO-6 2 ements.	PO-7 2 (4 CO-1 BTL-3	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Importance	PO-3 3 3 3 : e of Fli f Measument.	2. Unders acquisi 3. Carry of 2 2 2 2 ght Trials in Missurement, Introduction	PO-3 - 1 - sile Developmen	PO-4	PO-5 1 2 es, Safety Require	PO-6 2 ements.	PO-7 2 (4 CO-1 BTL-3	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Importance MODULE 2 Methods of of an instru	PO-3 3 3 3 : e of Fli : f Measument. :	2. Unders acquisi 3. Carry of 2 2 2 2 2 ght Trials in Missurement, Introduced	PO-3 - sile Developmen	PO-4	PO-5 1 2 es, Safety Require	PO-6 2 ements.	PO-7 2 (4 CO-1 BTL-3 (6 CO-2 BTL-3	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Importance MODULE 2 Methods of of an instru MODULE 3	ping PO- 3 3 3 3 : e of Fli : : : : : : : : : : : : : : : : : : :	2. Unders acquisi 3. Carry of 2 2 2 2 2 ght Trials in Missurement, Introduced	PO-3 - sile Developmen	PO-4	PO-5 1 2 es, Safety Require	PO-6 2 ements.	PO-7 2 (4 CO-1 BTL-3 (6 CO-2 BTL-3	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Importance MODULE 2 Methods of an instru MODULE 3 Static and I their respo	ping PO- 3 3 3 3 : e of Fli : : :Dynamnse.	2. Unders acquisi 3. Carry of 2 2 2 2 2 ght Trials in Missurement, Introduction of the control o	PO-3 - sile Developmen	PO-4	PO-5 1 2 es, Safety Require	PO-6 2 ements.	PO-7 2 (4 CO-1 BTL-3 (6 CO-2 BTL-3 (6)	
CO, PO Mapp CO CO-1 CO-2 CO-3 MODULE 1 Importance MODULE 2 Methods or of an instru MODULE 3 Static and I their respo MODULE 4 Calibration	ping PO- 3 3 3 3 : e of Fli : : :Dynam nse. : of Ins	2. Unders acquisi 3. Carry of 2 2 2 2 2 ght Trials in Missurement, Introduction of the control o	PO-3 - sile Developmen	PO-4	PO-5 1 2 es, Safety Require	PO-6 2 ements.	PO-7 2 (4 CO-1 BTL-3 (6 CO-2 BTL-3 (6) CO-2 BTL- (5)	
CO, PO Mappe CO CO-1 CO-2 CO-3 MODULE 1 Importance MODULE 2 Methods or of an instru MODULE 3 Static and E their respo MODULE 4 Calibration	ping PO- 3 3 3 : e of Fli : f Measument. : Dynamnse. :	2. Unders acquisi 3. Carry of 2 2 2 2 2 ght Trials in Missurement, Introduction Characteristic truments.	PO-3 - 1 - sile Development	PO-4	PO-5 1 2 es, Safety Require	PO-6 2 ements. onal elements ents and	PO-7 2 (4 CO-1 BTL-3 (6 CO-2 BTL-3 (6) CO-2 CO-2 CO-3	

MODULE 6:		(7)
Methods for po	st flight data analysis.	CO-4 BTL-3
REFERENCE BOOKS	5	
1.	"Advances in Missile Guidance, Control, and Estimation: 47 (Automation Engineering)", by editors S.N. Balakrishnan, A. Tsourdos, B.A. White.	and Control
2.	"CalibrationHandbookofMeasuringInstruments1stEdition",byAlessandrol Publisher International Society of Automation.	Brunelli.
3.	"Calibration Book", by Janne Kivilaakso, Antero Pitkäkoski Jori Valli, Mike J Nobuo Inamoto Arja Aukia Masaki Saito. Publisher: VaisalaOyj.	ohnson,
4.	"Sensors and Transducers", by Patranabis D. Publisher : Prentice Hall India Le Limited.	arning Private
5.	"Sensors and Transducers Paperback", by Ian Sinclair. Publisher: Elsevier.	
6.	Literature / books suggested by respective course Lecturers.	

COURSE TITL	AIR INDEPENDENT PROPULSION AND BATTERIES CREDITS				3					
COURSE COD	DE	DT	A-3749	COURSE CATEG	ORY	ı	DE	L-T-P-S	S	3-0-0-0
Version			1.0	Approval Det	ails		ACM, 2.2021		EARNING BTL-3	
ASSESSMENT S	CHEN	1E								
First Periodic Assessmen		_	l Periodical essment	Seminar/ Assignment Project		_	se Test / Juiz	Attenda	nce	ESE
15%			15%	10%		ţ	5%	5%		50%
Course Objectiv	ve			ded to provide cles, power req		_		-	•	•
Course Outcom	ne	1.	Understand	on of this cours the requireme analysis Energy	nts of	air inde	pendent	propulsio	•	
CO, PO Mappin	ng							_		
со	PO-1	L	PO-2	PO-3	PO-4		PO-5	PO-6	5	PO-7
CO-1 CO-2	3		2	3	-		2	2		2
MODULE 1:	3			3	-					(6)
	to H	vbrid Ele	ctric Vehicle	s: Impact of m	odern	drive-ti	rains on e	nergy		CO-1
supplies;		,								BTL-3
MODULE 2:										(7)
-			-	ction, various h	nybrid	drive-tı	rain topo	logies, po	wer	CO-2
flow control,	fuel	efficienc	cy analysis;							BTL-3
MODULE 3:										(7)
				electric drive-t efficiency analy		pologie	es, power	flow cont	trol	CO-2 BTL-
MODULE 4:									•	(6)
Configuration	n and	d control	of DC Moto	onents used in r drives, Induct nce Motor drive	ion M	otor dri	ives, Pern	nanent		CO-3 BTL-3
MODULE 5:									•	(6)
Energy Stora Vehicles.	ge: lı	ntroduct	ion to Energ	y Storage Requ	iireme	nts in H	lybrid and	d Electric		CO-3 BTL-3
MODULE 6:										(6)
analysis, Sup	er Ca its ar	apacitor	based energ	nnalysis, Fuel C y storage and i of different en	ts ana	lysis, Fly	wheel ba		gy	CO-4 BTL-3

1.	"Hybrid Electric Vehicles: Principles and Applications with Practical Perspec-tives", by Chris Mi, M. Abul Masrur. Publisher: Wiley.
2.	"Modern Electric, Hybrid Electric, and Fuel Cell Vehicles: Fundamentals, Theo-ry, and Design, Second Edition (Power Electronics and Applications Series)", by Mehrdad Ehsani, YiminGao, Ali Emadi, Publisher: Standards media.
3.	Literature / books suggested by respective course Lecturers.

	COURSE TITLE ADVANCED DIGITAL MODULATION TECHNOLOGIES & STANDARDS CREDITS						3		
COURSE CO	ODE	DTA-3	750	COURSE CATEGO	ORY	DE	L-T-P-S	3-0-0-0	
Version	1	1.0		Approval Deta	ils	23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3	
ASSESSMENT	SCHEM	E							
First Period Assessme		Second Per Assessn		Seminar/ Assignments Project	/	Surprise Test / Quiz	Attendance	ESE	
15%		15%	6	10%		5%	5%	50%	
Course Object		theories ar the design communica Upon 1. Und 2. Und sou	nd practice principles ation link. completion derstand to the codine of	course is to proses of a digital cost of transmitter on of this course the design digit the transmitter g-pulse code matcher the requirement	and re e, the s al com , receive	nication system eceiver so as to students will be munication sys ver communica tion, delta mod	e able to tems. tions system m	nill deal with able	1
CO, PO Mapp									
СО	PO-1)-2	PO-3	PO-4	PO-5	PO-6	PO-7	
CO-1	3	2			-	1	-	-	
CO-2	3	2			=	1	-	-	
CO-3 MODULE 1	. 3	2		-	-	2	-		<i>16</i> \
		ommunicat	ion sustan	n transmittars	and roc	noiver commun	ications	CO-1	(6)
system mo	_	ommunicat	lion syster	n, transmitter a	ina rec	ceiver commun	ications	BTL-3	
MODULE 2									
								5123	(6)
								CO-2	(6)
Voice source	ce codii	ng– pulse co	ode modu	ılation, delta m	odulati	ion, vocoders.			(6)
Voice source MODULE 3		ng– pulse co	ode modu	ılation, delta m	odulati	ion, vocoders.		CO-2	(6)
MODULE 3 Digital mod shift, Quad	: dulatior rature	n – Amplitu	de-shift, F	requency-shift, ure phase-shift	, Phase	e-shift, differen	•	CO-2	
MODULE 3 Digital mod shift, Quad	: dulatior rature e ampli	n – Amplitu phase-shift,	de-shift, F	requency-shift,	, Phase	e-shift, differen	•	CO-2 BTL-3	
MODULE 3 Digital mod shift, Quad Quadrature MODULE 4	: dulatior rature e ampli :	n – Amplitu phase-shift, tude modul	de-shift, F , Quadrat lation	requency-shift,	, Phase , and N	e-shift, differen Minimum-shift l	keying,	CO-2 BTL-3	(8)
MODULE 3 Digital mod shift, Quadrature MODULE 4 Communication	: dulatior rature e ampli : ations o	n – Amplitu phase-shift, tude modul	de-shift, F , Quadrat lation	requency-shift ure phase-shift	, Phase , and N	e-shift, differen Minimum-shift l	keying,	CO-2 BTL-3 CO-2 BTL-	(8)
MODULE 3 Digital mod shift, Quadrature MODULE 4 Communication Murphy MODULE 5	: dulation rature e ampli : ations o	n – Amplituo phase-shift tude modul channel – N	de-shift, F , Quadrat lation //ultipath	requency-shift ure phase-shift effects, fading a	, Phase , and M and div	e-shift, differen Minimum-shift l versity, models	of Egli and	CO-2 BTL-3 CO-2 BTL-	(8)
MODULE 3 Digital mod shift, Quadrature MODULE 4 Communication Murphy MODULE 5	idulation rature amplicitions of the super	n – Amplitu phase-shift, tude modul channel – M	de-shift, F , Quadrat lation //ultipath o	requency-shift ure phase-shift	, Phase , and M and div	e-shift, differen Minimum-shift l versity, models	of Egli and	CO-2 BTL-3 CO-2 BTL-	(8)

Introduction modulation	to cellular communication – CDMA, OFDM, MIMO, Introduction to digital standards.	CO-4 BTL-3
REFERENCE BC	OOKS	
1.	"Communication Systems", by, Haykin, S. Publisher: John Wiley & Sons.	
2.	"Modern Digital and Analog Communication Systems", by, Lathi, B.P. and D Publisher: Oxford University Press.	ing, Z.
3.	"Signal Processing for Wireless Communication Systems", by H. Vincent Tong Publisher: Springers	Poor, Lang
4.	"Digital Communication: Fundamentals and Applications", by Sklar, B., a Dorling Kindersley.	nd Ray, P.K.
5.	"Communication Systems: An Introduction to Signals and Noise in Electr Communication", by Carlson, A.B., Crilly, P.B. and Rutledge, J.C Publisher	
6.	"Detection, Estimation and Modulation Theory Part I", by Van Trees, H.L Wiley Inter science.	. Pub-lisher :
7.	"Information Theory, Coding and Cryptography", by Bose, R. Tata McGra	w-Hill.
8.	"Digital Communication", by Barry, J.R., Lee, E.A. and Messerschmitt, D.G.	G.Kluwer.
9.	"Principles of Digital Transmission: Wireless Applications", by Benedetto E. Publisher: Springer	, S. and Biglieri,
10.	Literature / books suggested by respective course Lecturers.	

COURSE CODE DTA-3751 COURSE CATEGORY DE L-T-P-S 3-0-0-0	COURSE TITLE
ASSESSMENT SCHEME First Periodical Assessment Second Periodical Assessment 15% 15% 10% Surprise Test / Quiz Attendance ESE The course is intended to provide the understanding of flight dynamics, trajectory design analysis, flight performance analysis and practical implications of trajectory planning. Upon completion of this course, the students will be able to 1. Understand the flight trajectories design requirements. 2. Evaluate and predict the flight performance for different trajectories. 3. Understand the practical implications while trajectory design. 4. Carry out MATLAB based simulation for trajectory modelling.	COURSE CODE
First Periodical Assessment Second Periodical Assignments/Project Surprise Test / Quiz Attendance ESE 15% 15% 10% 5% 5% 50% The course is intended to provide the understanding of flight dynamics, trajectory design analysis, flight performance analysis and practical implications of trajectory planning. Upon completion of this course, the students will be able to 1. Understand the flight trajectories design requirements. 2. Evaluate and predict the flight performance for different trajectories. 3. Understand the practical implications while trajectory design. 4. Carry out MATLAB based simulation for trajectory modelling.	Version
Assessment Assessment Assignments/ Project Surprise Test / Quiz Attendance ESE 15% 15% 10% 5% 5% 50% The course is intended to provide the understanding of flight dynamics, trajectory design analysis, flight performance analysis and practical implications of trajectory planning. Upon completion of this course, the students will be able to 1. Understand the flight trajectories design requirements. 2. Evaluate and predict the flight performance for different trajectories. 3. Understand the practical implications while trajectory design. 4. Carry out MATLAB based simulation for trajectory modelling.	SESSMENT SCHEM
Course Objective The course is intended to provide the understanding of flight dynamics, trajectory design analysis, flight performance analysis and practical implications of trajectory planning. Upon completion of this course, the students will be able to 1. Understand the flight trajectories design requirements. 2. Evaluate and predict the flight performance for different trajectories. 3. Understand the practical implications while trajectory design. 4. Carry out MATLAB based simulation for trajectory modelling.	
Course Objective design analysis, flight performance analysis and practical implications of trajectory planning. Upon completion of this course, the students will be able to 1. Understand the flight trajectories design requirements. 2. Evaluate and predict the flight performance for different trajectories. 3. Understand the practical implications while trajectory design. 4. Carry out MATLAB based simulation for trajectory modelling.	15%
1. Understand the flight trajectories design requirements. 2. Evaluate and predict the flight performance for different trajectories. 3. Understand the practical implications while trajectory design. 4. Carry out MATLAB based simulation for trajectory modelling. CO, PO Mapping	urse Objective
	urse Outcome
CO PO-1 PO-2 PO-3 PO-4 PO-5 PO-6 PO-7	, PO Mapping
	PO-1
CO-1 3 2 2	
CO-2 3 2 2 2 2 2 2	
CO-3 3 2	
CO-4 3 2 2 2 2 2 2 2 2	
MODULE 1: (6	ODULE 1:
Flight Dynamics, Flight envelope limitations. Aerodynamic sizing-equations of motion.	
Accuracy of simplified equations of motion, orbital mechanics. BTL-3	
MODULE 2: (7	
Role of rocket propulsion in orbital trajectories and maneuvers, Maximizing missile	•
flight performance. Benefits of flight trajectory shaping. BTL-3	•
MODULE 3: (7	JUULE 3:
Flight performance prediction of boost, climb, cruise, coast, steady descent, ballistic, maneuvering, divert, and homing flight. CO-2 BTL-	•
MODULE 4: (5	ODULE 4:
Practical implementation of integrated trajectory planning, Agility in maneuvering trajectories. CO-3 BTL-3	•
MODULE 5: (5	ODULE 5:
Multiplier theory and its use in solving practical problems covered from a real-time	
computational viewpoint, No-fly zones and engineering requirements, formulation as a mathematical mixture of state and decision-variable constraints.	mputational vie

MODULE 6:		(6)			
Extensive MATLAB-based mini-projects.		CO-4 BTL-3			
REFERENCE BOOKS					
1.	"Flight Dynamics", by Robert F. Stengel. Publisher : Princeton University Press.				
2.	Literature / books suggested by respective course Lecturers.				

COURSE TIT	LE SENSO	SENSOR TECHNOLOGY				CREDITS	3
COURSE CODE D		ГА-3752	COURSE CATEGORY DE		DE	L-T-P-S	3-0-0-0
Version		1.0	Approval Details		23 ACM, 06.02.2021	LEARNING LEVEL	BTL-3
ASSESSMENT S	SCHEME			•			
First Periodi Assessmer		nd Periodical sessment	Seminar/ Assignments/ Project	Sı	urprise Test / Quiz	Attendance	ESE
15%		15%	10%		5%	5%	50%
The main objective of the course is to provide learning on the basic physical princi and characteristic features in sensor technology, design, function and applications different sensors.						•	
Course Outcor		 Upon completion of this course, the students will be able to Understand the basic principles of sensor systems required for satellites and tactical aircraft. Understand the atmospheric propagation and its impact on the performance of sensors Troubleshoot, repair/replace a faulty sensor in optimize process efficiency. 					
CO, PO Mappi	ng						
СО	PO-1	PO-2	PO-3 PO	D-4	PO-5	PO-6	PO-7
CO-1	3	2			-	-	-
CO-2	3	2			-	-	2
CO-3	3	2	- -		2	2	2
MODULE 1:							(6)
Physical principles underlying the sensor systems needed for satellites and tactical aircraft, as well as limitations imposed by the atmosphere and operating environment on these systems and their communication links.							CO-1 BTL-3
MODULE 2:							(5)
Phased array and pulsed compressed radars, imaging synthetic aperture and inverse synthetic aperture radars.							CO-2 BTL-3
MODULE 3:							(5)
Atmospheric propagation of signal. Noise resources and thermal radiation.							CO-2 BTL-
MODULE 4: (8)							
Principles of semiconductor devices. Optical and infrared imaging detector systems.							CO-3 BTL-3
MODULE 5: (6)							
Detector resolution limitations and bandwidth requirements, Relationship between signals and noise.							CO-3 BTL-3
3.0							-

MODULE 6:				
The characterist and tracking).	CO-4 BTL-3			
REFERENCE BOOKS	3			
1.	"Handbook of Modern Sensors", by Jacob Fraden. Publisher : Springer.			
2.	"Micro sensors, Principles and Applications", by J. W. Gardner. Publisher : Wiley.			
3.	"Semiconductor Sensors", by S. M. Sze. Publisher : Wiley.			
4.	Literature / books suggested by respective course Lecturers.			